Annexe 1



Cet intercalaire doit obligatoirement être inséré devant la page de garde d'un manuel de vol en langue anglaise

AVERTISSEMENT

Le présent document en langue anglaise est le manuel de vol approuvé par l'Agence européenne de la sécurité aérienne.

En application des dispositions de l'arrêté du 24 juillet 1991 relatif aux conditions d'utilisation des aéronefs civils en aviation générale (« Un vol ne peut être entrepris que si, d'une part les membres d'équipage sont familiarisés avec l'aéronef et son équipement de bord, notamment le matériel de sécurité-sauvetage et les systèmes spéciaux, et d'autre part ont une connaissance pratique de son manuel de vol ou des documents acceptés comme équivalents. »),

Nul ne peut utiliser l'aéronef avec ce seul document s'il n'a pas une connaissance suffisante de la langue anglaise.

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Référence : Instruction du 13/11/2009 relative à la langue des manuels de vol



R - 20 - 00 Indice A

31 mai 2012

Page: 8

ARCHER III

PA-28-181

SN 2843001 AND UP

PILOT'S OPERATING HANDBOOK

AND

FAA APPROVED AIRPLANE FLIGHT MANUAL

AIRPLANE SERIAL NO.

2843426

AIRPLANE REGIST, NO. F HMCI

PA-28-181

REPORT: VB-1611 FAA APPROVED BY:

PETER E. PECK

DATE OF APPROVAL:

JULY 12, 1995

D.O.A. NO. SO-1 THE NEW PIPER AIRCRAFT, INC. VERO BEACH, FLORIDA

FAA APPROVED IN NORMAL AND UTILITY CATEGORIES BASED ON CAR 3. THIS HANDBOOK INCLUDES THE MATERIAL REQUIRED TO BE FURNISHED TO THE PILOT BY CAR 3 AND CONSTITUTES THE APPROVED AIRPLANE FLIGHT MANUAL AND MUST BE CARRIED IN THE AIRPLANE AT ALL TIMES.



Per-Olov Brink Luftfartsingenjör I UFTFARTSVERKET



WARNING

EXTREME CARE MUST BE EXERCISED TO LIMIT THE USE OF THIS HANDBOOK TO APPLICABLE AIRCRAFT. THIS HANDBOOK IS VALID FOR USE WITH THE AIRPLANE IDENTIFIED ON THE FACE OF THE TITLE PAGE. SUBSEQUENT REVISIONS SUPPLIED BY PIPER MUST BE PROPERLY INSERTED.

Published by
PUBLICATIONS DEPARTMENT
Issued: July 12, 1995
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APPLICABILITY

Application of this handbook is limited to the specific Piper PA-28-181 model airplane designated by serial number and registration number on the face of the title page of this handbook.

This handbook cannot be used for operational purposes unless kept in a current status.

REVISIONS

The information compiled in the Pilot's Operating Handbook, with the exception of the equipment list, will be kept current by revisions distributed to the airplane owners. The equipment list was current at the time the airplane was licensed by the manufacturer and thereafter must be maintained by the owner.

Revision material will consist of information necessary to update the text of the present handbook and/or to add information to cover added airplane equipment.

I. Revisions

Revisions will be distributed whenever necessary as complete page replacements or additions and shall be inserted into the handbook in accordance with the instructions given below:

- 1. Revision pages will replace only pages with the same page number.
- 2. Insert all additional pages in proper numerical order within each section.
- 3. Page numbers followed by a small letter shall be inserted in direct sequence with the same common numbered page.

II. Identification of Revised Material

Revised text and illustrations shall be indicated by a black vertical line along the outside margin of the page, opposite revised, added or deleted material. A line along the outside margin of the page opposite the page number will indicate that an entire page was added.

Black lines will indicate only current revisions with changes and additions to or deletions of existing text and illustrations. Changes in capitalization, spelling, punctuation or the physical location of material on a page will not be identified.

ORIGINAL PAGES ISSUED

The original pages issued for this handbook prior to revision are given below:

Title, ii through viii, 1-1 through 1-18, 2-1 through 2-10, 3-1 through 3-16, 4-1 through 4-28, 5-1 through 5-34, 6-1 through 6-12, 7-1 through 7-26, 8-1 through 8-20, 9-1 through 9-14, 10-1 through 10-2.

Current Revisions to the PA-28-181 ARCHER III Pilot's Operating Handbook, REPORT: VB-1611 issued July 12, 1995.

Revision Number and Code	Revised Pages	Description of Revisions	FAA Approval Signature and Date
Rev. 1 (PR961118)	v 4-27 5-3 5-7 5-26 5-27 5-28 5-29 8-14	Added Rev. 1 to L of R page. Revised para. 4.43. Revised para. 5.5 (a)(6). Revised para. 5.5 (g)(1) Revised fig. 5-27. Revised fig. 5-27a. Revised fig. 5-29. Revised fig. 5-29a. Revised para. 8.21.(c)	Peter E. Peck Nov. 18, 1996 Date
Rev. 2 (PR970403)	v 5-4 5-28 5-29 5-32 5-33 7-i 7-27 7-28 9-15 thru 9-26 9-27 thru 9-38 9-39 9-40	Added Rev. 2 to L of R page. Revised para. 5.5 (b)(5). Revised fig. 5-29. Revised fig. 5-29a. Revised fig. 5-35. Revised fig. 5-37. Rev. TOC. Added para. 7.39. Added blank page. Added Supplement 4 Bendix/King KLN89 (B) GPS Nav. System Added Supplement 5 Bendix/King KX 155A Comm/Nav System Added Supplement 6 Added blank page.	Peter E. Peck APRIL 3, 1997 Date

Number and Code	Revision			FAA Approval
Rev. 3	Number and	Revised	Description of Revisions	Signature and
Rev. 3		Pages	-	Date
Rev. 5				0.0
Rev. 4 (PR980312) 5-18 9-39 Revised fig. 5-15. Revised header. March 12, 1998 Date	Rev. 3	vi	Added Rev. 3 to L of R page.	My E. Va L
Rev. 4 (PR980331) Rev. 4 (PR980331) vi 5-14 5-15 Revised Fig. 5-7. Revised Fig. 5-9. S-16 Revised Fig. 5-11. Revised Fig. 5-13. S-18 Revised Fig. 5-15. Revised Fig. 5-17. Revised Fig. 5-17. Revised Fig. 5-19. Revised Fig. 5-31. Revised Fig. 5-31. Revised Fig. 5-31. Revised Fig. 5-35. Revised Fig. 5-37.	200220000000000000000000000000000000000	F. S.		Peter E. Peck
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S-14		vi	Added Rev. 4 to L of R page.	
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S-16				
S-17		5-16		
S-19		5-17		
S-20		5-18	Revised Fig. 5-15.	
S-30		5-19	Revised Fig. 5-17.	000
S-32		5-20	Revised Fig. 5-19.	16 2. Van 1
Rev. 5 (PR981106) Rev. 5 (PR981106) Vi Added Rev. 5 to L of R page. Revised para. 4.5. Revised para. 4.5. Revised para. 4.23. Revised Fig. 5-5. S-13 Revised Fig. 5-9. Revised Fig. 5-9. Revised Fig. 5-13. Revised Fig. 5-33. Revised T of C. 9-41 Added Supplement 7 - Garmin GNS 430 Nav/Comm. Peter E. Peck Nov. 6, 1998		5-30	Revised Fig. 5-31.	Peter E. Peck
Rev. 5 (PR981106) Vi Added Rev. 5 to L of R page. Revised para. 4.5. 4-11 Revised para. 4.5. 4-22 Revised para. 4.23. 5-13 Revised Fig. 5-5. 5-15 Revised Fig. 5-9. 8-17 Revised Fig. 5-13. Revised Fig. 5-33. P-i Revised T of C. 9-41 Added Supplement 7 - Garmin GNS 430 Nav/Comm. 9-48 Date Date Date Date Date		5-32	Revised Fig. 5-35.	
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(PR981106) 4-10 Revised para. 4.5. Revised para. 4.5. Revised para. 4.23. Revised Fig. 5-5. Revised Fig. 5-9. Revised Fig. 5-13. Revised Fig. 5-33. Revised T of C. Added Supplement 7 - thru Garmin GNS 430 Nav/Comm. Nov. 6, 1998			2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	Date
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4-11 Revised para. 4.5. 4-22 Revised para. 4.23. 5-13 Revised Fig. 5-5. 5-15 Revised Fig. 5-9. 5-17 Revised Fig. 5-13. 7-31 Revised Fig. 5-33. 9-i Revised T of C. 9-41 Added Supplement 7 - thru Garmin GNS 430 Nav/Comm. 9-48 Nov. 6, 1998	Rev. 5	vi	Added Rev. 5 to L of R page.	
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	110001		Garmin GNS 430 Nav/Comm.	
Date		9-48		
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	Rev. 6 (PR981218)	vi-a vi-b 9-i 9-49 9-50	Added page. Added page. Revised T of C. Added page. Added page.	Peter E. Peck Dec. 18, 1998 Date
	Rev. 7 (PR991206)	vi-a 5-23 9-i 9-51 thru 9-52	Added Rev. 7 to L of R. Revised Fig. 5-20b. Revised T of C. Added pages and Supplement 9.	Christina L. Marsh Dec. 6, 1999 Date
	Rev. 8 (PR000714)	vi-a 9-i 9-47 9-53 thru 9-58 9-59 thru 9-62 9-63 thru 9-70	Added Rev. 8 to L of R. Revised T of C. Revised Section 4. Added pages and Supplement 10. Added pages and Supplement 11. Added pages and Supplement 12.	Christina L. Marsh July 14, 2000 Date
\	Rev. 9 (PR010102)	vi-a vi-b 9-i 9-71 thru 9-80	Added Rev. 9 to L of R. Added Rev. 9 to L of R. Revised T of C. Added pages and Supplement 13.	

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Revision Number and Code	Revised Pages	Description of Revisions	FAA Approval Signature and Date
Rev. 9 (PR010102) continued	9-81 thru 9-82 9-83 thru 9-88 9-89 thru 9-94 9-95 thru 9-98	Added pages and Supplement 14. Added pages and Supplement 15. Added pages and Supplement 16. Added pages and Supplement 17.	Christina L. Marsh Jan. 2, 2001 Date
Rev. 10 (PR020415)	vi-b 3-4 4-7 4-8 4-9 4-18 4-19	Added Rev. 10 to L of R. Revised para. 3.5. Revised para. 4.5. Revised para. 4.5. Revised para. 4.5. Revised para. 4.13. Revised para. 4.13.	Albert J. Mill April 15, 2002 Date

REPORT: VB-1611

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Revision Number and Code	Revised Pages	Description of Revisions	FAA Approval Signature and Date
Rev. 11 (PR040105) continued	8-1b 8-2 9-i 9-99 thru 9-102	Added page and moved info. from pages 8-1 and 8-2. Moved info. to page 8-1b and revised para. 8.3. Revised T of C. Added pages and Supplement 18.	Albert J. Mill Jan. 5, 2004 Date
Rev. 12 (PR040614)	vi-c 9-i 9-103 thru 9-110	Added Rev. 12 to L of R. Revised T of C. Added pages and Supplement 19.	Albert J. Mill June 14, 2004
Rev. 13 (PR041007)	vi-c 9-i 9-111 thru 9-128 9-129 thru 9-132	Added Rev. 13 to L of R. Revised T of C. Added pages and Supplement 20. Added pages and Supplement 21.	Linda J. Dicken October 7, 2004
Rev. 14 (PR050912)	vi-c 9-i 9-111 thru 9-138 9-139 thru	Added Rev. 14 to L of R. Revised T of C. Revised Supplement 20. Revised page numbers.	
MIMA L FAIRA BOOK AT ROOM	9-142 9-143 thru 9-152	Added pages and Supplement 22.	Linda J. Dicken Sept. 12, 2005

ISSUED: JULY 12, 1995 REVISED: SEPTEMBER 12, 2005 REPORT: VB-1611 vi-c

Revision Number and Code	Revised Pages	Description of Revisions	FAA Approval Signature and Date
Rev. 15 (PR051128)	vi-d 9-116 9-119 9-123	Added Rev. 15 to L of R. Revised Section 3. Revised Section 3. Revised Section 3.	Linda J. Dicken Nov. 28, 2005
Rev. 16 (PR060109)	vi-d 9-i 9-111 thru 9-138	Added Rev. 16 to L of R. Revised T of C. Revised Supplement 20.	Linda J. Dicken Jan. 9, 2006
Rev. 17 (PR060214)	vi-d 9-ii 9-116 9-119 9-120 9-123 9-124 9-153 thru 9-188	Added Rev. 17 to L of R. Revised T of C. Revised Section 3. Added pages and Supplement 23.	Linda J. Dicken Feb. 14, 2006
Rev. 18 (PR060411)	vi-d 9-131 9-179 vi-d	Added Rev. 18 to L of R. Revised Section 7A. Revised Section 7A. Added Rev. 19 to L of R.	Linda J. Dicken April 11, 2006
Rev. 19 (PR070129) Rev. 20 (PR080411)	vi-d 8-20 vi-d 9-155	Added Rev. 19 to L of R. Revised para. 8.29. Added Rev. 20 to L of R. Revised Supp 23, Section 1.	Linda J. Dicken Jan. 29, 2007
	9-164 9-178 9-186	Revised Supp 23, Section 3. Revised Supp 23, Section 4. Revised Supp 23, Section 7B.	Albert J. Mill April 11, 2008

REPORT: VB-1611 vi-d

ISSUED: JULY 12, 1995 REVISED: APRIL 11, 2008

PA-28-181Archer III

PILOT'S OPERATING HANDBOOK LOG OF REVISIONS

7	Revision			FAA Approved
\bigcap	Number and Code	Revised Pages	Description of Revisions	Signature and Date
	Rev. 21 (PR081015)	v-e,f vi-e 9-ii 9-189 thru 9-202	Added new pages to L of R. Added Rev. 21 to L of R. Added Supplements 24 and 25 to Section 9 TOC. Added Supplements 24 and 25 to Section 9.	Albert J. Mill Oct. 15, 2008
	Rev. 22 (PR090615)	vi-e 4-7 4-17 8-1b 9-112 9-154	Added Rev. 22 to L of R. Revise Note in Para. 4.5. Revise Note in Para. 4.9. Revised text in Para. 8.1. Revised text in Para. 8.1. Revised text in Para. 8.1.	Albert J. Mill June 15, 2009
9	Rev. 23 (PR100205)	vi-e 4-23 7-13 7-15 9-ii 9-203 thru 9-206	Added Rev. 23 to L of R. Revised Para. 4.27. Revised Para. 7.19. Revised callouts for Instrument Panel. Added Supplements 26 and 27 to TOC. Added pages.	Albert J. Mill February 5, 2010
	Rev. 24 (PR100729)	vi-e,f 2-8 7-25 7-26 9-ii 9-205 9-206 9-207 thru 9-216	Added Rev. 24 to L of R. Added Note to Para. 2.25. Revised Para. 7.37. Revised Para. 7.37. Revised T.O.C. Revised Supplement 27. Revised Supplement 27. Added pages.	Albert J. Mill July 29, 2010

ISSUED: JULY 12, 1995 REVISED: JULY 29, 2010 REPORT: VB-1611

vi-e

TABLE OF CONTENTS

SECTION 1	GENERAL
SECTION 2	LIMITATIONS
SECTION 3	EMERGENCY PROCEDURES
SECTION 4	NORMAL PROCEDURES
SECTION 5	PERFORMANCE
SECTION 6	WEIGHT AND BALANCE
SECTION 7	DESCRIPTION AND OPERATION OF THE AIRPLANE AND ITS SYSTEMS
SECTION 8	AIRPLANE HANDLING, SERVICING AND MAINTENANCE
SECTION 9	SUPPLEMENTS

SECTION 10 OPERATING TIPS

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TABLE OF CONTENTS SECTION 1 GENERAL

Parag No.	raph	Page No.
1.1	Introduction	1-1
1.3	Engines	1-3
1.5	Propellers	1-3
1.7	Fuel	1-3
1.9	Oil	1-4
1.11	Maximum Weights	1-4
1.13	Standard Airplane Weights	1-4
1.15	Baggage Space	1-5
1.17	Specific Loadings	1-5
1.19	Symbols, Abbreviations and Terminology	1-6
1.21	Conversion Factors	1-12

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SECTION 1 GENERAL

1.1 INTRODUCTION

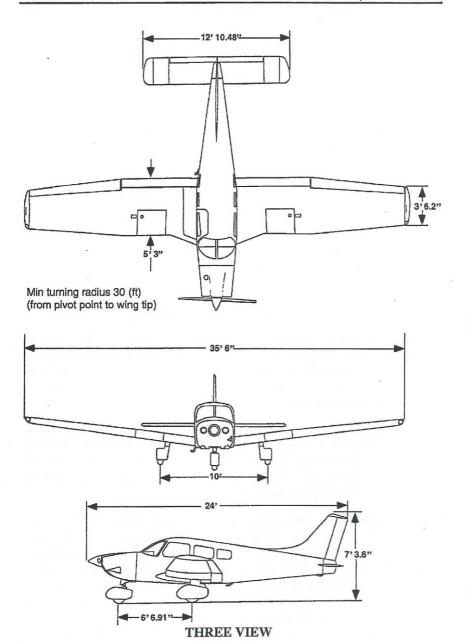
This Pilot's Operating Handbook is designed for maximum utilization as an operating guide for the pilot. It includes the material required to be furnished to the pilot by F.A.R./C.A.R. It also contains supplemental data supplied by the airplane manufacturer.

This handbook is not designed as a substitute for adequate and competent flight instruction, knowledge of current airworthiness directives, applicable federal air regulations or advisory circulars. It is not intended to be a guide for basic flight instruction or a training manual and should not be used for operational purposes unless kept in a current status.

Assurance that the airplane is in an airworthy condition is the responsibility of the owner. The pilot in command is responsible for determining that the airplane is safe for flight. The pilot is also responsible for remaining within the operating limitations as outlined by instrument markings, placards, and this handbook.

Although the arrangement of this handbook is intended to increase its in-flight capabilities, it should not be used solely as an occasional operating reference. The pilot should study the entire handbook to familiarize himself with the limitations, performance, procedures and operational handling characteristics of the airplane before flight.

The handbook has been divided into numbered (arabic) sections, each provided with a "finger-tip" tab divider for quick reference. The limitations and emergency procedures have been placed ahead of the normal procedures, performance and other sections to provide easier access to information that may be required in flight. The "Emergency Procedures" Section has been furnished with a red tab divider to present an instant reference to the section. Provisions for expansion of the handbook have been made by the deliberate omission of certain paragraph numbers, figure numbers, item numbers and pages noted as being intentionally left blank.



1.3 ENGINES

(a)	Number of Engines	1
(b)	Engine Manufacturer	Lycoming
	Engine Model Number	O-360-A4M
, ,	Takeoff Power (BHP)	180
	Takeoff Power Engine	
(0)	Speed (RPM)	2700
(0)	1	5.125
(f)	Bore (inches)	4.375
	Stroke (inches)	361.0
	Displacement (cubic inches)	
(i)	•	8.5:1
(j)	Engine Type	Four Cylinder, Direct
		Drive, Horizontally
		Opposed, Air Cooled
1.5 PR	OPELLERS	
(2)	Number of Propellers	1
	Propeller Manufacturer	Sensenich
	Model	76EM8S14-0-62
	Number of Blades	2
		_
(e)	Propeller Diameter (inches)	76
	(1) Maximum	76
10	(2) Minimum	Fixed Pitch
(1)	Propeller Type	Fixed Fitch
1.7 FU	TEL	
AV	GAS ONLY	
(a)	Fuel Capacity (U.S. gal.) (total)	50
	Usable Fuel (U.S. gal.) (total)	48
(c)		
(0)	(1) Minimum Octane	100 Green or 100LL Blue
	(1) Iriminani Counc	Aviation Grade
		AAAAAAAA OMAA

Refer to latest issue of

Lycoming Instruction No. 1070.

(2) Alternate Fuel

ISSUED: JULY 12, 1995

1.9 OIL

(a)	Oil Capacity (U.S. quarts)		8
(b)	Oil Specification	R	lefer to latest issue
		of	Lycoming Service
			Instruction 1014.
(c)	Oil Viscosity per Average Ambient		
	Temp. for Starting		
		Single	Multi
(1)	Above 60°F	S.A.E. 50	S.A.E. 40 or 50
(2)	30°F to 90°F	S.A.E. 40	S.A.E. 40
(3)	0°F to 70°F	S.A.E. 30	S.A.E. 40 or
			20W-30
(4)	Below 10°F	S.A.E. 20	S.A.E. 20W-30

1.11 MAXIMUM WEIGHTS

		Normal	Utility
(a)	Maximum Ramp Weight (lbs.)	2558	2138
(b)	Maximum Takeoff Weight (lbs.)	2550	2130
(c)	Maximum Landing Weight (lbs.)	2550	2130
(d)	Maximum Weights in Baggage		
	Compartment (lbs.)	200	0

1.13 STANDARD AIRPLANE WEIGHTS

Refer to Figure 6-5 for the Standard Empty Weight and the Useful Load.

PA-28-181, ARCHER III

1.15 BAGGAGE SPACE	
(a) Compartment Volume (cubic feet)(b) Entry Width (inches)(c) Entry Height (inches)	24 22 20
1.17 SPECIFIC LOADINGS	
(a) Wing Loading (lbs. per sq. ft.)	15.0
(b) Power Loading (lbs. per hp)	14.2

CAS

Calibrated Airspeed means the indicated

1.19 SYMBOLS, ABBREVIATIONS AND TERMINOLOGY

The following definitions are of symbols, abbreviations and terminology used throughout the handbook and those which may be of added operational significance to the pilot.

(a) General Airspeed Terminology and Symbols

KCAS Calibrated Airspeed expressed in "Knot GS Ground Speed is the speed of an airp	
GS Ground Speed is the speed of an airp	s."
relative to the ground.	lane
IAS Indicated Airspeed is the speed of an craft as shown on the airspeed indic when corrected for instrument error. values published in this handbook ass zero instrument error.	ator IAS
KIAS Indicated Airspeed expressed in `Knots.	,,
TAS True Airspeed is the airspeed of an airprelative to undisturbed air which is CAS corrected for altitude, tempera and compressibility.	the
relative to undisturbed air which is CAS corrected for altitude, tempera	the ture peed

in a prescribed extended position.

Vne/Mne Never Exceed Speed or Mach Number is the speed limit that may not be exceeded at any

time.

Vno Maximum Structural Cruising Speed is the

speed that should not be exceeded except in

smooth air and then only with caution.

Vs Stalling Speed or the minimum steady

flight speed at which the airplane is con-

trollable.

Vso Stalling Speed or the minimum steady flight

speed at which the airplane is con-trollable

in the landing configuration.

Vx Best Angle-of-Climb Speed is the airspeed which delivers the greatest gain of altitude

in the shortest possible horizontal distance.

Vy Best Rate-of-Climb Speed is the airspeed

which delivers the greatest gain in altitude in

the shortest possible time.

Meteorological Terminology (b)

ISA International Standard Atmosphere in

which: The air is a dry perfect gas; The temperature at sea level is 15° Celsius (59° Fahrenheit); The pressure at sea level is 29.92 inches Hg (1013.2 mb); The temperature gradient from sea level to the altitude at which the temperature is -56.5°C (-69.7°F) is -0.00198C (-0.003564°F) per foot and

zero above that altitude.

OAT Outside Air Temperature is the free air static

> temperature, obtained either from inflight temperature indications or ground meteorological sources, adjusted for

instrument error and compressibility effects.

Indicated

Pressure Altitude

The number actually read from an altimeter when the barometric subscale has been set to 29.92 inches of mercury (1013.2)

millibars).

Pressure Altitude

Altitude measured from standard sea-level pressure (29.92 in. Hg) by a pressure or barometric altimeter. It is the indicated pressure altitude corrected for position and instrument error. In this handbook, altimeter instrument errors are assumed to be zero.

Station Pressure

Actual atmospheric pressure at field

elevation.

Wind

The wind velocities recorded as variables on the charts of this handbook are to be understood as the headwind or tailwind components of the reported winds.

(c) Power Terminology

Takeoff Power

Maximum power permissible for takeoff.

Maximum Continuous Power Maximum power permissible continuously

during flight.

(d) Engine Instruments

EGT Gauge

Exhaust Gas Temperature Gauge

(e) Airplane Performance and Flight Planning Terminology

Climb Gradient The demonstrated ratio of the change in

height during a portion of a climb, to the horizontal distance traversed in the same

time interval.

Demonstrated

Crosswind Velocity

(Demo. X-Wind)

The demonstrated crosswind velocity is the velocity of the crosswind component for which adequate control of the airplane during takeoff and landing was actually

demonstrated during certification tests.

Accelerate-Stop

Distance

The distance required to accelerate an airplane to a specified speed and, assuming failure of an engine at the instant that speed is attained, to bring the airplane to a stop.

Route Segment

A part of a route. Each end of that part is identified by: (1) a geographical location; or (2) a point at which a definite radio fix can be established.

(f) Weight and Balance Terminology

horizontal distances are measured for

balance purposes.

Station A location along the airplane fuselage

usually given in terms of distance from the

reference datum.

Arm The horizontal distance from the reference

datum to the center of gravity (C.G.) of an

item.

Moment The product of the weight of an item multi-

plied by its arm. (Moment divided by a constant is used to simplify balance calculations by reducing the number of digits.)

lations by reducing the number of digi

Center of Gravity The point at which an airplane would (C.G.) balance if suspended. Its distance from the

reference datum is found by dividing the total moment by the total weight of the

airplane.

C.G. Arm The arm obtained by adding the airplane's

individual moments and dividing the sum

by the total weight.

C.G. Limits The extreme center of gravity locations

within which the airplane must be operated

at a given weight.

Usable Fuel Fuel available for flight planning.

Unusable Fuel Fuel remaining after a runout test has been

completed in accordance with govern-

mental regulations.

Standard Empty Weight of a standard airplane including

Weight unusable fuel, full operating fluids and full

oil.

Basic Empty Standard empty weight plus optional

Weight equipment.

Payload Weight of occupants, cargo and baggage.

Useful Load Difference between takeoff weight, or

ramp weight is applicable, and basic empty

weight.

Maximum Ramp Maximum weight approved for ground

Weight maneuver. (It includes weight of start, taxi

and run up fuel.)

Maximum Takeoff Weight Maximum weight approved for the start of the takeoff run.

Maximum Landing Weight Maximum weight approved for the landing touchdown.

Maximum Zero Fuel Weight Maximum weight exclusive of usable fuel.

1.21 CONVERSION FACTORS

MULTIPLY	BY	TO OBTAIN
centimeters (cm)	0.032808 0.3937 0.01	feet (ft.) inches (in.) meters (m)
centimeters of mercury at 0° C (cm Hg) cubic centimeters (cm ³)	13.3322 .3937 27.85 0.1934 3.531x10-5	hectopascals (hPa) inches of mercury (in. Hg) pounds / sq. foot (Ibf./ft ²) pounds / sq. inch (Ibf./in ²) cubic feet (ft ³)
,	0.06102 0.001 0.03381 2.642x10-4	cubic inches (in ³) Liters (1) fluid ounces (fl. oz) U.S. gallons (U.S. gal)
cubic feet (ft ³)	28317 7.481 1728 28.32 0.028317	cubic centimeters (cm ³) U.S. gallons (U.S. gal) cubic inches (in ³) liters (1) cubic meters (m ³)
cubic inches (in ³)	16.39 5.787×10-4 4.329×10-3 0.01639 1.639×10-5 0.5541 0.01732	cubic centimeters (cm ³) cubic feet (ft ³) U.S. gallons (U.S. gal) liters (1) cubic meters (m ³) fluid ounces (fl. oz) U.S. quarts (U.S. qt)
cubic meters (m ³)	35.3147 264.2 61024 1000000	cubic feet (ft ³) U.S. gallons (U.S. gal) cubic inches (in ³) liters (1)
degrees arc. (deg) degrees arc per second (deg / sec)	0.01745 0.01745 0.166667	radians radians per second revolutions per second (rpm)
		OVERTICAL TO SEE

MULTIPLY	BY	TO OBTAIN
drams, fluid (dr. fl.)	3.697x10 ⁻³ 3.697x10 ⁻⁶ 0.125	liters (1) cubic meters (m ³) fluid ounces (fl. oz)
feet (ft)	30.48	centimeters (cm)
	12 0.3048	inches meters (m)
	1.8939x10-4	miles (mi)
	1.6458	nautical miles (NM)
	0.0606061	rods
feet per minute (ft / min)	0.01829	kilometers per hour (km /
	2	hr)
	9.8716x10 ⁻³	knots (kt)
	0.00508	meters per second (m / s)
	0.01136	miles per hour (mph)
feet per second (ft / sec)	1.097	kilometers per hour (km /
		hr)
	0.5921	knots (kt)
	0.3048	meters per second (m / s)
	0.6818	miles per hour (mph)
foot-pounds (ftlbs.)	3.2383x10-4	kilocalorie (kcal)
	1.3558	joules (j)
	14.5939	newton-meters (n-m)
foot-pound per minute	3.03x10-5	horse power (hp)
(ft-lbs/ min)	81.348	joules per minute (j / min)
foot-pound per second	1.818x10-5	horse power (hp)
(ft-lbs/ sec)	1.3558	joules per second (j / sec)
gallons, imperial	4.546x10 ⁻³	cubic centimeters (cm ³)
(imperial gal)	1.201	U.S. gallon (U.S. gal)
	277.4	cubic inches (in ³)
	4.546	liters (l)
gallons, U.S. dry	4.405x10-3	cubic meters (m ³)
(U.S. gal dry)	0.1556	cubic feet (ft ³)
	1.164	U.S. gallon (U.S. gal)
	268.8	cubic inches (in ³)
	4.405	liters (l)

MULTIPLY	BY	TO OBTAIN
gallons, U.S. Liquid (U.S. gal)	3785.4 0.1337 0.83268	cubic centimeters (cm ³) cubic feet (ft ³) imperial gallons (imperial gal)
	231 3.785 3.785x10 ⁻³ 128	cubic inches (in ³) liters (1) cubic meters (m ³) fluid ounces (fl. oz)
hectares (ha)	2.471 107639 10000	acres square feet (ft ²) square meters (m ²)
horsepower (hp)	33000	foot-pound per minute (ft-lbs / min)
	550	foot-pound per second (ft-lbs / sec)
	745.7	joules per second (j / sec)
	1.014	metric horsepower (metric hp)
	8.026x10 ³	newton-meters per second (n-m / sec)
horsepower, metric	0.9863	horsepower (hp)
	735.484	joules per second (j / sec)
	8.138x10 ³	newton-meters per second (n-m / sec)
inches (in)	2.54	centimeters (cm)
	0.08333	feet (ft)
	0.0254	meters (m)
	25.4	millimeters (mm)
inches of mercury	0.033421	atmospheres (atm)
Try costs Tourse taken united	2.54	centimeters of mercury (cm Hg)
	33.8639	hectopascals (hPa)
	70.73	pounds per square foot
	,	(Tbf / ft^2)
	0.4912	pounds per square inch Ibf / in ²)
	25.4	millimeters mercury (mm Hg)

MULTIPLY	BY	TO OBTAIN
kilometers (km)	lx10-5	centimeter (cm)
,	3280.8	feet (ft)
	0.6214	miles (mi)
	0.53996	nautical miles (nm)
kilometers per hour	58.68	feet per minute (ft / min)
anomore per neur	0.9113	feet per second (ft / sec)
	0.53996	knots (kt)
	16.67	meters per minute (m / min)
	0.27778	meters per second (m / sec)
	0.6214	miles per hour (mph)
knots (kt)	1.689	feet per second (ft / sec)
Kilots (Kt)	1.852	kilometer per hour (km / hr)
	51.48	meter per second (m / sec)
	1	nautical mile per hour
	1	(nautical mph)
		statute mile per hour
		(statute mph)
liters (l)	1000	cubic centimeter (cm ³)
nters (1)	0.03531	cubic feet (ft ³)
	0.22	imperial gallons (imperial
	0.22	gal)
	0.264172	U.S. gallons (U.S. gal)
	61.02	cubic inches (in ³)
	0.001	cubic meter (m ³)
	33.814	fluid ounces (fl. oz.)
	1.05669	U. S. quart (qt)
liters per second (1 / sec)	2.12	cubic feet per minute
nters per second (17 sec)	2.12	(ft ³ / min)
meters (m)	3.28084	feet
meters (m)	39.37	inches
	6.214x10-4	miles (mi)
	5.3996x10-4	nautical mile (nm)
	0.198838	rod
maters per minute (m / min)	0.198838	kilometers per hour (km / hr)
meters per minute (m / min)	116.6307	knots (kt)
	110.0307	VIIOTO (VI)

MULTIPLY	BY	TO OBTAIN
meters per second (m/sec)	196.8504 3.280840 3.6	feet per minute (ft / min) feet per second (ft / sec) kilometers per hour (km / hr)
	1.94384	knots (kt)
miles, statute(mi)	2.237 5280 1609.3	miles per hour (mph) feet (ft) meters (m)
	1.6093 0.8684	kilometers (km) nautical miles (nm)
miles per hour (mph)	88 1.467 0.8684 0.447	feet per minute (ft / min) feet per second (ft / sec) knots (kt) meters per second (m / sec)
	1.6093	kilometer per hour
miles per hour squared (mi / hr ²)	2.151	feet per second squared (ft / sec ²)
,,	0.44704	meter per second squared (m / sec ²)
millibars	1.0 0.02953	hectopascals (hPa) inches of mercury (in Hg)
millimeters of mercury at 0° C (mm Hg)	1.3332 0.03937	hectopascals (hPa) inches of mercury (in Hg)
nautical miles (nm)	6080	feet (ft)
	1.852 1852 1.1516	kilometers (km) meters (m) statute miles (mi)
fluid ounces (fl. oz)	29.57 8 0.0078	cubic centimeters (cm ³) fluid drams (fl dr) U.S. gallons (U.S. gal)
	1.805 0.0296 2.9574x10 ⁻⁵	cubic inches (in ³) liters (1) cubic meters (m ³)
pounds per square foot	0.1414	inches of mercury (in Hg)
(psf or lbs / ft ²)	47.880	newtons per square meter (n / m ²)

MULTIPLY	ВҮ	TO OBTAIN
pounds per square inch	68.9475	millibar (mb)
(Ibs/in^2)	5.1715	centimeter of mercury
(/		(cm Hg)
	2.036	inches of mercury
		(in Hg)
quart, U.S. (qt)	57.749	cubic inches (in ³)
	0.94635	liters (1)
	9.46353x10-4	cubic meters (m ³)
radians	57.3	degrees arc (deg)
	0.1592	revolutions (rev)
radians per second	57.3	degrees per second
-		(deg /sec)
	9.549	revolutions per minute
		(rpm)
revolutions	360	degrees (deg)
	6.283	radians
revolutions per minute (rpm)	6	deg per second
		(deg / sec)
	0.1047	radians per second
		(r / sec)
rod	16.5	feet (ft)
	5.029	meters (m)
square centimeters (cm ²)	0.001076	square feet (ft ²)
	0.155	square inches (in ²)
	0.0001	square meters (m ²)
square feet (ft ²)	929	square centimeters (cm ²)
	144	square inches (in ²)
	0.092903	square meters (m ²)
square inches (in ²)	6.4516	square centimeters (cm ²)
	0.006944	square feet (ft ²)
	6.4516x10 ⁻⁴	square meters (m ²)
square kilometers (km ²)	1000000	square meters (m ²)
		aguara milas (mil)
	0.3861	square miles (mi ²)
square meters (m ²)	10.76391	square feet (ft ²)
_	10.76391 0.0001	square feet (ft ²) hectors (ha)
square meters (m ²) square miles (mi ²)	10.76391	square feet (ft ²)

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TABLE OF CONTENTS SECTION 2 LIMITATIONS

Parag No.	raph	Page No.
2.1 2.3 2.5	General	2-1 2-1 2-2
2.7 2.9	Power Plant Limitations Power Plant Instrument Markings	2-3 2-4
2.11 2.13	Weight Limits Center of Gravity Limits	2-4 2-5
2.15 2.17	Maneuver Limits	2-6 2-6
2.19 2.21	Types of Operations	2-6 2-6
2.25	Placards	2-7

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SECTION 2

LIMITATIONS

2.1 GENERAL

This section provides the "FAA Approved" operating limitations, instrument markings, color coding and basic placards necessary for operation of the airplane and its systems.

This airplane must be operated as a normal or utility category airplane in compliance with the operating limitations stated in the form of placards and markings and those given in this section and this complete handbook.

Limitations associated with those optional systems and equipment which require handbook supplements can be found in Section 9. (Supplements).

2.3 AIRSPEED LIMITATIONS

SPEED	KIAS	KCAS
Never Exceed Speed (VNE) - Do not exceed this speed in any operation.	154	148
Maximum Structural Cruising Speed (VNO) - Do not exceed this speed except in smooth air and then only with caution.	125	121

extended.

102

100

SPEED	KIAS	KCAS
Design Maneuvering Speed (VA) - Do not make full or abrupt control movements above this speed.		
At 2550 lbs. G.W.	113	111
At 1634 lbs. G.W.	89	89
CAUTION: Maneuvering speed lighter weight as the effects of aero become more pronounced. Linear in be used for intermediate gross weiging speed should not be exceeded in rough air.	dynamic forces terpolation may thts. Maneuver-	
Maximum Flaps Extended Speed (VFE) - Do not exceed this speed with the flaps		

2.5 AIRSPEED INDICATOR MARKINGS

MARKING	IAS
Red Radial Line (Never Exceed)	154 KTS
Yellow Arc (Caution Range - Smooth Air Only)	125 KTS to 154 KTS
Green Arc (Normal Operating Range)	50 KTS to 125 KTS
White Arc (Flap Down)	45 KTS to 102 KTS

2.7 POWER PLANT LIMITATIONS

	S. C.		
(a)	Number of Engines	1	
(b)	The state of the s		
(c)	Engine Model No.	O-360-A4M	
(d)	Engine Operating Limits		
(-)	(1) Takeoff Power		
	limit (BHP)	180	
	(2) Takeoff Engine		
	Speed (RPM)	2700	
	(3) Maximum Oil Temperature	245F	
	(4) Oil Pressure		
	Minimum (red line)	25 PSI	
	Maximum (red line)	115 PSI	
	(5) Fuel Pressure		
	Minimum (red line)	0.5 PSI	
	Maximum (red line)	8 PSI	
	(6) Fuel (AVGAS ONLY)		
	(minimum grade)	100 or 100LL	
		Aviation Grade	
	(7) Number of Propellers	1	
	(8) Propeller Manufacturer	Sensenich	
	(9) Propeller Model	76EM8S14-0-62	
	(10) Propeller Diameter		
	Minimum	76 IN.	
	Maximum	. 76 IN.	
	(11) Propeller Tolerance (static RPM		
	at maximum permissible throttle		
	setting at sea level)	Not above 2340 RPM	
	at ISA conditions	Not below 2240 RPM	

NOTE: Reference aircraft maintenance manual for test procedure to determine approved static RPM under non-standard conditions.

2.9 POWER PLANT INSTRUMENT MARKINGS

(a)	Tachometer	
	Green Arc (Normal Operating Range)	500 to 2700 RPM
	Red Line (Takeoff Power)	2700 RPM
(b)	Oil Temperature	
	Green Arc (Normal Operating Range)	100° to 245°F
	Red Line (Maximum)	245°F
(c)	Oil Pressure	
	Green Arc (Normal Operating Range)	55 PSI to 95 PSI
	Yellow Arc (Caution Range) (Idle)	25 PSI to 55 PSI
	Yellow Arc (Ground Warm-Up)	95 PSI to 115 PSI
	Red Line (Minimum)	25 PSI
	Red Line (Maximum)	115 PSI
(d)	Fuel Pressure	
	Green Arc (Normal Operating Range)	0.5 PSI to 8 PSI
	Red Line (Minimum)	0.5 PSI
	Red Line (Maximum)	8 PSI
(e)	Vacuum Gauge	
	Red Line (Minimum)	4.8 in Hg
	Green Arc (Normal Operating Range)	4.8 in Hg. to 5.2 in Hg
	Red Line (Maximum)	5.2 in Hg

2.11 WEIGHT LIMITS

		Normal	Utility
(a)	Maximum Ramp (lbs.)	2558	2138
(b)	Maximum Weight (lbs.)	2550	2130
(c)	Maximum Baggage (lbs.)	200	0

NOTE

Refer to Section 5 (Performance) for maximum weight as limited by performance.

2.13 CENTER OF GRAVITY LIMITS

(a) Normal Category

Weight Pounds	Forward Limit Inches Aft of Datum	Rearward Limit Inches Aft of Datum
2550	88.6	93.0
2050 (and less)	82.0	93.0

(b) Utility Category

Weight	Forward Limit	Rearward Limit
Pounds	Inches Aft of Datum	Inches Aft of Datum
2130 2050 (and less)	83.0 82.0	93.0 93.0

NOTES

Straight line variation between points given.

The datum used is 78.4 inches ahead of the wing leading edge at the inboard intersection of the straight and tapered section.

It is the responsibility of the airplane owner and the pilot to insure that the airplane is properly loaded. See Section 6 (Weight and Balance) for proper loading instructions.

T T4:1:4.

2.15 MANEUVER LIMITS

- (a) Normal Category All acrobatic maneuvers including spins prohibited.
- (b) Utility Category Approved maneuvers for bank angles exceeding 60°.

	Entry Speed
Steep Turns	113 KIAS
Lazy Eights	113 KIAS
Chandelles	113 KIAS

2.17 FLIGHT LOAD FACTORS

		Normai	Ounty
(a)	Positive Load Factor (Maximum)	3.8 G	4.4 G
(b)	Negative Load Factor (Maximum)	No inve	rted maneuvers
	9		approved

2.19 TYPES OF OPERATION

The airplane is approved for the following operations when equipped in accordance with FAR 91 or FAR 135.

- (a) Day V.F.R.
- (b) Night V.F.R.
- (c) Day I.F.R.
- (d) Night I.F.R.
- (e) Non Icing

2.21 FUEL LIMITATIONS

(a)	Total Capacity	50 U.S. GAL.
(b)	Unusable Fuel	2 U.S. GAL.
	The unusable fuel for this airplane has	
	been determined as 1.0 gallon in each	
	wing in critical flight attitudes.	
(c)	Usable Fuel	48 U.S. GAL.

The usable fuel in this airplane has been determined as 24.0 gallons in each wing.

2.25 PLACARDS

In full view of the pilot:

"THIS AIRPLANE MUST BE OPERATED AS A NOR-MAL OR UTILITY CATEGORY AIRPLANE IN COM-PLIANCE WITH THE OPERATING LIMITATIONS STATED IN THE FORM OF PLACARDS, MARKINGS AND MANUALS.

ALL MARKINGS AND PLACARDS ON THIS AIR-PLANE APPLY TO ITS OPERATION AS A UTILITY CATEGORY AIRPLANE. FOR NORMAL AND UTILITY CATEGORY OPERATION REFER TO THE PILOT'S OPERATING HANDBOOK.

NO ACROBATIC MANEUVERS ARE APPROVED FOR NORMAL CATEGORY OPERATIONS. SPINS ARE PROHIBITED FOR NORMAL AND UTILITY CATEGORY."

In full view of the pilot, in the area of the air conditioner control panel when the air conditioner is installed:

"WARNING" AIR CONDITIONER MUST BE OFF TO INSURE NORMAL TAKEOFF CLIMB PERFORMANCE."

Adjacent to upper door latch:

"ENGAGE LATCH BEFORE FLIGHT."

On inside of the baggage compartment door.

"BAGGAGE MAXIMUM 200 LBS."
"UTILITY CATEGORY OPERATION - NO BAGGAGE OR AFT PASSENGERS ALLOWED. NORMAL CATEGORY OPERATION - SEE PILOT'S OPERATING HANDBOOK WEIGHT AND BALANCE SECTION FOR BAGGAGE AND AFT PASSENGER LIMITATIONS."

In full view of the pilot:

" V_A 113 KIAS AT 2550# (SEE P.O.H.)"

"DEMO. X-WIND 17 KTS."

NOTE

Demonstrated crosswind values are NOT limitations.

REPORT: VB-1611 2-8 ISSUED: JULY 12, 1995 REVISED: JULY 29, 2010

In full view of the pilot:

- "UTILITY CATEGORY OPERATION ONLY."
- (1) NO AFT PASSENGERS ALLOWED.
- (2) ACROBATIC MANEUVERS ARE LIMITED TO THE FOLLOWING:

	ENTRY SPEED
SPINS PROHIBITED	
STEEP TURNS	113 KIAS
LAZY EIGHTS	113 KIAS
CHANDELLES	113 KIAS

In full view of the pilot:

"WARNING" TURN OFF STROBE LIGHTS WHEN IN CLOSE PROXIMITY TO GROUND OR DURING FLIGHT THROUGH CLOUD, FOG OR HAZE."

Adjacent to the filler caps:



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TABLE OF CONTENTS

SECTION 3

EMERGENCY PROCEDURES

Parag No.	raph	Page No.
3.1	General	3-1
3.3	Airspeeds for Safe Operation	3-2
3.5	Emergency Procedures Checklist	3-2
0.0	Engine Fire During Start	3-2
	Engine Power Loss During Takeoff	3-2
	Engine Power Loss In Flight	3-3
	Power Off Landing	3-3
	Fire In Flight	3-4
	Loss of Oil Pressure	3-4
	Loss of Fuel Pressure	3-4
	High Oil Temperature	3-5
	Electrical Failures	3-5
	Electrical Overload	3-6
	Spin Recovery	3-6
	Open Door	3-7
	Carburetor Icing	3-7
	Engine Roughness	3-7
3.7	Amplified Emergency Procedures (General)	3-9
3.9	Engine Fire During Start	3-9
3.11	Engine Power Loss During Takeoff	3-9
3.13	Engine Power Loss In Flight	3-10
3.15	Power Off Landing	3-11
3.17	Fire In Flight.	3-11
3.19	Loss of Oil Pressure	3-12
3.21	Loss of Fuel Pressure	3-13
3.23	High Oil Temperature	3-13

TABLE OF CONTENTS (cont) SECTION 3 (cont)

Parag No.	graph	Page
3.25	Electrical Failures	3-14
		3-14
3.29	Spin Recovery	3-15
3.31	Open Door	3-15
3.33	Carburetor Icing	3-16
	Engine Roughness	3-16

SECTION 3

EMERGENCY PROCEDURES

3.1 GENERAL

ISSUED: JULY 12, 1995

The recommended procedures for coping with various types of emergencies and critical situations are provided by this section. All of required (FAA regulations) emergency procedures and those necessary for the operation of the airplane as determined by the operating and design features of the airplane are presented.

Emergency procedures associated with those optional systems and equipment which require handbook supplements are provided in Section 9 (Supplements).

The first portion of this section consists of an abbreviated emergency check list which supplies an action sequence for critical situations with little emphasis on the operation of systems.

The remainder of the section is devoted to amplified emergency procedures containing additional information to provide the pilot with a more complete understanding of the procedures.

These procedures are suggested as a course of action for coping with the particular condition described, but are not a substitute for sound judgment and common sense. Pilots should familiarize themselves with the procedures given in this section and be prepared to take appropriate action should an emergency arise.

Most basic emergency procedures, such as power off landings, are a normal part of pilot training. Although these emergencies are discussed here, this information is not intended to replace such training, but only to provide a source of reference and review, and to provide information on procedures which are not the same for all aircraft. It is suggested that the pilot review standard emergency procedures periodically to remain proficient in them.

REPORT: VB-1611

3.3 AIRSPEEDS FOR SAFE OPERATION

Stall Speeds 2550 lbs (0° Flaps)	
2550 lbs (0° Flaps)	50 KIAS
2550 lbs (Full Flaps)	45 KIAS
Maneuvering Speeds	
2550 lbs	113 KIAS
1634 lbs	89 KIAS
Never Exceed Speed	154 KIAS
2550 lbs (0° Flaps)	76 KIAS

3.5 EMERGENCY PROCEDURES CHECK LIST

ENGINE FIRE DURING START

Starter	crank engine
Mixture	idle cut-off
Throttle	open
Electric fuel pump	OFF
Fuel selector	OFF
Abandon if fire continues.	

ENGINE POWER LOSS DURING TAKEOFF

If sufficient runway remains for a normal landing, land straight ahead.

If insufficient runway remains:

Maintain safe airspeed.

Make only shallow turn to avoid obstructions.

Flaps as situation requires.

If sufficient altitude has been gained to attempt a restart:

Maintain safe airspeed.

Fuel selector	
	containing fuel
Electric fuel pump	check ON
Mixture	
Carburetor heat	ON

If power is not regained, proceed with power off landing.

ENGINE POWER LOSS IN FLIGHT If at low altitude: AirspeedMAINTAIN 76 KIAS If altitude permits: Fuel selector.......switch to tank containing fuel Electric fuel pumpON Carburetor heat.....ON of cause of power loss If no fuel pressure is indicated, check tank selector position to be sure it is on a tank containing fuel. When power is restored: Carburetor heatOFF Electric fuel pump......OFF If power is not restored prepare for power off landing. POWER OFF LANDING Trim for 76 KIAS. Locate suitable field. Establish spiral pattern. 1000 ft. above field at downwind position for normal landing approach. When field can easily be reached, slow to 66 KIAS for shortest landing. Touchdowns should normally be made at lowest possible airspeed with full flaps. When committed to landing: Mixture ______idle cut-off Magnetos.....OFF Battery Master switch.....OFF ALTR SwitchOFF

Fuel selector.......OFF
Seat belt and harness.....tight

FIRE IN FLIGHT

Source of fire	check
Electrical fire (smoke in cabin):	
Batt. Master switch	OFF
ALTR switch	OFF
Vents	open
Cabin heat	
Land as soon as possible.	
Engine fire:	
Fuel selector	
Throttle	CLOSED
Mixture	idle cut-off
Electric fuel pump	check OFF
Heater and defroster	OFF
Proceed with power off landing procedure.	

NOTE:

The possibility of an engine fire in flight is extremely remote. The procedure given is general and Pilot judgment should be the determining factor for action in such an emergency.

LOSS OF OIL PRESSURE

Land as soon as possible and investigate cause. Prepare for power off landing.

LOSS OF FUEL PRESSURE

Electric fuel pump	ON
Fuel selector	check on full tank

HIGH OIL TEMPERATURE

Land at nearest airport and investigate the problem. Prepare for power off landing.

ELECTRICAL FAILURES

ISSUED: JULY 12, 1995

NOTE:

Anytime the bus voltage is below 25 Vdc, the Low Bus Voltage Annunciator will be illuminated.

ALT annunciator light illuminated: Ammeter	Check to verify inop. alt.
If ammeter shows zero: ALT switch	OFF
Reduce electrical loads to minimum: ALT circuit breaker	Check and reset
ALT switch	ON
If power not restored: ALT switch	
If alternator output cannot be restored, reduce electras practical. Anticipate complete electrical failure.	rical loads and land as soon Duration of battery power

NOTE:

will be dependent on electrical load and battery condition prior to failure.

Low Bus Voltage Annunciator will be illuminated.

ELECTRICAL OVERLOAD (Alternator over 20 amps above knowlestical load)	wn
ALT switch	ON
BAT switch	
If alternator loads are reduced: Electrical loadReduce to Minim	ıum
Land as soon as practical.	
NOTE	

NOIE

Due to increased system voltage and radio frequency noise, operation with ALT switch ON and BAT switch OFF should be made only when required by an electrical system failure.

If alternator loads are not reduced: ALT switch.....OFF

Land as soon as possible. Anticipate complete electrical failure.

SPIN RECOVERY

Rudder full opposite to direction of rotation neutralizing ailerons Throttle idle Rudder.....neutral (when rotation stops) Control wheelas required to smoothly regain level flight attitude

OPEN DOOR

If both upper and side latches are open, the door will trail slightly open and airspeeds will be reduced slightly.

To close the door in flight:	
Slow airplane to 87 KIAS.	
Cabin vents	
Storm window	open
If upper latch is open	latch
If side latch is open	
	moving latch handle
	to latched position
	to lateriou position
If both latches are open	latch side latch
	then top latch
CARBURETOR ICING	tion top taken
	0.17
Carburetor heat	
Mixture	
	smoothness
THE POLICE PARTY	
ENGINE ROUGHNESS	
Carburetor heat	ON
If roughness continues after one min:	
Carburetor heat	OFF
Mixture	adjust for maximum
	smoothness
Electric fuel pump	ON
Fuel selector	
Engine gauges	
Magneto switches	
11101100 0 11 1101100	

If operation is satisfactory on either one, continue on that magneto at reduced power and full RICH mixture to first airport.

Prepare for power off landing.

ISSUED: JULY 12, 1995

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3.7 AMPLIFIED EMERGENCY PROCEDURES (GENERAL)

The following paragraphs are presented to supply additional information for the purpose of providing the pilot with a more complete understanding of the recommended course of action and probable cause of an emergency situation.

3.9 ENGINE FIRE DURING START

Engine fires during start are usually the result of overpriming. The first attempt to extinguish the fire is to try to start the engine and draw the excess fuel back into the induction system.

If a fire is present before the engine has started, move the mixture control to idle cut-off, open the throttle and crank the engine. This is an attempt to draw the fire back into the engine.

If the engine has started, continue operating to try to pull the fire into the engine.

In either case (above), if fire continues more than a few seconds, the fire should be extinguished by the best available external means.

The fuel selector valves should be OFF and the mixture at idle cut-off if an external fire extinguishing method is to be used.

3.11 ENGINE POWER LOSS DURING TAKEOFF

The proper action to be taken if loss of power occurs during takeoff will depend on the circumstances of the particular situation.

If sufficient runway remains to complete a normal landing, land straight ahead.

If insufficient runway remains, maintain a safe airspeed and make only a shallow turn if necessary to avoid obstructions. Use of flaps depends on the circumstances. Normally, flaps should be fully extended for touchdown.

If sufficient altitude has been gained to attempt a restart, maintain a safe airspeed and switch the fuel selector to another tank containing fuel. Check the electric fuel pump to insure that it is ON and that the mixture is RICH. The carburetor heat should be ON .

If engine failure was caused by fuel exhaustion, power will not be regained after switching fuel tanks until the empty fuel lines are filled. This may require up to ten seconds.

If power is not regained, proceed with the Power Off Landing procedure (refer to the emergency check list and Paragraph 3.15).

3.13 ENGINE POWER LOSS IN FLIGHT

Complete engine power loss is usually caused by fuel flow interruption and power will be restored shortly after fuel flow is restored. If power loss occurs at a low altitude, the first step is to prepare for an emergency landing (refer to Paragraph 3.15). An airspeed of at least 76 KIAS should be maintained.

If altitude permits, switch the fuel selector to another tank containing fuel and turn the electric fuel pump ON. Move the mixture control to RICH and the carburetor heat to ON. Check the engine gauges for an indication of the cause of the power loss. If no fuel pressure is indicated, check the tank selector position to be sure it is on a tank containing fuel.

When power is restored move the carburetor heat to the OFF position and turn OFF the electric fuel pump.

If the preceding steps do not restore power, prepare for an emergency landing.

If time permits, turn the Left and Right magneto switches OFF then ON one at a time. Move the throttle and mixture control levers to different settings. This may restore power if the problem is too rich or too lean a mixture or if there is a partial fuel system restriction. Try other fuel tanks. Water in the fuel could take some time to be used up, and allowing the engine to windmill may restore power. If power loss is due to water, fuel pressure indications will be normal.

If engine failure was caused by fuel exhaustion, power will not be restored after switching fuel tanks until the empty fuel lines are filled. This may require up to ten seconds.

If power is not regained, proceed with the Power Off Landing procedure (refer to the emergency check list and Paragraph 3.15).

3.15 POWER OFF LANDING

If loss of power occurs at altitude, trim the aircraft for best gliding angle 76 KIAS (Air Cond. off) and look for a suitable field. If measures taken to restore power are not effective, and if time permits, check your charts for airports in the immediate vicinity; it may be possible to land at one if you have sufficient altitude. If possible, notify the FAA by radio of your difficulty and intentions. If another pilot or passenger is aboard, let him help.

When you have located a suitable field, establish a spiral pattern around this field. Try to be at 1000 feet above the field at the downwind position, to make a normal landing approach. When the field can easily be reached, slow to 66 KIAS with flaps down for the shortest landing. Excess altitude may be lost by widening your pattern, using flaps or slipping, or a combination of these.

Touchdown should normally be made at the lowest possible airspeed.

When committed to a landing lower the flaps as desired, close the throttle, move the mixture to idle cut-off, and shut OFF the magnetos. Turn the battery master and alternator switches OFF. Move the fuel selector valve to OFF. The seat belts and shoulder harness should be tightened.

3.17 FIRE IN FLIGHT

The presence of fire is noted through smoke, smell and heat in the cabin. It is essential that the source of the fire be promptly identified through instrument readings, character of the smoke, or other indications since the action to be taken differs somewhat in each case.

Check for the source of the fire first.

REPORT: VB-1611

If an electrical fire is indicated (smoke in the cabin), the battery master switch should be turned OFF. The cabin vents should be opened and the cabin heat turned OFF. A landing should be made as soon as possible.

If an engine fire is present, switch the fuel selector to OFF and close the throttle. The mixture should be at idle cut-off. Turn the electric fuel pump OFF. In all cases, the heater and defroster should be OFF. If radio communication is not required, select battery master and alternator switchs OFF. Proceed with power off landing procedure.

NOTE

The possibility of an engine fire in flight is extremely remote. The procedure given is general and pilot judgment should be the determining factor for action in such an emergency.

3.19 LOSS OF OIL PRESSURE

Loss of oil pressure may be either partial or complete. A partial loss of oil pressure usually indicates a malfunction in the oil pressure regulating system, and a landing should be made as soon as possible to investigate the cause and prevent engine damage.

A complete loss of oil pressure indication may signify oil exhaustion or may be the result of a faulty gauge. In either case, proceed toward the nearest airport, and be prepared for a forced landing. If the problem is not a pressure gauge malfunction, the engine may stop suddenly. Maintain altitude until such time as a dead stick landing can be accomplished. Don't change power settings unnecessarily, as this may hasten complete power loss.

Depending on the circumstances, it may be advisable to make an off airport landing while power is still available, particularly if other indications of actual oil pressure loss, such as sudden increases in temperatures, or oil smoke, are apparent, and an airport is not close.

If engine stoppage occurs, proceed with Power Off Landing.

3.21 LOSS OF FUEL PRESSURE

The most probable cause of loss of fuel pressure is either fuel depletion in the fuel tank selected or failure of the engine driven fuel pump. If loss of fuel pressure occurs, turn ON the electric fuel pump and check that the fuel selector is on a tank containing usable fuel.

If loss of fuel pressure is due to failure of the engine driven fuel pump the electric fuel pump will supply sufficient fuel pressure.

After fuel pressure and power are regained, turn the electric fuel pump OFF. If fuel pressure starts to drop, turn the electric fuel pump ON and land at the nearest suitable airport as soon as possible and have the cause investigated.

CAUTION

If normal engine operation and fuel pressure is not immediately re-established, the electric fuel pump should be turned off. The lack of fuel pressure indication could indicate a leak in the fuel system, or fuel exhaustion.

3.23 HIGH OIL TEMPERATURE

ISSUED: JULY 12, 1995

An abnormally high oil temperature indication may be caused by a low oil level, an obstruction in the oil cooler, damaged or improper baffle seals, a defective gauge, or other causes. Land as soon as practical at an appropriate airport and have the cause investigated.

A steady, rapid rise in oil temperature is a sign of trouble. Land at the nearest airport and let a mechanic investigate the problem. Watch the oil pressure gauge for an accompanying loss of pressure.

3.25 ELECTRICAL FAILURES

NOTE:

Anytime the bus voltage is below 25 Vdc, the Low Bus Voltage Annunciator will be illuminated.

Loss of alternator output is detected through zero reading on the ammeter. Before executing the following procedure, insure that the reading is zero and not merely low by actuating an electrically powered device, such as the landing light. If no increase in the ammeter reading is noted, alternator failure can be assumed.

The electrical load should be reduced as much as possible. Check the alternator circuit breakers for a popped circuit.

The next step is to attempt to reset the overvoltage relay. This is accomplished by moving the ALT switch to OFF for one second and then to ON. If the trouble was caused by a momentary overvoltage condition (30.5 volts and up) this procedure should return the ammeter to a normal reading.

NOTE:

Low Bus Voltage Annunciator will be illuminated.

If the ammeter continues to indicate ``0'' output, or if the alternator will not remain reset, turn off the ALT switch, maintain minimum electrical load and land as soon as practical. Anticipate complete electrical failure. Duration of battery power will be dependent on electrical load and battery condition prior to failure.

3.27 ELECTRICAL OVERLOAD (Alternator over 20 amps above known electrical load)

If abnormally high alternator output is observed (more than 20 amps above known electrical load for the operating conditions) it may be caused by a low battery, a battery fault or other abnormal electrical load. If the cause is a low battery, the indication should begin to decrease toward normal within 5 minutes. If the overload condition persists attempt to reduce the load by turning off non-essential equipment.

Turn the BAT switch OFF and the ammeter should decrease. Turn the BAT switch ON and continue to monitor the ammeter. If the alternator output does not decrease within 5 minutes, turn the BAT switch OFF and land as soon as practical. All electrical loads are being supplied by the alternator.

NOTE

Due to higher voltage and radio frequency noise, operation with the ALT switch ON and the BAT switch OFF should be made only when required by an electrical failure.

3.29 SPIN RECOVERY

Intentional spins are prohibited in this airplane. If a spin is inadvertently entered, immediately apply full rudder opposite to the direction of rotation. Move the control wheel full forward while neutralizing the ailerons. Move the throttle to IDLE. When the rotation stops, neutralize the rudder and ease back on the control wheel as required to smoothly regain a level flight attitude.

3.31 OPEN DOOR

The cabin door is double latched, so the chances of its springing open in flight at both the top and side are remote. However, should you forget the upper latch, or not fully engage the side latch, the door may spring partially open. This will usually happen at takeoff or soon afterward. A partially open door will not affect normal flight characteristics, and a normal landing can be made with the door open.

If both upper and side latches are open, the door will trail slightly open, and airspeed will be reduced slightly.

To close the door in flight, slow the airplane to 87 KIAS, close the cabin vents and open the storm window. If the top latch is open, latch it. If the side latch is open, pull on the armrest while moving the latch handle to the latched position. If both latches are open, close the side latch then the top latch.

REPORT: VB-1611

3.33 CARBURETOR ICING

Under certain moist atmospheric conditions at temperatures of -5°C to 20°C, it is possible for ice to form in the induction system, even in summer weather. This is due to the high air velocity through the carburetor venturi and the absorption of heat from this air by vaporization of the fuel.

To avoid this, carburetor preheat is provided to replace the heat lost by vaporization. Carburetor heat should be full on when carburetor ice is encountered. Adjust mixture for maximum smoothness.

3.35 ENGINE ROUGHNESS

Engine roughness is usually due to carburetor icing which is indicated by a drop in RPM, and may be accompanied by a slight loss of airspeed or altitude. If too much ice is allowed to accumulate, restoration of full power may not be possible; therefore, prompt action is required.

Turn carburetor heat on (See Note). RPM will decrease slightly and roughness will increase. Wait for a decrease in engine roughness or an increase in RPM, indicating ice removal. If no change in approximately one minute, return the carburetor heat to OFF.

If the engine is still rough, adjust the mixture for maximum smoothness. The engine will run rough if too rich or too lean. The electric fuel pump should be switched to ON and the fuel selector switched to the other tank to see if fuel contamination is the problem. Check the engine gauges for abnormal readings. If any gauge readings are abnormal, proceed accordingly. Select the Left magneto switch OFF then ON and repeat with the Right magneto switch. If operation is satisfactory on either magneto, proceed on that magneto at reduced power, with mixture full RICH, to a landing at the first available airport.

If roughness persists, prepare for a precautionary landing at pilot's discretion.

NOTE

Partial carburetor heat may be worse than no heat at all, since it may melt part of the ice, which will refreeze in the intake system. When using carburetor heat, therefore, always use full heat, and when ice is removed return the control to the full cold position.

TABLE OF CONTENTS SECTION 4

NORMAL PROCEDURES

Parag No.	raph	Page No.
4.1	General	4-1
4.3	Airspeeds for Safe Operations	4-1
4.5	Normal Procedures Checklist	4-3
	Preflight Check	4-3
	Engine Start - General	4-6
	Before Starting Engine	4-7
	Normal Start - Cold Engine	4-7
	Normal Start - Hot Engine	4-7
	Engine Start - When Flooded	4-8
	Starting With External Power Source	4-8
	Warm-Up	4-9
	Taxiing	4-9
	Ground Check	4-9
	Before Takeoff	4-10
	Takeoff	4-10
	Short Field, Obstacle Clearance	4-11
	Climb	4-11
	Cruising	4-11
	Descent	4-11
	Approach and Landing	4-12
	Stopping Engine	4-12
	Mooring	4-12
4.7	Preflight Check	4-14
4.9	Engine Start - General	4-17
4.11	Before Starting Engine	4-17
4.13	Starting Engine	4-18
4.15	Warm-Up	4-20
4.17	Taxiing	4-20
4.19	Ground Check	4-20

TABLE OF CONTENTS (cont)

SECTION 4 (cont)

Parag No.	graph	Pag No
4.21	Before Takeoff	4-21
4.23	Takeoff	4-22
4.25	Climb	4-22
4.27	Cruising	4-23
4.29	Descent	4-24
4.31	Approach and Landing	4-24
4.33	Stopping Engine	4-25
4.35	Mooring	4-26
4.37	Stalls	4-26
4.39	Turbulent Air Operation	4-27
4.41	Weight and Balance	4-27
4.43	Noise Level	4-27

SECTION 4

NORMAL PROCEDURES

4.1 GENERAL

This section describes the recommended procedures for the conduct of normal operations for the Archer III. All of the required (FAA regulations) procedures and those necessary for operation of the airplane as determined by the operating and design features of the airplane are presented.

Normal procedures associated with those optional systems and equipment which require handbook supplements are provided by Section 9 (Supplements).

These procedures are provided to present a source of reference and review and to supply information on procedures which are not the same for all aircraft. Pilots should familiarize themselves with the procedures given in this section in order to become proficient in the normal operations of the airplane.

The first portion of this section consists of a short form check list which supplies an action sequence for normal operations with little emphasis on the operation of the systems.

The remainder of the section is devoted to amplified normal procedures which provide detailed information and explanations of the procedures and how to perform them. This portion of the section is not intended for use as an in-flight reference due to the lengthly explanations. The short form check list should be used for this purpose.

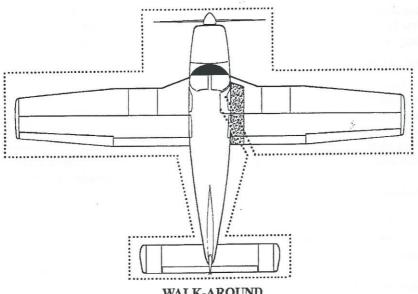
4.3 AIRSPEEDS FOR SAFE OPERATIONS

ISSUED: JULY 12, 1995

The following airspeeds are those which are significant to the safe operation of the airplane. These figures are for standard airplanes flown at gross weight under standard conditions at sea level.

Performance for a specific airplane may vary from published figures depending upon the equipment installed, the condition of the engine, airplane and equipment, atmospheric conditions and piloting technique.

(a)	Best Rate of Climb Speed	76 KIAS
(b)	Best Angle of Climb Speed	64 KIAS
(c)	Turbulent Air Operating Speed (See	
	Subsection 2.3)	113 KIAS
(d)	Maximum Flap Speed	102 KIAS
(e)	Landing Final Approach Speed (Flaps 40)	66 KIAS
(f)	Maximum Demonstrated Crosswind Velocity	17 KTS



WALK-AROUND

Figure 4-1

4.5 NORMAL PROCEDURES CHECK LIST

COCKPIT

PREFLIGHT CHECK

Control wheel	release restraints
Parking brake	set
Avionics ,	OFF
All switches	OFF
Mixture	idle cut-off
Magneto switches	OFF
Battery master switch	ON
Fuel gauges	check quantity
Annunciator panel	check
Battery master switch	OFF
Flaps	extend
Primary flight controls	proper operation
Trim	neutral
Pitot and static systems	drain
Windows	

Required papers and POH
RIGHT WING
Surface condition
1 doi tank vont
CAUTION: When draining any amount of fuel, care should be taken to ensure that no fire hazard exists before starting engine.
Fuel tank sumpsdrain and check for water, sediment and proper fuel
Tie down and chockremove
Main gear strutproper
inflation $(4.5 \pm .25 \text{ in.})$
Tire
Brake block and disccheck
Fresh air inlet
NOSE SECTION
General condition
Cowlingsecure
Windshield
Propeller and spinner
Air inlets
Engine baffle seals
Chockremove
Nose gear strutproper
inflation $(3.25 \pm .25 \text{ in.})$
Nose wheel tire
Oil
Dipstick properly seated
Oil filler capsecure

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CAUTION : When draining any amount of fuel, care should be taken to ensure that no fire hazard exists before starting engine.		
Fuel strainerdrain		
LEFT WING		
Surface condition		
CAUTION: When draining any amount of fuel, care should be taken to ensure that no fire hazard exists before starting engine.		
Fuel tank sumpdrain and check for water, sediment and proper fuel		
Fuel tank vent		
Main gear strutproper inflation (4.5 \pm .25 in.)		
Tirecheck		
Brake block and disccheck		
Tie down and chockremove		
Fuel tank		
visually - secure cap		
Pitot/static headremove cover - holes clear		
Wing tip and lights		
Aileron and hinges		
Flap and hinges		
Static wicks		
FUSELAGE		
Antennas		
Empennage		
Stabilator and trim tab		

MISCELLANEOUS

Battery master switch	ON
Flaps	retract
Interior lighting	
Pitot heat switch	ON
Pitot heat OFF/INOP Annunciator	extinguished

CAUTION: Care should be taken when an operational check of the heated pitot head is being performed. The unit becomes very hot. Ground operation should be limited to three minutes to avoid damaging the heater elements.

NOTE: Secure and adjust all unused seat belts and shoulder harness to prevent control interference or passenger injury during flight in turbulent air.

Exterior lighting switches	ON and check
Pitot	
Stall warning horn	check
All lighting switches	
Pitot heat switch	
Pitot heat OFF/INOP Annunciator	illuminated
Battery master switch	OFF
Passengers	board
Door	
Seats	adjusted and /locked in position
Seat belts and harness	fasten/adjust
	check inertia reel

ENGINE START - GENERAL

CAUTION: Do not attempt flight if there is no indication of alternator output.

CAUTION: If a positive oil pressure is not indicated within 30 seconds following an engine start, stop the engine and determine the trouble. In cold weather it will take a few seconds longer to get a positive oil pressure indication.

BEFORE STARTING ENGINE

Brakes	set
Circuit breakers	check in
Alternate static source	OFF
Carburetor heat	full cold
Avionics	OFF
Fuel selector	desired tank
NORMAL START - COLD ENGINE	
Throttle	1/4 in. open
Battery master switch	ON
Alternator switch	ON
Left magneto switch	ON
Electric fuel pump	ON
Mixture	full RICH
Propeller	clear
Starter	engage
Throttle	adjust
Right magneto switch	ON

NOTE: If engine does not start within 10 seconds, prime and repeat starting procedure. Starter manufacturer recommends starter cranking periods be limited to 10 seconds with a 2 minute rest period between cranking periods. Maximum of 5 start periods allowed. If start is not achieved on fifth attempt allow starter to cool for 30 minutes before attempting additional starts.

NORMAL START - HOT ENGINE

Throttle		1/2 in, open
Battery master switch		ON
Alternator switch		ON
Left magneto switch		ON
Electric fuel pump		ON
Mixture		full RICH
Propeller		clear
Starter		
Throttle	i	adjust
Right magneto switch	***************************************	ON
Oil pressure		check

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GINE START WHEN FLOODED

Inrottle	open full
Battery master switch	ON
Alternator switch	
Left magneto switch	ON
Electric fuel pump	
Mixture	
Propeller	clear
Starter	engage
Mixture	advance
Throttle	retard
Right magneto switch	ON
Oil Pressure	

STARTING WITH EXTERNAL POWER SOURCE

CAUTION: It is possible to use the ship's battery in parallel by turning only the battery master switch ON. This will give longer cranking capabilities, but will not increase the amperage. Care should be exercised if the ship's battery has been depleted. The external power supply can be be reduced to the level of the ship's battery. This can be tested by turning only the battery master switch on momentarily while the starter is engaged. If cranking speed increases, the ship's battery is at a higher level than the external power supply. If the battery is at a lower level than the external power supply, continue starting with the battery master switch off.

Battery master switch	OFF
Alternator switch	OFF
Left magneto switch	ON
All electrical equipment	OFF
Terminals	
External power plug	insert in fuselage

Proceed with normal start
Throttle lowest possible RPM Right magneto switch ON External power plug disconnect from fuselage Battery master switch ON - check ammeter Oil pressure check
WARM-UP
Throttle
TAXIING
Taxi area
GROUND CHECK
Parking brakeset Throttle2000 RPM Magnetosmax. drop 175 RPM max. diff. 50 RPM
Vacuum
Engine is warm for takeoff when throttle can be opened without engine faltering.
Electric fuel pump. OFF Fuel pressure

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BEFORE TAKEOFF

to climb attitude

SHORT FIELD, OBSTACLE CLEARANCE

Flaps
Accelerate to 55 KIAS depending on aircraft weight. Control wheel
After breaking ground, accelerate to 60 KIAS depending on aircraft weight. Accelerate to best flaps up angle of climb speed - 64 KIAS. Flaps
Accelerate to best flaps up rate of climb speed - 76 KIAS.
CLIMB
Best rate (flaps up) 76 KIAS Best angle. (flaps up) 64 KIAS En route 87 KIAS Electric fuel pump OFF at desired altitude
CRUISING
Power
DESCENT
NORMAL Throttle
POWER OFF
Carburetor heat ON if required Throttle

ISSUED: JULY 12, 1995

REVISED: NOVEMBER 6, 1998

REPORT: VB-1611

APPROACH AND LANDING

Fuel selector	proper tank
Seat backs	erect
Seats	adjusted and locked in position
Belts/harness	fasten/adjust
Electric fuel pump	ON
Mixture	set
Flaps	set - 102 KIAS max
Air conditioner (if installed)	OFF
Initial approach speed	75 KIAS
Final approach speed (flaps 40°)	66 KIAS

STOPPING ENGINE

CAUTION:

The flaps must be placed in the up position for the flap stop to support weight. Passengers should be cautioned accordingly.

Flaps	retract
Electric fuel pump	
Air conditioner (if installed)	
Avionics master switch	OFF
Electrical switches	OFF
Throttle	closed
Mixture	idle cut-off
Magneto switches	
Alternator switch	
Battery master switch	
MOORING	
Parking brake	set
Flaps	full up
Control wheel	
Wheel chocks	
Tie downs	

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4.7 PREFLIGHT CHECK

The airplane should be given a thorough preflight and walk-around check. The preflight should include a check of the airplane's operational status, computation of weight and C.G. limits, takeoff distance and in-flight performance. A weather briefing should be obtained for the intended flight path, and any other factors relating to a safe flight should be checked before takeoff.

CAUTION

The flap position should be noted before boarding the airplane. The flaps must be placed in the UP position before they will lock and support weight on the step.

COCKPIT

Upon entering the cockpit, release the seat belts securing the control wheel. Set the parking brake by first depressing and holding the toe brake pedals and then pull the parking brake lever while depressing the knob attached to the top of he handle. Insure that all electrical switches are OFF. Turn OFF all avionics equipment (to save power and prevent wear on the units). The mixture should be in idle cut-off and the magneto switches in the OFF position. Turn ON the battery master switch, check the fuel quantity gauges for adequate supply, check that the annunciator panel illuminates. Turn OFF the battery master switch. Check the primary flight controls for proper operation, extend the flaps and set the trim to neutral. Open the pitot and static drains to remove any moisture that has accumulated in the lines. Check the windows for cleanliness and that the required papers are on board. Properly stow and secure the tow bar and baggage. Close and secure the baggage door.

RIGHT WING

Begin the walk-around at the trailing edge of the right wing by checking that the wing surface and control surfaces are clear of ice, frost, snow or other extraneous substances. Check the flap, aileron and hinges for damage and operational interference. Static wicks should be firmly attached and in good condition. Check the wing tip and lights for damage.

Open the fuel cap and visually check the fuel supply. Replace cap securely. The fuel tank vent should be clear of obstructions.

Place a container under the quick drain. Drain the fuel tanks through the quick drain prior to the first flight and after refueling, making sure that enough fuel has been drained to verify the proper fuel and insure that all water and sediment is removed.

CAUTION

When draining any amount of fuel, care should be taken to insure that no fire hazard exists before starting engine.

Remove the tie down and chock.

Next, complete a check of the landing gear. Check the gear strut for proper inflation; there should be $4.5 \pm .25$ inches of strut exposure under a normal static load. Check the tire for cuts, wear, and proper inflation. Make a visual check of the brake block and disc.

Check that the fresh air inlet is clear of foreign matter.

NOSE SECTION

Check the general condition of the nose section; look for oil or fluid leakage and that the cowling is secure. Check the windshield and clean if necessary. The propeller and spinner should be checked for detrimental nicks, cracks, or other defects. The air inlets should be clear of obstructions. Check the engine baffle seals

Remove the chock and check the nose gear strut for proper inflation; there should be $3.25 \pm .25$ inches of strut exposure under a normal static foad. Check the tire for cuts, wear, and proper inflation. Check the oil level; make sure that the dipstick has been properly seated and that the oil filler cap has been properly secured. Drain the fuel strainer valve located on the bottom left side of the engine compartment.

CATITION

When draining any amount of fuel, care should be taken to ensure that no fire hazard exists before starting engine.

LEFT WING

ISSUED: JULY 12, 1995

The wing surface should be clear of ice, frost, snow, or other extraneous substances. Check that the fresh air inlet is clear of foreign matter and remove the tie downs and chocks. Check the gear strut for proper inflation: there should be $4.5 \pm .25$ inches of strut exposure under a normal static load. Check the tire and the brake block and disc.

REPORT: VB-1611

Open the fuel cap and visually check the fuel supply. Replace cap securely. The fuel tank vent should be clear of obstructions. Place a container under the quick drain. Drain enough fuel to verify the proper fuel and to insure that all water and sediment has been removed.

CAUTION

When draining any amount of fuel, care should be taken to ensure that no fire hazard exists before starting engine.

Remove the cover from the pitot/static head on the underside of the wing. Make sure the holes are open and clear of obstructions. Check the wing tip and lights for damage. Check the aileron, flap, and hinges for damage and operational interference. Check that the static wicks are firmly attached and in good condition.

FUSELAGE

Check the condition of any antennas located on the fuselage. All surfaces of the empennage should be examined for damage and operational interference and clear of ice, frost and snow. Fairings and access covers should be attached properly. Check the baggage to be sure it is stowed properly. Check that the lights on the tail are clean and intact. The stabilator and rudder should be operational and free from interference of any type. Check the condition of the tabs and insure that all hinges and push rods are sound and operational. If the tail has been tied down, remove the tie down rope.

MISCELLANEOUS

Turn the battery master switch "ON" and begin checking the interior lights by turning "ON" the necessary switches. After the interior lights are checked, turn "ON" the pitot heat switch and the exterior light switches. Next, perform a walk-around check on the exterior lights. With the pitot heat on the pitot heat OFF/INOP annunciator will extinguish informing the pilot that the pitot heat is activated.

Check the heated pitot head for proper heating. Turn all electrical switches and battery master switch OFF. Verify that the pitot heat OFF/INOP annunciator illuminates when pitot heat is turned OFF.

CAUTION:

Care should be taken when an operational check of the heated pitot head is being performed. The unit becomes very hot. Ground operation should be limited to three minutes maximum to avoid damaging the heating elements.

When all passengers are on board, the pilot should check the cabin doors for proper closing and latching procedures. The door should be gently pulled shut, the door handle firmly latched and the overhead latch button turned to the "LOCK" position. Seat belts on empty seats should be snugly fastened. All passengers should fasten their seat belts and shoulder harnesses. Adjust and lock seats in position.

NOTE:

With the shoulder harness fastened and adjusted, a pull test of it's locking restraint feature should be performed.

4.9 ENGINE START - GENERAL

CAUTION:

Do not attempt flight if there is no indication of alternator output.

CAUTION:

If a positive oil pressure is not indicated within 30 seconds following an engine start, stop the engine and determine the trouble. In cold weather it will take a few seconds longer to get a positive oil pressure indication.

NOTE:

Starter manufacturer recommends starter cranking periods be limited to 10 seconds with a 2 minute rest period between cranking periods. Maximum of 5 start periods allowed. If start is not achieved on fifth attempt allow starter to cool for 30 minutes before attempting additional starts.

4.11 BEFORE STARTING ENGINE

Before starting the engine, the brakes should be set. Check to make sure all the circuit breakers are in and the carburetor heat is off. Check that the avionics master switch is OFF. Check the fuel selector control to verify the desired tank.

ISSUED: JULY 12, 1995 REVISED: June 15, 2009 REPORT: VB-1611 4-17

STARTING ENGINE

(a) Starting Engine When Cold

Open the throttle lever approximately 1/4 inch. Turn ON the battery master switch, alternator switch, left magneto switch and the electric fuel pump.

Move the mixture control to full RICH, verify the propeller area is clear and engage the starter. When the engine fires, release the starter switch, and move the throttle to the desired setting. Turn ON the right magneto switch. Check the oil pressure for a positive indication.

If the engine does not fire within five to ten seconds, disengage the starter, prime the engine and repeat the starting procedure.

(b) Normal Start; Hot Engine

Open the throttle approximately 1/2 inch. Turn ON the battery master switch, alternator switch, left magneto switch and the electric fuel pump. Move the mixture control lever to full RICH, verify the propeller area is clear and engage the starter. When the engine fires, release the starter switch and move the throttle to the desired setting. Turn ON the right magneto switch. Check the oil pressure for a positive indication.

(c) Engine Start When Flooded

The throttle lever should be full OPEN. Turn ON the battery master switch, alternator switch, left magneto switch, and turn OFF the electric fuel pump. Move the mixture control lever to idle cut-off, verify the propeller area is clear and engage the starter. When the engine fires, release the starter switch, advance the mixture and retard the throttle. Turn ON the right magneto switch. Check the oil pressure for a positive indication.

(d) Starting Engine With External Power Source

CAUTION:

It is possible to use the ship's battery in parallel by turning only the battery master switch ON. This will give longer cranking capabilities, but will not increase the amperage. Care should exercised if the ship's battery has been depleted. The external power supply can be be reduced to the level of the ship's battery. This can be tested by turning only the battery master switch on momentarily while the starter is engaged. If cranking speed increases, the ship's battery is at a higher level than the external power supply. If the battery is at a lower level than the external power supply, continue starting with the battery master switch off.

Verify that the battery master, alternator switches are OFF, left magneto switch is ON, and all electrical equipment is OFF. Connect the RED lead of the PEP kit jumper cable to the POSITIVE () terminal of an external 24-volt battery and the BLACK lead to the NEGATIVE (-) terminal. Insert the plug of the jumper cable into the socket located on the fuselage. Note that when the plug is inserted, the electrical system is ON. Proceed with the normal starting technique.

After the engine has started, reduce power to the lowest possible RPM to reduce sparking, and turn ON the right magneto switch. Disconnect the jumper cable from the aircraft. Turn the battery master and alternator switches ON and check the alternator ammeter for an indication of output. Check the oil pressure for a positive indication. DO NOT ATTEMPT FLIGHT IF THERE IS NO INDICATION OF ALTERNATOR OUTPUT.

ISSUED: JULY 12, 1995 REVISED: APRIL 15, 2002 REPORT: VB-1611

4-19

4.15 WARM-UP

Warm-up the engine at 800 to 1200 RPM for not more than two minutes in warm weather and four minutes in cold. Avoid prolonged idling at low RPM, as this practice may result in fouled spark plugs.

Takeoff may be made as soon as the ground check is completed, provided that the throttle may be opened fully without backfiring or skipping, and without a reduction in engine oil pressure.

Do not operate the engine at high RPM when running up or taxiing over ground containing loose stones, gravel or any loose material that may cause damage to the propeller blades.

4.17 TAXIING

Before attempting to taxi the airplane, ground personnel should be instructed and approved by a qualified person authorized by the owner. Ascertain that the propeller back blast and taxi areas are clear.

Power should be applied slowly to start the taxi roll. Taxi a few feet forward and apply the brakes to determine their effectiveness. While taxiing, make slight turns to ascertain the effectiveness of the steering.

Observe wing clearances when taxiing near buildings or other stationary objects. If possible, station an observer outside the airplane.

Avoid holes and ruts when taxiing over uneven ground.

Do not operate the engine at high RPM when running up or taxiing over ground containing loose stones, gravel or any loose material that may cause damage to the propeller blades.

4.19 GROUND CHECK

Set the parking brake.

The magnetos should be checked at 2000 RPM. Drop off on either magneto should not exceed 175 RPM and the difference between the magnetos should not exceed 50 RPM. Operation on one magneto should not exceed 10 seconds.

Check the vacuum gauge; the indicator should read 4.8" to 5.2" Hg at 2000 RPM.

Check the annunciator panel lights with the press-to-test button. Also check the air conditioner.

Carburetor heat should also be checked prior to takeff to be sure the control is operating properly and to clear any ice which may have formed during taxiing. Avoid prolonged ground operation with carburetor heat "ON" as the air is unfiltered. Engine RPM should decrease no more than 75 RPM when carburator heat is on. If no or excessive RPM decrease is observed, investigate and have the cause corrected prior to flight.

The electric fuel pump should be turned OFF after starting or during warm-up to make sure that the engine driven pump is operating. Prior to takeoff the electric pump should be turned ON again to prevent loss of power during takeoff should the engine driven pump fail.

4.21 BEFORE TAKEOFF

ISSUED: JULY 12, 1995

All aspects of each particular takeoff should be considered prior to executing the takeoff procedure.

Verify that the battery master, alternator, magneto switches are ON and check and set all of the flight instruments as required. Check the fuel selector to make sure it is on the proper tank (fullest). Turn ON the electric fuel pump and check the engine gauges. The carburetor heat should be in the OFF position.

All seat backs should be erect with all seats adjusted and locked in position.

The mixture should be set. The seat belts and shoulder harness should be fastened and adjusted. Fasten the seat belts snugly around the empty seats.

NOTE

With the shoulder harness fastened and adjusted, a pull test of its locking restraint feature should be performed.

REPORT: VB-1611

4-21

Exercise and set the flaps and trim tab. Insure proper flight control movement and response.

All doors should be properly secured and latched.

On air conditioned models, the air conditioner must be OFF to insure normal takeoff performance.

4.23 TAKEOFF

NORMAL TECHNIQUE (SEE CHART, SECTION 5)

When the available runway length is well in excess of that required and obstacle clearance is no factor, the normal takeoff technique may be used. The flaps should be set in the retracted position and the pitch trim set slightly aft of neutral. Align the airplane with the runway, apply full power, and accelerate to 60 KIAS depending on weight. Apply back pressure to the control wheel to lift off, then control pitch attitude as required to attain the desired climb speed.

SHORT FIELD TECHNIQUE (SEE CHART, SECTION 5)

For departure from short runways with adjacent obstructions, a short field takeoff technique with flaps set to 25° should be used in accordance with the short field takeoff ground roll-flaps 25° and short field performance - flaps 25° charts. Maximum power is established before brake release and the airplane is accelerated to 55 KIAS depending on aircraft weight for liftoff. After liftoff, control the airplane attitude to accelerate to 60 KIAS depending on aircraft weight, passing through the 50 foot obstacle height. Once clear of the obstacle accelerate to the best flaps up angle of climb speed of 64 KIAS while retracting the flaps. Transition to 76 KIAS, flaps up best rate of climb speed.

4.25 CLIMB

The best rate of climb at gross weight will be obtained at 76 KIAS. The best angle of climb may be obtained at 64 KIAS. At lighter than gross weight these speeds are reduced somewhat. For climbing en route, a speed of 87 KIAS is recommended. This will produce better forward speed and increased visibility over the nose during the climb.

When reaching the desired altitude, the electric fuel pump may be turned off.

REPORT: VB-1611 ISSUED: JULY 12, 1995 4-22 REVISED: NOVEMBER 6, 1998

4.27 CRUISING

The cruising speed of the ARCHER III is determined by many factors, including power setting, altitude, temperature, loading and equipment installed in the airplane.

The normal maximum cruising power is 75% of the rated horsepower of the engine. Airspeeds which may be obtained at various altitudes and power settings can be determined from the performance graphs provided by Section 5.

Use of the mixture control in cruising flight reduces fuel consumption significantly, especially at higher altitudes. The mixture should be leaned during cruising operation above 5000 ft. altitude and at pilot's discretion at lower altitudes when 75% power or less is being used. If any doubt exists as to the amount of power being used, the mixture should be in the full RICH position for all operations under 5000 feet.

To lean the mixture, disengage the lock and pull the mixture control back.

Best economy mixture is obtained by slowly leaning the mixture until engine operation becomes rough or until engine power rapidly diminishes. When either condition occurs, enrich the mixture sufficiently to obtain an evenly firing engine. Some engine power and airspeed must be sacrificed to gain a best economy mixture setting.

Best power mixture is obtained by gradually leaning the mixture until either the tachometer or the airspeed indicator reading peaks.

If the airplane is equipped with the optional exhaust gas temperature (EGT) gauge, a more accurate means of leaning is available to the pilot. Best economy mixture is obtained by moving the mixture control aft until peak EGT is reached. Best power mixture is obtained by leaning to peak EGT and then enrichening until the EGT is 100F. rich of the peak value. Under some conditions of altitude and throttle position, the engine may exhibit roughness before peak EGT is reached. If this occurs, the EGT corresponding to the onset of engine roughness should be used as the peak reference value.

Always remember that the electric fuel pump should be turned ON before switching tanks, and should be left on for a short period thereafter. In order to keep the airplane in best lateral trim during cruising flight the fuel should be used alternately from each tank. It is recommended that one tank be used for one hour after takeoff, then the other tank be used for two hours; then return to the first tank, which will have approximately one and one half hours of fuel remaining if the tanks were full at takeoff. The second tank will contain approximately one half hour of fuel. Do not run tanks completely dry in flight. The electric fuel pump should be normally OFF so that any

ISSUED: JULY 12, 1995 REVISED: FEBRUARY 5, 2010 REPORT: VB-1611

n nction of the engine driven fuel pump is immediately apparent. If signs of __el starvation should occur at any time during flight, fuel exhaustion should be suspected, at which time the fuel selector should be immediately positioned to the other tank and the electric fuel pump switched to the ON position.

4.29 DESCENT

NORMAL

To achieve the performance on Figure 5-31 the power on descent must be used. The throttle should be set for 2500 RPM, mixture full rich and maintain an airspeed of 122 KIAS. In case carburetor ice is encountered apply full carburetor heat.

POWER OFF

If a prolonged power off descent is to be made, apply full carburetor heat prior to power reduction if icing conditions are suspected. Throttle should be retarded and mixture control leaned as required. Power response should be verified approximately every 30 seconds by partially opening and then closing the throttle (clearing the engine). When leveling off enrichen me, set power as required and select carburetor heat off unless carburetor icing conditions are suspected.

4.31 APPROACH AND LANDING

Check to insure the fuel selector is on the proper (fullest) tank and that the seat backs are erect, with the seats adjusted and locked in position. The seat belts and shoulder harness should be fastened and adjusted and the inertia reel checked.

NOTE

With the shoulder harness fastened and adjusted, a pull test of its locking restraint feature should be performed.

Turn ON the electric fuel pump and turn OFF the air conditioner. The mixture should be set in the full RICH position.

The airplane should be trimmed to an initial approach speed of about 75 KIAS with a final approach speed of 66 KIAS with flaps extended. The flating and be lowered at speeds up to 102 KIAS, if desired.

REPORT: VB-1611 4-24 **ISSUED: JULY 12, 1995**

The mixture control should be kept in full RICH position to insure maximum acceleration if it should be necessary to open the throttle again. Carburetor heat should not be applied unless there is an indication of carburetor icing, since the use of carburetor heat causes a reduction in power which may be critical in case of a go-around. Full throttle operation with carburetor heat on can cause detonation.

The amount of flap used during landings and the speed of the aircraft at contact with the runway should be varied according to the landing surface and conditions of wind and airplane loading. It is generally good practice to contact the ground at the minimum possible safe speed consistent with existing conditions.

Normally, the best technique for short and slow landings is to use full flap and enough power to maintain the desired airspeed and approach flight path. Mixture should be full RICH, fuel on the fullest tank, and electric fuel pump ON. Reduce the speed during the flareout and contact the ground close to the stalling speed. After ground contact hold the nose wheel off as long as possible. As the airplane slows down, gently lower the nose and apply the brakes. Braking is most effective when flaps are raised and back pressure is applied to the control wheel, putting most of the aircraft weight on the main wheels. In high wind conditions, particularly in strong crosswinds, it may be desirable to approach the ground at higher than normal speeds with partial or no flaps.

4.33 STOPPING ENGINE

At the pilot's discretion, the flaps should be raised and the electric fuel pump turned OFF.

NOTE

The flaps must be placed in the UP position for the flap step to support weight. Passengers should be cautioned accordingly.

ISSUED: JULY 12, 1995

REPORT: VB-1611

The air conditioner (when installed) and radios should be turned OFF, and the engine stopped by disengaging the mixture control lock and pulling the mixture control back to idle cut-off. The throttle should be left full aft to avoid engine vibration while stopping. Then the magneto, alternator and battery master, switches must be turned OFF.

4.35 MOORING

If necessary, the airplane should be moved on the ground with the aid of the nose wheel tow bar provided with each airplane and secured behind the rear seats. The aileron and stabilator controls should be secured by looping the safety belt through the control wheel and pulling it snug. The flaps are locked when in the UP position and should be left retracted.

Tie downs can be secured to rings provided under each wing and to the tail skid. The rudder is held in position by its connections to the nose wheel steering and normally does not have to be secured.

4.37 STALLS

The stall characteristics of the ARCHER III are conventional. An approaching stall is indicated by a stall warning horn which is activated between five and ten knots above stall speed. Mild airframe buffeting and gentle pitching may also precede the stall.

The gross weight stalling speed of the ARCHER III with power off and full flaps is 45 KIAS. With the flaps up this speed is increased 5 KTS. Loss of altitude during stalls varies from 100 to 350 feet, depending on configuration and power.

NOTE

The stall warning system is inoperative with the master switch OFF.

During preflight, the stall warning system should be checked by turning the master switch ON, lifting the detector and checking to determine if the horn is actuated. The master switch should be returned to the OFF position after the check is complete.

4.39 TURBULENT AIR OPERATION

In keeping with good operating practice used in all aircraft, it is recommended that when turbulent air is encountered or expected, the airspeed be reduced to maneuvering speed to reduce the structural loads caused by gusts and to allow for inadvertent speed build-ups which may occur as a result of the turbulence or of distractions caused by the conditions. (See Subsection 2.3)

4.41 WEIGHT AND BALANCE

It is the responsibility of the owner and pilot to determine that the airplane remains within the allowable weight vs. center of gravity envelope while in flight.

For weight and balance data, refer to Section 6 (Weight and Balance).

4.43 NOISE LEVEL

(a) FAR 36 Appendix G for aircraft with the standard exhaust system, the noise level is 73.1 dB(A). For aircraft with the optional exhaust system, the noise level is 71.9 dB(A).

No determination has been made by the Federal Aviation Administration that the noise levels of this airplane are or should be acceptable or unacceptable for operation at, into, or out of, any airport.

The above statement notwithstanding, the noise level stated above has been verified by and approved by the Federal Aviation Administration in noise level test flights conducted in accordance with FAR 36. Noise Standards -Aircraft Type and Airworthiness Certification. This aircraft model is in compliance with all FAR 36 noise standards applicable to this type.

(b) ICAO 10 for aircraft with the standard exhaust system, the noise level is 77.7 dB(A). For aircraft with the optional exhaust system, the noise level is 75.3 dB(A).

ISSUED: JULY 12, 1995

REVISED: NOVEMBER 18, 1996

4-27

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TABLE OF CONTENTS

SECTION 5

PERFORMANCE

Parag No.	graph	Page No.
5.1	General	5-1
5.3	Introduction to Performance and Flight Planning	5-1
5.5	Flight Planning Example	5-3
5.7	Performance Graphs	5-9
	List of Figures	5-9

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SECTION 5

PERFORMANCE

5.1 GENERAL

All of the required (FAA regulations) and complementary performance information applicable to the ARCHER III is provided by this section.

Performance information associated with those optional systems and equipment which require handbook supplements is provided by Section 9 (Supplements).

5.3 INTRODUCTION TO PERFORMANCE AND FLIGHT PLANNING

The performance information presented in this section is based on measured Flight Test Data corrected to I.C.A.O. standard day conditions and analytically expanded for the various parameters of weight, altitude, temperature, etc.

The performance charts are unfactored and do not make any allowance for varying degrees of pilot proficiency or mechanical deterioration of the aircraft. This performance, however, can be duplicated by following the stated procedures in a properly maintained airplane.

Effects of conditions not considered on the charts must be evaluated by the pilot, such as the effect of soft or grass runway surface on takeoff and landing performance, or the effect of winds aloft on cruise and range performance. Endurance can be grossly affected by improper leaning procedures, and inflight fuel flow and quantity checks are recommended.

REMEMBER! To get chart performance, follow the chart procedures.

The information provided by paragraph 5.5 (Flight Planning Example) outlines a detailed flight plan using the performance charts in this section. Each chart includes its own example to show how it is used.

WARNING

Performance information derived by extrapolation beyond the limits shown on the charts should not be used for flight planning purposes.

5.5 FLIGHT PLANNING EXAMPLE

(a) Aircraft Loading

The first step in planning the flight is to calculate the airplane weight and center of gravity by utilizing the information provided by Section 6 (Weight and Balance) of this handbook.

The basic empty weight for the airplane as licensed at the factory has been entered in Figure 6-5. If any alterations to the airplane have been made effecting weight and balance, reference to the aircraft logbook and Weight and Balance Record (Figure 6-7) should be made to determine the current basic empty weight of the airplane.

Make use of the Weight and Balance Loading Form (Figure 6-11) and the C.G. Range and Weight graph (Figure 6-15) to determine the total weight of the airplane and the center of gravity position.

After proper utilization of the information provided, the following weights have been determined for consideration in the flight planning example.

The landing weight cannot be determined until the weight of the fuel to be used has been established [refer to item (g)(1)].

(1)	Empty Weight	1400 lbs.
(2)	Occupants (2 x 170 lbs.)	340 lbs.
(3)	Baggage and Cargo	360 lbs.
(4)	Fuel (6 lb./gal. x 50)	300 lbs.
(5)	Takeoff Weight	2400 lbs.
(6)	Landing Weight	
	(a)(5) minus (g)(1), (2400 lbs.	
	minus 160.2 lbs.)	2239.8 lbs.

The takeoff weight is below the maximum of 2550 lbs. and the weight and balance calculations have determined that the C.G. position is within the approved limits.

ISSUED: JULY 12, 1995 REVISED: NOVEMBER 18, 1996

(b) Takeoff and Landing

After determining the aircraft loading, all aspects of takeoff and landing must be considered.

Conditions of the departure and destination airport must be acquired, evaluated and maintained throughout the flight.

Apply the departure airport conditions and takeoff weight to the appropriate Takeoff Performance graph (Figure 5-7 or 5-9) to determine the barrier distance or (Figure 5-11 or 5-13) to determine the length of runway necessary for the takeoff.

The landing distance calculations are performed in the same manner using the existing conditions at the destination airport and, when established, the landing weight.

The conditions and calculations for the example flight are listed below. The takeoff and landing distances required for the example flight have fallen well below the available runway lengths.

	gidan Sering poor decreased pool selling	Departure Airport	Destination Airport
(1)	Pressure Altitude	2000 ft.	2500 ft.
(2)	Temperature	23°C	21°C
(3)	Wind Component (Headwind)	8 Kt.	5 Kt.
(4)	Runway Length Available	7000 ft.	4500 ft.
(5)	Runway Required	1073 ft.*	820 ft.**

NOTE

The remainder of the performance charts used in this flight plan example assume a no wind condition. The effect of winds aloft must be considered by the pilot when computing climb, cruise and descent performance.

ISSUED: JULY 12, 1995 REVISED: APRIL 3, 1997

5-4

^{*}reference Figure 5-11 or 5-13

^{**}reference Figure 5-37

(c) Climb

The next step in the flight plan is to determine the necessary climb segment components.

The desired cruise pressure altitude and corresponding cruise outside air temperature values are the first variables to be considered in determining the climb components from the Time, Distance and Fuel to Climb graph (Figure 5-17). After the time, distance and fuel for the cruise pressure altitude and outside air temperature values have been established, apply the existing conditions at the departure field to the graph (Figure 5-17). Now, subtract the values obtained from the graph for the field of departure conditions from those for the cruise pressure altitude.

The remaining values are the true fuel, distance and time components for the climb segment of the flight plan corrected for field pressure altitude and temperature.

The following values were determined from the above instructions in the flight planning example.

(1)	Cruise Pressure Altitude	6000 ft.
(2)	Cruise OAT	15°C
(3)	Time to Climb (12 min. minus 3 min.)	9 min.*
(4)	Distance to Climb	
	(17 naut. miles minus 5 naut. miles)	12 naut. miles*
(5)	Fuel to Climb (4 gal, minus 2 gal.)	2 gal. *

(d) Descent

The descent data will be determined prior to the cruise data to provide the descent distance for establishing the total cruise distance.

Utilizing the cruise pressure altitude and OAT, determine the basic time, distance and fuel for descent (Figure 5-31). These figures must be adjusted for the field pressure altitude and temperature at the destination airport. To find the necessary adjustment values, use the existing pressure altitude and temperature conditions at the destination airport as variables to find the time, distance and fuel values from

^{*}reference Figure 5-17

the graph (Figure 5-31). Now, subtract the values obtained from the field conditions from the values obtained from the cruise conditions to find the true time, distance and fuel values needed for the flight plan.

The values obtained by proper utilization of the graphs for the descent segment of the example are shown below.

(1) Time to Descend

(16 min. minus 6 min.)

10 min.*

(2) Distance to Descend

(33 naut. miles minus 13 naut. miles)

20 naut. miles*

(3) Fuel to Descend

(3.2 gal. minus 1.3 gal.)

1.9 gal. *

(e) Cruise

Using the total distance to be traveled during the flight, subtract the previously calculated distance to climb and distance to descend to establish the total cruise distance. Refer to the appropriate Avco Lycoming Operator's Manual when selecting the cruise power setting. The established pressure altitude and temperature values and the selected cruise power should now be utilized to determine the true airspeed from the appropriate Speed Power graph (Figure 5-20 [a,b] and 5-21).

Calculate the cruise fuel flow for the cruise power setting from the information provided by the Avco Lycoming Operator's Manual.

The cruise time is found by dividing the cruise distance by the cruise speed and the cruise fuel is found by multiplying the cruise fuel flow by the cruise time.

The cruise calculations established for the cruise segment of the flight planning example are as follows:

(1) Total Distance

314 naut, miles

(2) Cruise Distance

(e)(1) minus (c)(4) minus (d)(2),

(314 nm minus 12 nm minus 20 nm)

282 naut, miles

^{*}reference Figure 5-31

(3)	Cruise Power	65%
(4)	Cruise Speed	117 Kts.*
(5)	Cruise Fuel Consumption	9.5 gal./hr.
(6)	Cruise Time	
	(e)(2) divided by (e)(4),	
	(282 nm divided by 117 kts)	2.4 hrs.
(7)	Cruise Fuel	
	(e)(5) multiplied by (e)(6),	
	(9.5 gal./hr multiplied by 2.4 hrs)	22.8 gal

(f) Total Flight Time

The total flight time is determined by adding the time to climb, the time to descend and the cruise time. Remember! The time values taken from the climb and descent graphs are in minutes and must be converted to hours before adding them to the cruise time.

The following flight time is required for the flight planning example.

(1) Total Flight Time (c)(3) plus (d)(1) plus (e)(6), (.15 hr plus .17 hr plus 2.4 hrs) 2.7 hrs

(g) Total Fuel Required

Determine the total fuel required by adding the fuel to climb, the fuel to descend and the cruise fuel. When the total fuel (in gallons) is determined, multiply this value by 6 lb./gal. to determine the total fuel weight used for the flight.

The total fuel calculations for the example flight plan are shown below.

(1) Total Fuel Required (c)(5) plus (d)(3) plus (e)(7), (2 gal. plus 1.9 gal. plus 22.8 gal.) 26.7 gal. (26.7 gal. multiplied by 6 lb./gal.) 160.2 lbs

*reference Figure 5-20a

ISSUED: JULY 12, 1995

REPORT: VB-1611

PA-28-181, ARCHER III

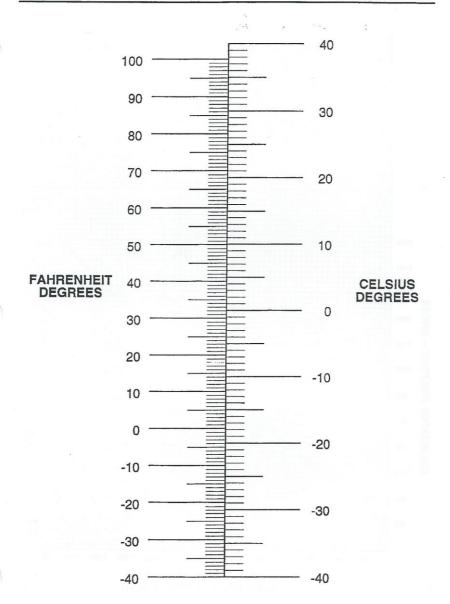
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5.7 PERFORMANCE GRAPHS

LIST OF FIGURES

Figur No.	e e	Pag No
5-1	Temperature Conversion	5-11
5-3	Airspeed System Calibration	5 12
5-5	Stall Speeds	5-13
5-7	Flaps Up Takeoff Performance	5-14
5-9	25 Flaps Takeoff Performance	5-15
5-11	Flaps Up Takeoff Ground Roll	5-16
5-13	25 Flaps Takeoff Ground Roll	5-17
5-15	Climb Performance	5-18
5-17	Time, Distance and Fuel to Climb.	5-19
5-19	Engine Performance	5-20
5-20	Engine/Cruise Performance (55%)	5-21
5-20a	Engine/Cruise Performance (65%)	5-22
5-20ь	Engine/Cruise Performance (75%)	5-23
5-21	Speed Power	5-25
5-27	Range (No reserve)	5-26
5-27a	Range (45 min. reserve)	5-27
5-29	Endurance (No reserve)	5-28
5-29a	Endurance (45 min. reserve)	5-29
5-31	Time, Distance and Fuel to Descend	
5-33	Glide Range	5-30
5-35	Landing Performance	5-31
5-37	Landing Ground Roll	5-32

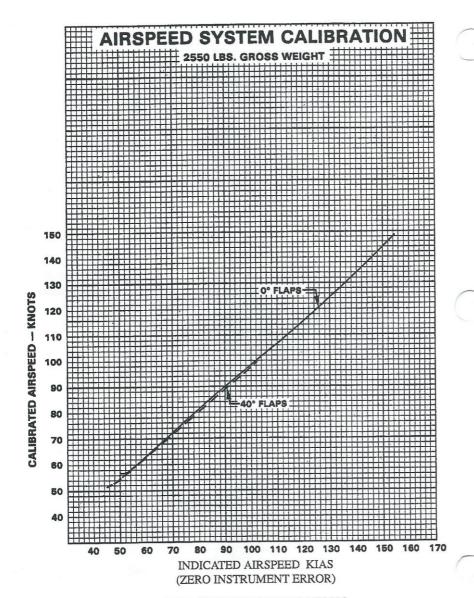
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TEMPERATURE CONVERSION
Figure 5-1

ISSUED: JULY 12, 1995

REPORT: VB-1611

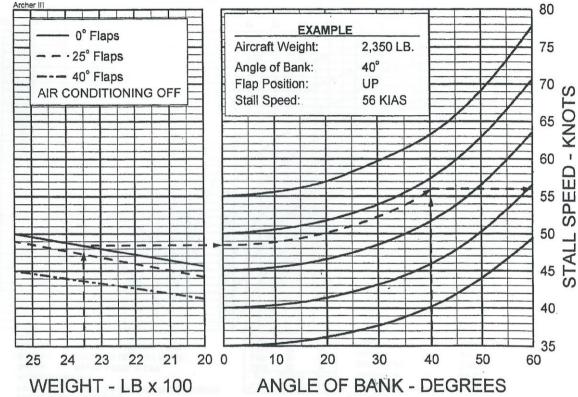


AIRSPEED SYSTEM CALIBRATION Figure 5-3

REPORT: VB-1611 5-12 **ISSUED: JULY 12, 1995**

PA-28-181, ARCHER III

POWER OFF STALL SPEED



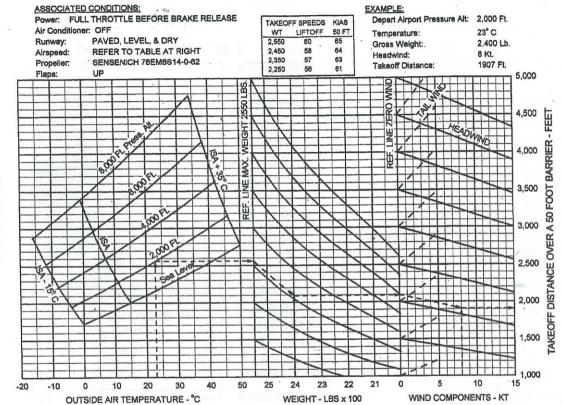
STALL SPEEDS Figure 5-5

PA-28-181, ARCHER III

FLAPS UP TAKEOFF PERFORMANCE

Figure 5-7

FLAPS UP TAKEOFF PERFORMANCE



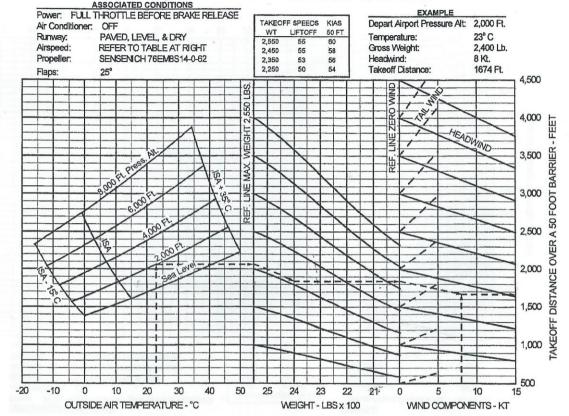
25° FLAPS TAKEOFF PERFORMANCE

Figure 5-9

PA-28-181,

ARCHER III

FLAPS 25° TAKEOFF PERFORMANCE



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1995

FLAPS UP TAKEOFF GROUND ROLL

Figure 5-11

FLAPS UP TAKEOFF GROUND ROLL



Air Conditioner: OFF

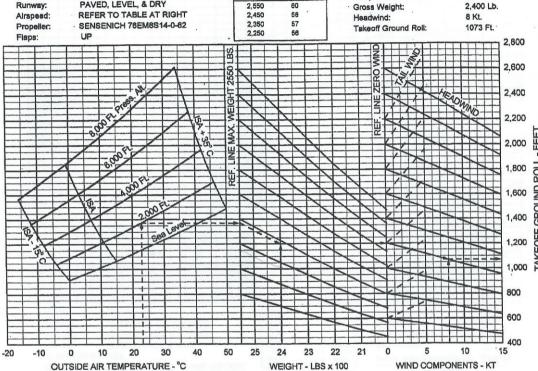
PAVED, LEVEL, & DRY

TAKEOFF SPEEDS KIAS LIFTOFF WT 2.550 2,450 58 2.350 57 2,250

EXAMPLE:

Depart Airport Pressure Alt: 2,000 Ft. 23° C

Temperature: Gross Weight: Headwind:



25°

FLAPS TAKEOFF GROUND ROLL

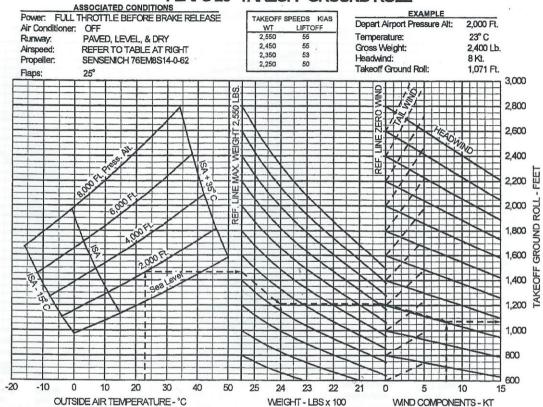
Figure 5-

FLAPS 25° TAKEOFF GROUND ROLL

PA-28-181, ARCHER III

PERFORMANCE

SECTION 5



ASSOCIATED CONDITIONS:

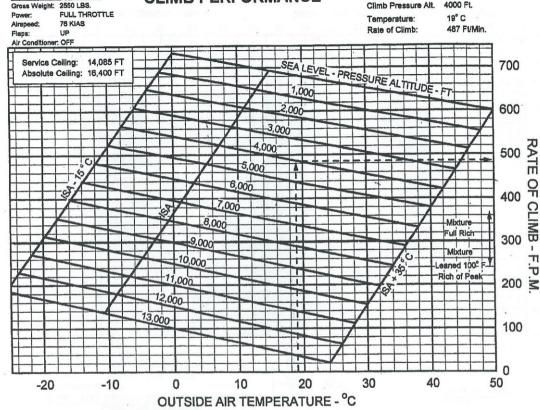
CLIMB PERFORMANCE

Figure 5-15

SECTION 5

PERFORMANCE

Temperature:



CLIMB PERFORMANCE

TIME, DISTANCE AND FUEL TO CLIMB Figure 5-17

PERFORMANCE SECTION 5

PA-28-181, ARCHER III

TIME, FUEL, DISTANCE TO CLIMB

ASSOCIATED CONDITIONS

Gross Weight: 2550 LB Power: **FULL THROTTLE**

Airspeed: 76 KIAS

NOTE: This chart includes fuel allowance for start, taxi, & takeoff.

EXAMPLE

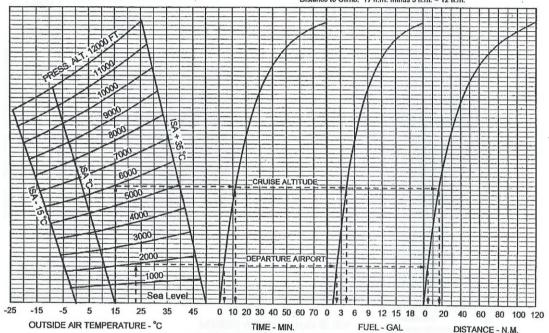
Depart Airport Press Alt.: 2000 FT.

Temperature: 23 °C 15 °C Cruise OAT:

Cruise Press Alt.: Time to Climb:

6000 FT. 12 min. minus 3 min. = 9 min

Fuel to Climb: 4 gal. minus 2 gal = 2 gal Distance to Climb: 17 n.m. minus 5 n.m. = 12 n.m.



ENGINE PERFORMANCE

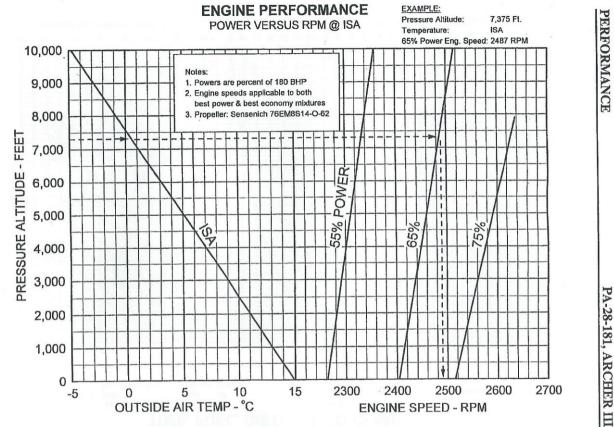
1,000

0

-5

0 5 10 OUTSIDE AIR TEMP - °C

Figure 5-19



15

2400

ENGINE SPEED - RPM

2300

2500

2600

2700

SECTION 5

Engine / Cruise Performance for Non-ISA OAT* RPM for Constant 55% Power Fuel Flow: Best Economy Mixture, 8.2 GPH

Pressure	Indicated (Outside Air	Temperature	Engine	True Air	
Altitude Feet	°C °C		°F	Speed RPM	Speed Knots **	
Sea Level	ISA-15	0	32	2245	105	
	ISA	15	59	2265		
	ISA +10	25	77	2275		
	ISA +20	35	95	2285		
	ISA +30	45	113	2295	106	
2000	ISA -15	-4	25	2265	106	
	ISA	11	52	2280		
	ISA +10	21	70	2295		
	ISA +20	31	88	2305		
	ISA +30	41	106	2315	107	
4000	ISA -15	-8	18	2285	106	
	IS:A	7	45	2300		
	ISA +10	17	63	2315		
	ISA +20	27	81	2325		
	ISA +30	37	99	2335	108	
6000	ISA -15	-12	10	2305	107	
	ISA	3	37	2320		
	ISA +10	13	55	2330		
	ISA +20	23	73	2345		
	ISA +30	33	91	2355	108	
8000	ISA -15	-16	3	2320	107	
	ISA	-1	30	2340		
	ISA +10	9	48	2350		
	ISA +17.5	16.5	62	2360	108	
9000	ISA -15	-18	0	2330	107	
	ISA	-3	27	2350		
	ISA +8.5	5.5	42	2360	108	
10000	ISA - 15	-20	-4	2340	107	
	ISA	-5	23	2360	108	

NOTE: * Aircraft weight 2550 Lbs., Wheel pants and strut fairings installed ** Subtract 3 KTAS if wheel pants are removed.

ENGINE/CRUISE PERFORMANCE (55%)

Figure 5-20

ISSUED: JULY 12, 1995

REPORT: VB-1611

Engine / Cruise Performance for Non-ISA OAT* RPM for Constant 65% Power Fuel Flow: Best Economy Mixture, 9.5 GPH

Pressure	Indicated O	utside Air	Temperature	Engine	True Air
Altitude Feet	°C	°C	°F	Speed RPM	Speed Knots **
Sea Level	ISA-15	0	32	2385	113
	ISA	15	59	2405	
	ISA +10	25	77	2415	
	ISA +20	35	95	2430	
	ISA +30	45	113	2440	116
2000	ISA -15	-4	25	2405	114
	ISA	11	52	2425	
	ISA +10	21	70	2440	
	ISA +20	31	88	2450	
	ISA +30	41	106	2465	117
4000	ISA -15	-8	18	2430	115
	ISA	7	45	2450	
	ISA +10	17	63	2460	
	ISA +20	27 .	81	2475	
	ISA +30	37	99	2485	118
6000	ISA -15	-12	10	2450	116
	ISA	3	37	2470	
	ISA +10	13	55	2485	
	ISA +20	23	73	2495	
	ISA +30	33	91	2510	119
8000	ISA -15	-16	3	2475	117
	ISA	-1	30	2495	
	ISA +10	9	48	2505	
	ISA +17.5	16.5	62	2515	119
9000	ISA -15	-18	0	2485	117
and the profession	ISA	-3	27	2505	
	ISA +8.5	5.5	42	2515	119
10000	ISA -15	-20	-4	2495	118
	ISA	-5	23	2515	119

NOTE: * Aircraft weight 2550 Lbs., Wheel pants and strut fairings installed ** Subtract 3 KTAS if wheel pants are removed.

ENGINE/CRUISE PERFORMANCE (65%)

Figure 5-20a

REPORT: VB-1611

ISSUED: JULY 12, 1995

Engine / Cruise Performance for Non-ISA OAT* RPM for Constant 75% Power Fuel Flow: Best Economy Mixture, 11.0 GPH

Pressure	Indicated (Outside A	ir Temperature	Engine	True Air
Altitude			•	Speed	Speed
Feet	°C	°C	°F	RPM	Knots **
Sea Level	ISA-15	0	32	2485	119
	ISA	15	59	2515	18
	ISA +10	25	77	2535	
	ISA +20	35	95	2550	
	ISA +30	45	113	2565	124
2000	ISA -15	-4	25	2520	121
'	ISA	11	52	2545	
	ISA +10	21	70	2565	
	ISA +20	31	88	2580	
	ISA +30	41	106	2600	126
3000	ISA -15	-6	21	2535	122
	ISA	9	48	2560	
	ISA +10	19	66	2580	
1	ISA +20	29	84	2595	
	ISA +30	39	102	2615	127
4000	ISA -15	8	18	2550	123
	ISA	7	45	2575	
	ISA +10	17	63	2595	
	ISA +20	27	81	2610	
	ISA +30	37	99	2630	128
5000	ISA -15	-10	14	2565	124
	ISA	5	41	2590	
	ISA +10	15	59	2610	
	ISA +20	25	77	2625	
	ISA +25	30	86	2635	128
6000	ISA -15	-12	10	2580	125
	ISA	3	37	2605	47.7
	ISA +10	13	55	2625	
	ISA +15	18	64	2635	128
7000	ISA -15	-14	6.8	2595	126
	ISA	1	34	2625	
	ISA +7.5	8.5	47	2635	128

NOTE: * Aircraft weight 2550 Lbs., Wheel pants and strut fairings installed ** Subtract 3 KTAS if wheel pants are removed.

ENGINE/CRUISE PERFORMANCE (75%)

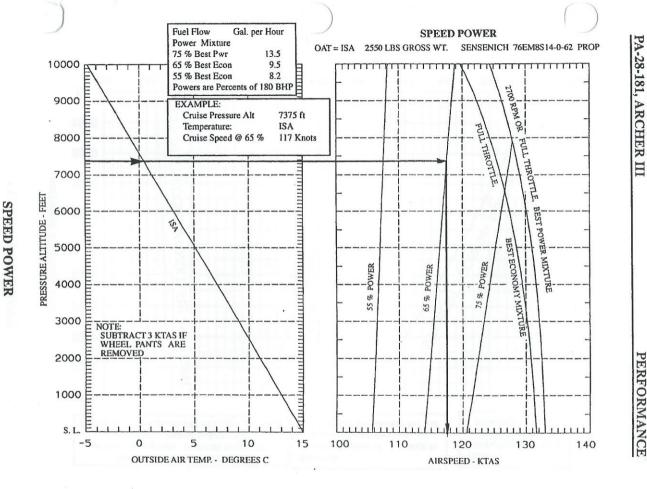
Figure 5-20b

ISSUED: JULY 12, 1995 REVISED: DECEMBER 6, 1999 REPORT: VB-1611

5-23

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Figure 5-21



ISSUED: JULY 1995 RANGE (NO RESERVE)

Figure 5-27

RANGE WITHOUT 45 MIN. RESERVE

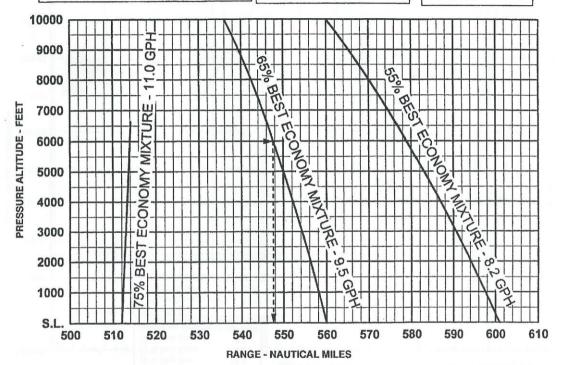
48 GAL USABLE FUEL 2550 LBS GROSS WT. SENSENICH 76EM8S14-0-62 PROP RANGE INCLUDES CLIMB AND DESCENT DISTANCE EXAMPLE:

Cruise Pressure Alt. 6000 Ft. Power 65% Best Economy Range with No Reserves 547 n.m. NOTE:

REDUCE RANGE 3% IF WHEEL PANTS ARE REMOVED

PERFORMANCE SECTION 5

PA-28-181, ARCHER III



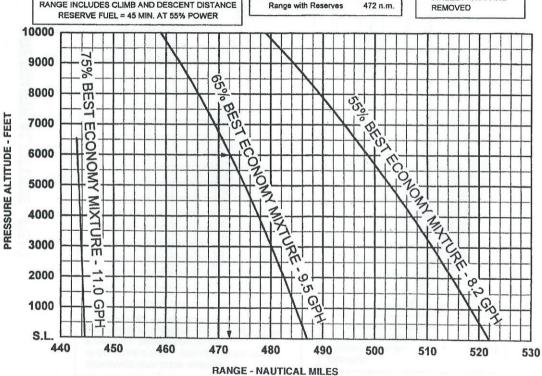
PA-28-181, ARCHER III

RANGE WITH 45 MIN. RESERVE

48 GAL USABLE FUEL 2550 LBS GROSS WT.
SENSENICH 76EMBS14-0-62 PROP
RANGE INCLUDES CLIMB AND DESCENT DISTANCE
RESERVE FUEL = 45 MIN. AT 55% POWER

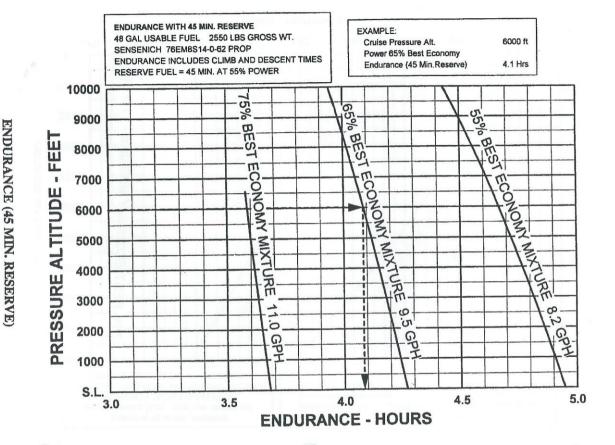
EXAMPLE:
Cruise Pressure Alt. 6000 Ft.
Power 65% Best Economy

NOTE: REDUCE RANGE 3% IF WHEEL PANTS ARE REMOVED



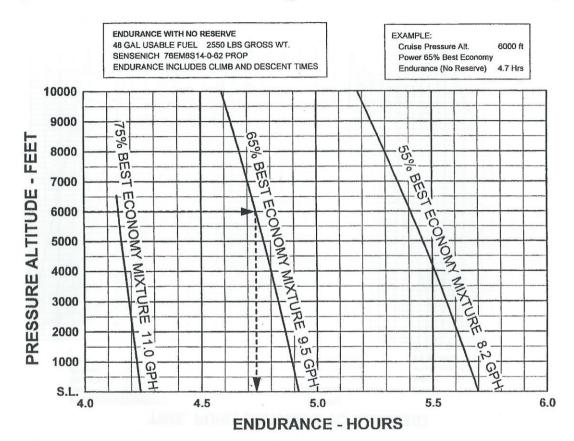
RANGE (45 MIN. RESERVE)
Figure 5-27a

APRIL 3, 1997

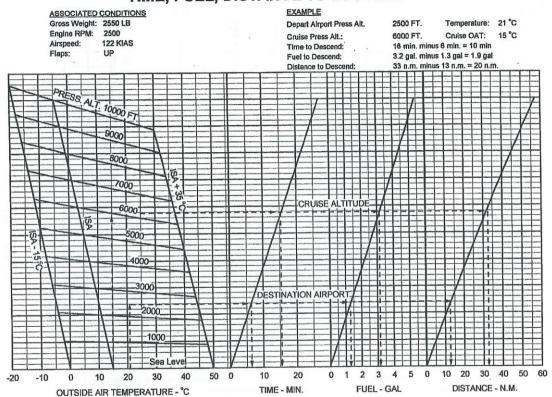


PA-28-181, ARCHER III

ENDURANCE (NO RESERVE) Figure 5-29a



TIME, FUEL, DISTANCE TO DESCEND



TIME, DISTANCE AND FUEL Figure 5-31 TO DESCEND

ISSUED: JULY 12, 1995 REVISED: MARCH 31, 1998

PA-28-181, ARCHER III



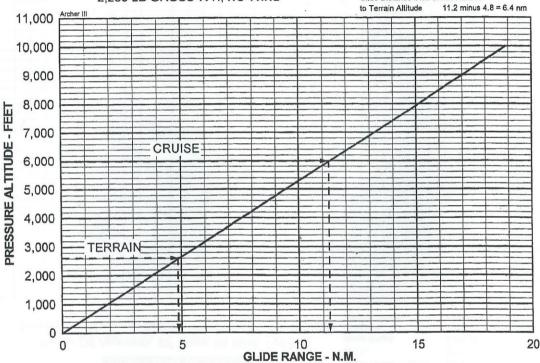
POWER OFF, FLAP UP, 76 KIAS 2,250 LB GROSS WT., NO WIND EXAMPLE:

above sea level

Glide Distance from 6,000 ft Cruise Alt. 11.2 nm Glide Distance from 2,600 ft Terrain

4.8 nm

Glide Distance from Cruise Altitude



GLIDE RANGE Figure 5-33

REPORT: VB-1611

, 1995

LANDING PERFORMANCE

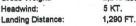
Figure 5-35

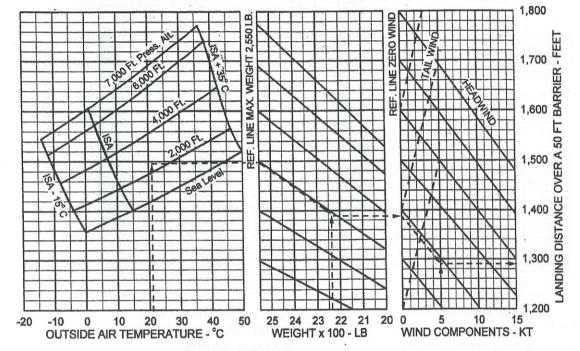
PERFORMANCE SECTION 5

LANDING PERFORMANCE **ASSOCIATED CONDITIONS**

Power Off Approach, 40° Flaps, 66 KIAS, Full Stall Touchdown, Maximum Braking, Paved, Level, Dry Runway

EXAMPLE: Airport Pressure Altitude: 2,500 FT. 21°C O.A.T.: Gross Weight: 2,240 LB. Headwind: 5 KT.





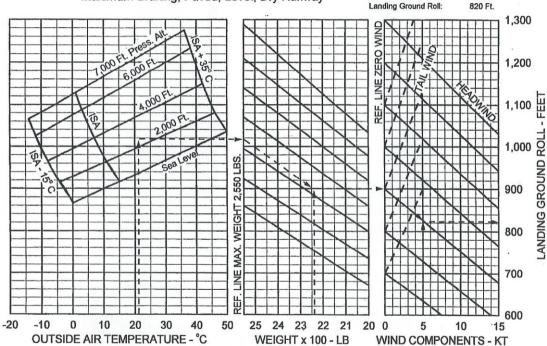
SECTION 5 PERFORMANCE

PA-28-181, ARCHER III

LANDING GROUND ROLL ASSOCIATED CONDITIONS

Power Off Approach, 40° Flaps, Full Stall Touchdown Maximum Braking, Paved, Level, Dry Runway

EXAMPLE:
Alrport Pressure Altitude: 2,500 Ft.
O.A.T.: 21°C
Gross Weight: 2,240 Lb.
Headwind: 5 Kt.



LANDING GROUND ROLL Figure 5-37

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TABLE OF CONTENTS

SECTION 6

WEIGHT AND BALANCE

aph	Page
General	6-1
Airplane Weighing Procedure	6-2
Weight and Balance Data and Record	6-5
Weight and Balance Determination for Flight	6-9
	General

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SECTION 6

WEIGHT AND BALANCE

6.1 GENERAL

ISSUED: JULY 12, 1995

In order to achieve the performance and flying characteristics which are designed into the airplane, it must be flown with the weight and center of gravity (C.G.) position within the approved operating range (envelope). Although the airplane offers flexibility of loading, it cannot be flown with the maximum number of adult passengers, full fuel tanks and maximum baggage. With the flexibility comes responsibility. The pilot must ensure that the airplane is loaded within the loading envelope before he makes a takeoff.

Misloading carries consequences for any aircraft. An overloaded airplane will not take off, climb or cruise as well as a properly loaded one. The heavier the airplane is loaded, the less climb performance it will have.

Center of gravity is a determining factor in flight characteristics. If the C.G. is too far forward in any airplane, it may be difficult to rotate for takeoff or landing. If the C.G. is too far aft, the airplane may rotate prematurely on takeoff or tend to pitch up during climb. Longitudinal stability will be reduced. This can lead to inadvertent stalls and even spins; and spin recovery becomes more difficult as the center of gravity moves aft of the approved limit.

A properly loaded airplane, however, will perform as intended. Before the airplane is licensed, a basic empty weight and C.G. location is computed (basic empty weight consists of the standard empty weight of the airplane plus the optional equipment). Using the basic empty weight and C.G. location, the pilot can easily determine the weight and C.G. position for the loaded airplane by computing the total weight and moment and then determining whether they are within the approved envelope.

REPORT: VB-1611

The basic empty weight and C.G. location are recorded in the Weight and Balance Data Form (Figure 6-5) and the Weight and Balance Record (Figure 6-7). The current values should always be used. Whenever new equipment is added or any modification work is done, the mechanic responsible for the work is required to compute a new basic empty weight and C.G. position and to write these in the Aircraft Log Book and the Weight and Balance Record. The owner should make sure that it is done.

A weight and balance calculation is necessary in determining how much fuel or baggage can be boarded so as to keep within allowable limits. Check calculations prior to adding fuel to insure against improper loading.

The following pages are forms used in weighing an airplane in production and in computing basic empty weight, C.G. position, and useful load. Note that the useful load includes usable fuel, baggage, cargo and passengers. Following this is the method for computing takeoff weight and C.G.

6.3 AIRPLANE WEIGHING PROCEDURE

At the time of licensing, Piper provides each airplane with the basic empty weight and center of gravity location. This data is supplied by Figure 6-5.

The removal or addition of equipment or airplane modifications can affect the basic empty weight and center of gravity. The following is a weighing procedure to determine this basic empty weight and center of gravity location:

(a) Preparation

- (1) Be certain that all items checked in the airplane equipment list are installed in the proper location in the airplane.
- (2) Remove excessive dirt, grease, moisture, foreign items such as rags and tools from the airplane before weighing.
- (3) Defuel airplane. Then open all fuel drains until all remaining fuel is drained. Operate engine on each tank until all undrainable fuel is used and engine stops. Then add the unusable fuel (2.0 gallons total, 1.0 gallons each wing).

ISSUED: JULY 12, 1995

CAUTION

Whenever the fuel system is completely drained and fuel is replenished it will be necessary to run the engine for a minimum of 3 minutes at 1000 RPM on each tank to ensure no air exists in the fuel supply lines.

- (4) Fill with oil to full capacity.
- (5) Place pilot and copilot seats in fourth (4th) notch, aft of forward position. Put flaps in the fully retracted position and all control surfaces in the neutral position. Tow bar should be in the proper location and all entrance and baggage doors closed.
- (6) Weigh the airplane inside a closed building to prevent errors in scale readings due to wind.

(b) Leveling

- (1) With airplane on scales, block main gear oleo pistons in the fully extended position.
- (2) Level airplane (refer to Figure 6-3) deflating nose wheel tire, to center bubble on level.

(c) Weighing - Airplane Basic Empty Weight

(1) With the airplane level and brakes released, record the weight shown on each scale. Deduct the tare, if any, from each reading.

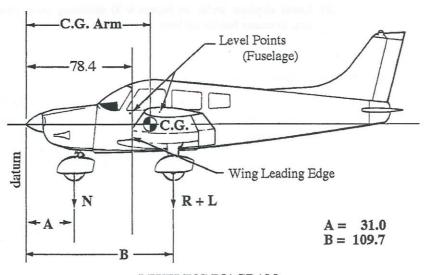
Scale Position and Symbol	Scale Reading	Tare	Net Weight
Nose Wheel (N)			
Right Main Wheel (R)			
Left Main Wheel (L)			
Basic Empty Weight, as Weighed (T)	- 10		

WEIGHING FORM

Figure 6-1

(d) Basic Empty Weight Center of Gravity

(1) The following geometry applies to the PA-28-181 airplane when it is level. Refer to Leveling paragraph 6.3 (b).



LEVELING DIAGRAM

Figure 6-3

(2) The basic empty weight center of gravity (as weighed including optional equipment, full oil and unusable fuel) can be determined by the following formula:

C.G. Arm =
$$N(A) + (R + L)(B)$$
 inches

Where: T = N + R + L

6.5 WEIGHT AND BALANCE DATA AND RECORD

The Basic Empty Weight, Center of Gravity Location and Useful Load listed in Figure 6-5 are for the airplane as licensed at the factory. These figures apply only to the specific airplane serial number and registration number shown.

The basic empty weight of the airplane as licensed at the factory has been entered in the Weight and Balance Record (Figure 6-7). This form is provided to present the current status of the airplane basic empty weight and a complete history of previous modifications. Any change to the permanently installed equipment or modification which affects weight or moment must be entered in the Weight and Balance Record.

ISSUED: JULY 12, 1995

REPORT: VB-1611

MODEL PA-28-181 ARCHER III

Airplane Se	erial Number	2843426
-------------	--------------	---------

Registration Number SE-ILV

Date 02/12/01

AIRPLANE BASIC EMPTY WEIGHT

. 164	C.G. Arm			
Item	Weight x (Lbs)	(Inches Aft = of Datum)	Moment (In-Lbs)	
Actual Standard Empty Weight* Computed	1682.2	87.5548	147284.7	
Optional Equipment	73.0	102.2918	7467.3	
Basic Empty Weight	1755.2	88.1677	154752.0	

^{*}The standard empty weight includes full oil capacity and 2.0 gallons of unusable fuel.

AIRPLANE USEFUL LOAD

(Ramp Weight) - (Basic Empty Weight) = Useful Load

Normal Category (2558 lbs) - (1755.2 lbs) = 802.8 lbs.

Utility Category (2138 lbs) - (1755.2 lbs) = 382.8 lbs.

THIS BASIC EMPTY WEIGHT, C.G. AND USEFUL LOAD ARE FOR THE AIRPLANE AS LICENSED AT THE FACTORY. REFER TO APPROPRIATE AIRCRAFT RECORD WHEN ALTERATIONS HAVE BEEN MADE.

WEIGHT AND BALANCE DATA FORM

Figure 6-5

REPORT: VB-1611

SECTION 6 WEIGHT AND BALANCE

PA-28-181, ARCHER III

WEIGHT AND BALANCE RECORD

Figure 6-7

PA-28-	181	Serial Number 2843426		Registrati	Registration Number SE-ILV			Page Number		
	No.	Description of Article	d (+) /ed (-)	Weight Change		Running Basic Empty Weight				
Date	Item No.	or Modification	Added (+) Removed (-)	Wt. (Lb.)	Arm (In.)	Moment /100	Wt. (Lb.)	Moment /100		
02/12/01		As licensed					1755.2	154752.0		
		As homeol								
y in	1	in Modification) TOD pygonilinniy		200		
		and Edments			amin Class		gowin	13.44-7		

WEIGHT AND BALANCE RECORD (cont)

Figure 6-7 (cont)

PA-28-181 Serial Number			Registration Number		Page Nur	nber		
	lo.	Description of Article	1 (+) ed (-)	v	Veight Cha	ange	Runni Empty	ng Basic Weight
Date Description of Article or Modification	Added (+) Removed (-)	Wt. (Lb.)	Arm (In.)	Moment /100	Wt. (Lb.)	Moment /100		
		As licensed			,			
						,	Laco	
		CCModiffication	1	-5mm1 -867	(1) (1) (1) (1) (1) (1) (1) (1) (1) (1)	- , ·		
			188		gs, salata n			
		Zenej yilimper zazor		Description.			LINE LA	

6.7 WEIGHT AND BALANCE DETERMINATION FOR FLIGHT

- (a) Add the weight of all items to be loaded to the basic empty weight.
- (b) Use the Loading Graph (Figure 6-13) to determine the moment of all items to be carried in the airplane.
- (c) Add the moment of all items to be loaded to the basic empty weight moment.
- (d) Divide the total moment by the total weight to determine the C.G. location.
- (e) By using the figures of item (a) and item (d) (above), locate a point on the C.G. range and weight graph (Figure 6-15). If the point falls within the C.G. envelope, the loading meets the weight and balance requirements.

Arm Aft				
Weight	Datum	Moment		
(Lbs)	(Inches)	(In-Lbs)		
1590.0	87.5	139125		
340.0	80.5	27370		
340.0	118.1	40154		
288.0	95.0	27360		
	142.8			
2558	91.5	234009		
-8	95.0	-760		
2550.0	91.5	233249		
	(Lbs) 1590.0 340.0 340.0 288.0 2558	(Lbs) (Inches) 1590.0 87.5 340.0 80.5 340.0 118.1 288.0 95.0 142.8 2558 91.5 -8 95.0		

The center of gravity (C.G.) of this sample loading problem is at 91.5 inches aft of the datum line. Locate this point (91.5) on the C.G. range and weight graph. Since this point falls within the weight - C.G. envelope, this loading meets the weight and balance requirements.

IT IS THE RESPONSIBILITY OF THE PILOT AND AIRCRAFT OWNER TO ENSURE THAT THE AIRPLANE IS LOADED PROPERLY.

*Utility Category Operation - No baggage or rear passengers allowed.

SAMPLE LOADING PROBLEM (NORMAL CATEGORY)
Figure 6-9

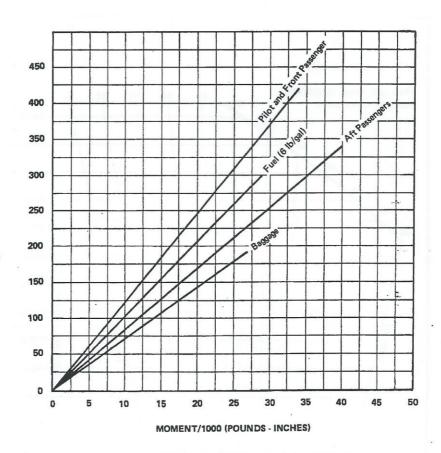
ISSUED: JULY 12, 1995 REPORT: VB-1611

		Arm Aft	
	Weight	Datum	Moment
and the second second by	(Lbs)	(Inches)	(In-Lbs)
Basic Empty Weight			
Pilot and Front Passenger		80.5	
Passengers (Rear Seats)*		118.1	
Fuel (48 Gallon Maximum)		95.0	
Baggage (200 Lbs. Maximum)*		142.8	
Ramp Weight (2558 Lbs. Normal, 2138 Lbs. Utility Maximum)			
Fuel Allowance For Engine Start, Taxi and Run Up	-8	95.0	-760
Takeoff Weight (2550 Lbs. Normal, 2130 Lbs. Utility Maximum)			

Totals must be within approved weight and C.G. limits. It is the responsibility of the airplane owner and the pilot to insure that the airplane is loaded properly. The Basic Empty Weight C.G. is noted on the Weight and Balance Data Form (Figure 6-5). If the airplane has been altered, refer to the Weight and Balance Record for this information.

*Utility Category Operation - No baggage or rear passengers allowed.

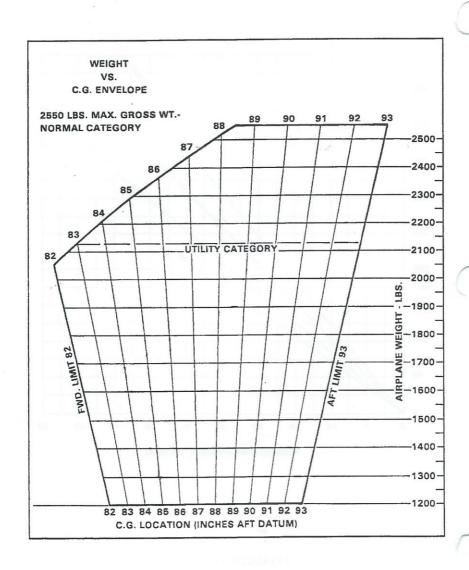
WEIGHT AND BALANCE LOADING FORM Figure 6-11



LOADING GRAPH Figure 6-13

ISSUED: JULY 12, 1995

REPORT: VB-1611



C.G. RANGE AND WEIGHT Figure 6-15

REPORT: VB-1611



PA-28-181, ARCHER III EQUIPMENT LIST S/N 2843415 and UP

EQUIPMENT LIST

SERIAL NO. 2843426

The following is a list of standard and optional equipment for the PA-28-181 Archer III. Optional equipment items marked with an X are installed on the airplane. All items are as described below at the time of licensing by the manufacturer. The New Piper Aircraft, Inc. will not revise this equipment list once the aircraft is licensed. It is the owner's responsibility to retain and amend this equipment list to reflect changes in equipment installed in this airplane. Unless otherwise indicated, the installation certification basis for the equipment included in this list is the aircraft's approved type design.

DATE 02/12/01

REGISTRATION NO. SE-ILV

THE NEW PIPER AIRCRAFT INC.

PA-28-181, ARCHER III

SEKIAL	NO. <u>2043420</u> REGISTRATION NO. <u>SE-IL V</u> DATE <u>92/12/01</u>			
Item No.	Item	Weight (Pounds)	Arm (In.) Aft Datum	Moment (LbsIn.)
	(a) Propeller and Propeller Accessories			
1.	Propeller, Sensenich 76EM8S14-0-62, Piper PS 50077-91 includes Propeller extension and Propeller bolts, Cert. Basis -TC P4EA	44.2	2.8	123.8
3.	Spinner, Piper Drawing 83349-2 a. Bulkhead-Aft b. Dome and Forward Bulkhead	1.5 3.7	3.3 -0.4	5.0 -1.5
	(b) Engine and Engine Accessories, Fuel and Oil Systems			
11.	Engine, Textron Lycoming Model O-360-A4M, Piper Drawing 62941-18 Cert. Basis - TC E286	281.0	20.9	5872.9
13.	Oil Filter, Cert. Basis - TC E286 a. Lycoming 75528, (AC OF5578770) b. Lycoming LW-13743, (Champion CH-48110)	3.3 2.8	35.5 35.5	117.2 99.4
15.	Alternator, 70 Amp, Piper Drawing 99109-13 (Includes belts and hoses) Electro Systems Inc. ES4032 , Lycoming #32C21997	12.0	12.8	153.6
17.	Engine Driven Fuel Pump, Lycoming Drawing 73297, 74082, 75148 or 75246 Cert. Basis-TC E286	1.7	36.3	61.7
19.	Electric Fuel Pump, Facet 476088	1.8	45.0	81.0
21.	Fuel Valve, Piper Drawing 66945 (System Components Corp., SP-2378-B3 or Allen Aircraft Products Inc., 6S122)	0.4	61.9	24.8
23.	Oil Cooler, Niagara N.D.M.20002A, Piper Drawing 85472-8 (wet)	2.6	31.8	82.7
25.	Air Filter, PMA 638873	0.9	27.0	24.3
27.	Starter - 24 volt Lycoming, ESI MHB4016 (Lycoming # LW15572) Cert. Basis TC E286	18.0	13.8	248.4

REVISED: 1/16/01

240-0177 1 of 24



REVISED: 1/16/01

THE NEW PIPER AIRCRAFT, INC

PA-28-181, ARCHER III EQUIPMENT LIST S/N 2843415 and UP

240-0177 2 of 24

Item No.	Item	Weight (Pounds)	Arm (In.) Aft Datum	Moment (LbsIn.
	(b) Engine and Engine Accessories, Fuel and Oil Systems -continued			
29.	Primer System, Piper Drawing 89367-4	1.2	36.0	43.2
	(c) Landing Gear and Brakes			
35.	Main Landing Gear Cleveland Aircraft Products Wheel Assembly (2) 40-86B, Piper PS50035-9 Brake Assembly 30-55 (2), Piper PS50121-1, Cert. Basis-TSO C26a			
	6.00 x 6 Type III 4 Ply Rating Tire, Piper PS50119-11 and Tubes (2), Piper PS50119-101 Cert. Basis - TSO C62d	38.8	109.6	4252.5
37.	Nose Wheel Assembly			
	a. Cleveland Aircraft Products Wheel Assembly 40-56B, Piper PS50035-23, Cert. Basis - TSO C26a	4.3	31.0	133.3
	b. 6.00-6 Type III 4 Ply Rating Tire, Piper PS50119-11 and Tube PS50119-101			
	Cert. Basis -TSO C62d	11.8	31.0	365.8
39.	Hand Brake Master Cylinder, Piper Drawing 65842 (Cleveland Aircraft Products 10-22)	0.6	60.9	36.5
41.	Toe Brake Cylinders			
	a. Cleveland Aircraft Products 10-27	0.7	53.0	37.1
	b. Gar-Kenyon Instruments 17000	0.4	53.0	21.2
43.	Nose Wheel Fairing Installation, Piper Drawing 37896-3	3.8	36.3	137.9
45.	Main Wheel Fairings Installation (2), Piper Drawing 79893-2 LH,-3 RH	17.0	113.6	1931.2
	(d) Electrical Equipment			
51.	Voltage Regulator, Piper Drawing 68804-5	0.4	51.9	20.8
53.	Battery, 28 volt Gill G-243	28.0	171.7	4807.6
55.	Starter Relay-28 v (RBM Controls 70-117224-3), Piper Drawing 26898-5	0.8	180.0	144.0
57.	Stall Warning Devices (Safe Flight C52207), Piper Drawing 85370	0.2	80.2	16.0
59.	Stall Warning Horn (Safe Flight 53534-3), Piper Drawing 35214-9	0.2	58.8	11.8
61.	Radio Master Switch Relay 6041H299, Piper Drawing 39870-9	0.5	59.5	29.8
63.	Instrument Panel Lights Installation, Piper Drawing 85370	0.3	62.8 99.0	18.8 29.7
67.	Cabin Light, Piper Drawing 89875-2 Landing Light/Taxi Light Installation, Piper Drawing 85402-2,-3	0.3	99.0	29.1
69.	(G.E. 4594)(2)	1.8	95.6	172.1
71.	Navigation Lights (Wings)(2) Red/White and Green /White With White		106.6	703.7
70	Strobe, Whelen Power Supply A413HDA-CF-14/28, Piper Drawing 36789-48	6.6 0.4	106.6 100.0	40.0
79.	Heated Pitot Installation, Piper Drawing 35493-20	0.4	100.0	40.0



Item No.	Item	Weight (Pounds)	Arm (In.) Aft Datum	Moment (LbsIn.)
	(d) Electrical Equipment			
81.	Auxiliary Power Receptacle, Piper Drawing 104462-002		.=0.00	155.04
	 Receptacle MS3506-1 Piper Code 484-125, Piper Drawing 44259-001 	0.88	179.36	157.84
	b. Bracket, Harness, Relay and Hardware, Piper Drawing 104462-002	2.46	175.89	432.19
	(e) Instruments			
91.	Truspeed, Airspeed Indicator, Piper PS50049-64T2			
	Cert. Basis -TSO C2b	0.6	61.8	37.1
93.	Altimeter, Piper PS50008-10-2D (United Instruments UI5934-PD-3)			
	Cert. Basis - TSO C10b	0.9	60.9	54.8
95.	Compass, Magnetic, Piper Drawing. 67462-8(Airpath C-2200-L4-1B)			
	Cert. Basis TSO C7c	0.9	64.6	58.1
97.	Tachometer, Piper PS50048-15-1	0.7	61.2	42.8
99.	Oil Press./Cylinder Temp./Oil Temp./ Piper PS50160-7	1.0	62.2	62.2
101.	Fuel Quantity Indicator, Piper PS50161-6	0.5	62.2	31.1
103.	Narco AR-850 Encoder Installation, Piper Drawing 79658-004,			
	Cert. Basis TSO C88(a)			
	 Narco AR 850 Altitude Reporter 03753-0500, Piper PS50040-30-5, 			
	Piper Code 599-012	0.569	51.038	29.041
	 b. Narco AR -850 Altitude Reporter Mounting Tray 53873-0102, 	0.000	51.000	4.002
	Piper Code 599-012	0.080	51.038	4.083 7.39
	c. Altitude Reporter Hose, tube and hardware Piper Drawing 79658-004	0.136	54.47	38.6
105.	Exhaust Gas Temperature Gauge, Piper PS50159-4-1	0.6	64.4	38.0
107.	Vacuum Installation 85434-2			
	a. Dry Air Pump Parker Hannifin AM215CC, Piper Drawing 79399-3,	1.00	22.47	62.46
	Piper Code number 461-754	1.90 0.44	33.47 48.85	63.46 21.47
	b. Vacuum Regulator Parker Hannifin ARM-AM-2H3-19, Piper Code 492-240			
	c. Hoses, Fittings and Hardware, Piper Drawing 85434-2	2.54	49.33	125.07
109.	Auxiliary Vacuum Pump Installation, Piper Drawing 85387-2			
	a. Standby Auxiliary Vacuum Pump, Parker Hannifin 4A2-1,	7.10	43.88	312.41
	Piper Code 566-527	7.12 2.01	47.11	94.83
	b. Hardware, Parker Hannifin Kit 374-10, Piper Code 566-527	2.01	45.06	133.92
	c. Brackets and Hardware, Piper Drawing 85387-2	2.97	59.9	167.7
111.	Attitude Gyro, Piper Drawing. 99002-9, RCA 22-15, Cert. Basis TSO C4c	2.8	59.7	143.3
113.	Directional Gyro, Piper PS50126-5, Cert. Basis TSO C5c	2.4	39.7	143.3
115.	Rate of Climb, Piper Drawing. 99010-5 (United Instruments UI-7000)	0.7	60.9	42.6
115	Cert. Basis - TSO C8b	0.7	61.0	24.4
117.	Alternate Static Source Installation, Piper Drawing. 35493-20	1.2	59.7	71.6
119.	Turn Coordinator, Piper PS50030-3-5, Cert. Basis TSO C3b		62.0	18.6
121.	Engine Hour Meter, Piper Drawing. 87346-6	0.3	02.0	18.0

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PA-28-181, ARCHER III EQUIPMENT LIST S/N 2843415 and UP

Item No.	Item	Weight (Pounds)	Arm (In.) Aft Datum	Moment (LbsIn.)
140.	nem	(r ounds)		(200,)
	(e) Instruments - continued			
123.	Clock, Piper Drawing. 87347-2	0.4	62.4	25.0
125.	Outside Air temperature Gauge (Rochester 1592-70064)			
	Piper Drawing, 87702-7	0.3	72.6	21.8
127.	Ammeter, Digital, EIL Instruments PM-349 (548-885)	0.3	61.1	18.3
	(f) Cabin Interior			
131.	Pilot Adjustable Seat (cloth) with headrest and lumbar support,			
	Piper Drawing. 89026-2, 02585-2 Lumbar Installation	24.46	83.00	2030.18
133.	CoPilot Adjustable Seat (cloth) with headrest and lumbar support,			
	Piper Drawing 89026-3, 02585-3 Lumbar Installation	24.46	82.80	2025.29
135.	Aft Rear Seat (cloth), (right) with headrest, Piper Drawing 89027-3	15.79	123.00	1942.17
137.	Aft Rear Seat (cloth), (left) with headrest, Piper Drawing 89027-2	15.79	123.00	1942.17
139.	Pilot Restraint System, Piper Drawings 76170-7, 79164-011, Cert, Basis TSO - C114/JTSO-C114			
	a. Pilot Inertia Reel, Schroth 5-01-1F0701, Piper Code 564-897,	1.20	110.50	154.39
	Piper Drawing 104211-014	1.29	119.50	134.39
	b. Pilot stiffening Sleeve, Schroth 5-01-1F0701, Piper Code 564-897, Piper Drawing 104211-014	0.29	84.00	24.32
141.	CoPilot Restraint System, Piper Drawings 76170-7, 79164-011,			
	Cert. Basis TSO - C114/JTSO-C114			
	a. CoPilot Inertia Reel, Schroth 5-01-1F5701, Piper Code 564-896,	1.20	110.50	154.87
	Piper Drawing 104211-015	1.30	119.50	134.07
	 b. CoPilot Stiffening Sleeve, Schroth 5-01-1F5701, Piper Code 564-896, Piper Drawing 104211-015 	0.29	84.00	24.19
143.	Aft Seat Restraint System (LH), Piper Drawings 76170-7, 79164-012,			
	Cert. Basis TSO - C114/JTSO-C114			
	a. Aft Seat Inertia Reel, Schroth 5-01-480701, Piper Code 564-895,			
	Piper Drawing 104211-012	1.23	140.30	173.13
	b. Aft Seat Inertia Reel, Schroth 5-01-480701, Piper Code 564-895,	0.06	102.00	21.67
	Piper Drawing 104211-012	0.26	123.00	31.67
145.	Aft Seat Restraint System (RH), Piper Drawings 76170-7, 79164-012,			
	Cert. Basis TSO - C114/JTSO-C114			
	 Aft Seat Inertia Reel, Schroth 5-01-285701, Piper Code 564-893, Piper Drawing 104211-003 	1.23	140.30	173.20
	b. Aft Seat Stiffening Sleeve, Schroth 5-01-285701, Piper Code 564-893,	1.23	110.50	175.25
	Piper Drawing Number 104211-003	0.26	123.00	31.49

REVISED: 1/16/01

240-0177 4 of 24



(g) Miscellaneous 153. Overhead Vent System with Ground Ventilating Blower Installation (Ram Air Installation) Piper Drawing 36983-17 14.2 168.5 23 155. Assist Step, Piper Drawing 65384-0 157. Tow Bar, Piper Drawing 99458-0 158. Locking Fuel Caps (2), Piper Drawing 39824-3 159. Locking Fuel Caps (2), Piper Drawing 82235-2 a. Saber Halon 1211-1301 Fire Extinguisher 600 and Installation Hardware 160. Standard Avionics Equipment 171. GNS 430 GPS/Nav/Com, Single with Stormscope and Skywatch Provisions, Single COM/NaV/GPS, Piper Drawing 104479-2 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214, Cert. Basis - TSO C37d, C38d, C40c, C36e, C34e, C129a b. Cables/harnesses and hardware, Piper Drawing 104479-2 2.00 55.578 11.	Item No.		m (In.) I Datum (Moment LbsIn.)
(g) Miscellaneous 153. Overhead Vent System with Ground Ventilating Blower Installation (Ram Air Installation) Piper Drawing 36983-17 155. Assist Step, Piper Drawing 65384-0 157. Tow Bar, Piper Drawing 99458-0 159. Locking Fuel Caps (2), Piper Drawing 39824-3 161. Fire Extinguisher Installatio, Piper Drawing 82235-2 a. Saber Halon 1211-1301 Fire Extinguisher 600 and Installation Hardware 171. GNS 430 GPS/Nav/Com, Single with Stormscope and Skywatch Provisions, Single COM/NAV/GPS, Piper Drawing 104479-2 a. Garmin GNS430 # Iwith mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214, Cert. Basis - TSO C37d, C38d, C40c, C36e, C34e, C129a b. Cables/harnesses and hardware, Piper Drawing 104479-2 173. Garmin GI-106 VOR /LOC Indicator, Piper Code 602-239, Cert. Basis-TSO C36c,C40a,C34c		erior - continued		
153. Overhead Vent System with Ground Ventilating Blower Installation (Ram Air Installation) Piper Drawing 36983-17 14.2 168.5 23 155. Assist Step, Piper Drawing 65384-0 1.8 156.0 2 157. Tow Bar, Piper Drawing 99458-0 1.3 156.0 2 159. Locking Fuel Caps (2), Piper Drawing 39824-3 161. Fire Extinguisher Installatio, Piper Drawing 82235-2 a. Saber Halon 1211-1301 Fire Extinguisher 600 and Installation Hardware 171. GNS 430 GPS/Nav/Com, Single with Stormscope and Skywatch Provisions, Single COM/NAV/GPS, Piper Drawing 104479-2 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214, Cert. Basis - TSO C37d, C38d, C40c, C36e, C34e, C129a b. Cables/harnesses and hardware, Piper Drawing 104479-2 173. Garmin GI-106 VOR /LOC Indicator, Piper Code 602-239, Cert. Basis-TSO C36c,C40a,C34c 175. Garmin GTX-327, Transponder Installation with AR-850 and GPS,	149.	os, Piper Drawings 66804-0 & 66805-0 1.3	142.8	185.6
(Ram Air Installation) Piper Drawing 36983-17 14.2 168.5 22 155. Assist Step, Piper Drawing 65384-0 1.8 156.0 2 157. Tow Bar, Piper Drawing 99458-0 1.3 156.0 2 159. Locking Fuel Caps (2), Piper Drawing 39824-3 161. Fire Extinguisher Installatio, Piper Drawing 82235-2 a. Saber Halon 1211-1301 Fire Extinguisher 600 and Installation Hardware 2.1 95.8 2 (h) Standard Avionics Equipment 171. GNS 430 GPS/Nav/Com, Single with Stormscope and Skywatch Provisions, Single COM/NaV/GPS, Piper Drawing 104479-2 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214, Cert. Basis - TSO C37d, C38d, C40c, C36e, C34e, C129a b. Cables/harnesses and hardware, Piper Drawing 104479-2 173. Garmin GI-106 VOR /LOC Indicator, Piper Code 602-239, Cert. Basis-TSO C36e, C40a, C34e 175. Garmin GTX-327, Transponder Installation with AR-850 and GPS,		eous		
157. Tow Bar, Piper Drawing 99458-0 159. Locking Fuel Caps (2), Piper Drawing 39824-3 161. Fire Extinguisher Installatio, Piper Drawing 82235-2 a. Saber Halon 1211-1301 Fire Extinguisher 600 and Installation Hardware 2.1 95.8 2 (h) Standard Avionics Equipment 171. GNS 430 GPS/Nav/Com, Single with Stormscope and Skywatch Provisions, Single COM/NAV/GPS, Piper Drawing 104479-2 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214, Cert. Basis - TSO C37d, C38d, C40c, C36e, C34e, C129a b. Cables/harnesses and hardware, Piper Drawing 104479-2 173. Garmin GI-106 VOR /LOC Indicator, Piper Code 602-239, Cert. Basis-TSO C36c,C40a,C34c 175. Garmin GTX-327, Transponder Installation with AR-850 and GPS,			168.5	2392.7
159. Locking Fuel Caps (2), Piper Drawing 39824-3 161. Fire Extinguisher Installatio, Piper Drawing 82235-2 a. Saber Halon 1211-1301 Fire Extinguisher 600 and Installation Hardware 2.1 95.8 2 (h) Standard Avionics Equipment 171. GNS 430 GPS/Nav/Com, Single with Stormscope and Skywatch Provisions, Single COM/NAV/GPS, Piper Drawing 104479-2 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214, Cert. Basis - TSO C37d, C38d, C40c, C36e, C34e, C129a b. Cables/harnesses and hardware, Piper Drawing 104479-2 173. Garmin GI-106 VOR /LOC Indicator, Piper Code 602-239, Cert. Basis-TSO C36c,C40a,C34c 175. Garmin GTX-327, Transponder Installation with AR-850 and GPS,	155.	iper Drawing 65384-0 1.8	156.0	280.8
161. Fire Extinguisher Installatio, Piper Drawing 82235-2 a. Saber Halon 1211-1301 Fire Extinguisher 600 and Installation Hardware 2.1 95.8 2 (h) Standard Avionics Equipment 171. GNS 430 GPS/Nav/Com, Single with Stormscope and Skywatch Provisions, Single COM/NAV/GPS, Piper Drawing 104479-2 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214, Cert. Basis - TSO C37d, C38d, C40c, C36e, C34e, C129a b. Cables/harnesses and hardware, Piper Drawing 104479-2 173. Garmin GI-106 VOR /LOC Indicator, Piper Code 602-239, Cert. Basis-TSO C36c,C40a,C34c 175. Garmin GTX-327, Transponder Installation with AR-850 and GPS,	157.	er Drawing 99458-0 1.3	156.0	202.8
a. Saber Halon 1211-1301 Fire Extinguisher 600 and Installation Hardware 2.1 95.8 2 (h) Standard Avionics Equipment 171. GNS 430 GPS/Nav/Com, Single with Stormscope and Skywatch Provisions, Single COM/NAV/GPS, Piper Drawing 104479-2 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214, Cert. Basis - TSO C37d, C38d, C40c, C36e, C34e, C129a b. Cables/harnesses and hardware, Piper Drawing 104479-2 173. Garmin GI-106 VOR /LOC Indicator, Piper Code 602-239, Cert. Basis-TSO C36e, C40a, C34e 175. Garmin GTX-327, Transponder Installation with AR-850 and GPS,	159.	Caps (2), Piper Drawing 39824-3 0.85	3.85	80.10
171. GNS 430 GPS/Nav/Com, Single with Stormscope and Skywatch Provisions, Single COM/NAV/GPS, Piper Drawing 104479-2 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214, Cert. Basis - TSO C37d, C38d, C40c, C36e, C34e, C129a b. Cables/harnesses and hardware, Piper Drawing 104479-2 2.00 55.578 11 173. Garmin GI-106 VOR /LOC Indicator, Piper Code 602-239, Cert. Basis-TSO C36c,C40a,C34c 175. Garmin GTX-327, Transponder Installation with AR-850 and GPS,			95.8	201.2
Single COM/NAV/GPS, Piper Drawing 104479-2 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214, Cert. Basis - TSO C37d, C38d, C40c, C36e, C34e, C129a b. Cables/harnesses and hardware, Piper Drawing 104479-2 173. Garmin GI-106 VOR /LOC Indicator, Piper Code 602-239, Cert. Basis-TSO C36c,C40a,C34c 175. Garmin GTX-327, Transponder Installation with AR-850 and GPS,		Avionics Equipment		
Cert. Basis-TSO C36c,C40a,C34c 175. Garmin GTX-327, Transponder Installation with AR-850 and GPS,		NAV/GPS, Piper Drawing 104479-2 NS430 #1 with mount, connectors and data card, 040-40-1, Piper Code 601-214, - TSO C37d, C38d, C40c, C36e, C34e, C129a 6.48		76.73424 111.22
		o rottizo o martaron, a par a a a a a a	0.228	61.43
a. Garmin GTX327 Transponder Unit 011-00490-10, Piper PS50040-12-12,		3 104438-002, Cert. Basis - TSO C74C X327 Transponder Unit 011-00490-10, Piper PS50040-12-12,	59.24	171.79
b. Garmin Connector/Rack Kit 011-00338-00, Piper PS50040-12-12, Piper Code 651-938 0.64 59.24 3 c. Garmin Transponder Antenna 010-10160-00, Piper Code 683-724 0.21 55.11 1		nnector/Rack Kit 011-00338-00, Piper PS50040-12-12, .651-938 0.64 ansponder Antenna 010-10160-00, Piper Code 683-724 0.21	59.24 55.11	37.91 11.57 58.04



Item No.	Item	Weight (Pounds)	Arm (In.) Aft Datum	Moment (LbsIn.)
	(h) Standard Avionics Equipment - continued			
177.	Garmin Audio Amp/Marker Installation, Piper Drawing 101193-003,			
1//.	Cert. Basis- TSO C35d and C50b			
	a. Garmin GMA 340 Audio Selector Panel, Piper PS50040-15-25,			
	Piper Code 601-210	1.57	59.84	93.95
	1. Garmin 011-00401-10 GMA Audio Panel Marker/Receiver	0.17	59.84	10.17
	2. Garmin 011-00403-00 Connector/Rack Kit	2.19	65.89	144.10
	b. Harnesses, Brackets and Hardware, Piper Drawing 101193-003	2.19	03.09	144.10
179.				
	Cert. Basis TSO C91a			
	a. Artex ELT 110-4 Kit, Piper Code 599-515	1.26	226.75	1008.56
	1. Artex Transmitter 110-4 Unit/Bracket, Piper Code 599-515	4.26 0.09	236.75 208.88	18.80
	2. Antenna Artex 110-324, Piper Code 599-515	0.09	222.82	31.20
	3. Coax Cable Artex 611-6013, Piper Code 599-515			4.37
	4. Remote Switch Artex 645-6196, Piper Code 599-515	0.07	62.44	
	b. Harness and Hardware, Piper Drawing 06327-009	0.89	190.40	168.60
181.	Antennas			
	a. NAV Receiving AV12-PPR Antenna, Piper Code 451-802	0.40	264.9	105.96
	1. Nav Antenna Cable Assembly and Hardware, Piper Drawing 101311 002	0.862	169.431	146.02
	b. VHF Comm Comant CI-121 Antenna, Piper PS50040-18-2, Piper Code 596-664	0.543	158.500	85.99
	Comm Antenna Cable Assembly and Hardware, Piper Drawing 101311-002	0.802	99.892	80.11
	c. Comant CI-507 Antenna Coupler, Piper Code 557-704	0.163	54.938	8.95
	1. Antenna Coupler Hardware, Piper Drawing 101311-002	0.007	58.938	0.38
	d. Installation Hardware, Piper Drawing 101311-002	0.07	66.35	4.58
	e. GPS Antenna (Single) Installation, Piper Drawing 101273-2			
	1. Garmin 010-10040-01 Antenna Kit 683-721			
	a. Garmin 011-00134-00 GA56 Antenna, Piper Code 683-721	0.242	96.26	23.29
	b. Garmin 115-00031-00 Backing Plate, Piper Code 683-721	0.088	96.26	8.47
	2. Coax Cable, Piper Drawing 101265-005	0.523	77.98	40.78
183.	Marker Beacon Antenna Installation, Piper Drawing 39737-004			
105.	a. Marker Beacon Antenna Comant CI-102, Piper PS50040-15-10,			
	Piper Code 597-893	0.45	217.17	98.60
	b. Marker Beacon Cable and Hardware, Piper Drawing 39737-004	1.08	122.559	132.50
185.				
	a. Troll Avionics Icebox FN-200 PSV 4000020 Blower, Piper Code 460-110	1.07	56.54	60.44
	b. Cable, Bracket and Hardware, Piper Drawing 101318-002	0.57	54.685	31.00



REVISED: 1/16/01

THE NEW PIPER AIRCRAFT, INC

PA-28-181, ARCHER III EQUIPMENT LIST S/N 2843415 and UP

240-0177

7 of 24

Item No.	Item	Mark if Option Installed	Weight (Pounds)	Arm (In.) Aft Datum	Moment (LbsIn.)
	(h) Standard Avionics Equipment - continued				
187.	Cabin Speaker Installation, Piper Drawing 84289-2 a. Speaker Assembly, Piper Drawing 85430-002 1. Speakers (2), Oaktron 4EU2742, Piper Code 487-192 2. Harness and Hardware, Piper Drawing 85430-002 b. Brackets and Hardware, Piper Drawing 84289-2		1.33 0.03 0.171	88.18 88.18 88.18	117.01 2.910 15.11
189.	Pilot's Microphone a. Telex 100T/NH Microphone 62800-001, Piper Code 474-657 b. Telex Holder 64022-000 and Hardware, Piper Drawing 79036-024		0.26 0.03	74.13 74.13	19.35 2.34
191.	Pilot's Headset a. Telex 5161A Airman 760 Headset, Piper Code 692-205		0.20	80.5	16.34
193.	Pilot Mike Switch Assembly, Piper Drawing 101117-005		0.093	68.938	6.399
195.	CoPilot Mike Switch Assembly, Piper Drawing 101117-006		0.093	68.938	6.399
197.	Static wick installation Piper Drawing 69667-8 a.) Static Wicks (6)-Wing b.)Static Wicks (3)-Empennage		0.2 0.1	136.3 274.1	27.3 27.4
HE	END OF STANDARD EQUIPMENT		1 10		
	(i) Optional Electrical Equipment				
201.	Tail Light Assembly, Piper Drawing 63886-4		0.4	281.0	112.4
202.	Tail Strobe (Low Profile) Installation, Piper Drawing 104296-003 a. Strobe Light, Whelen 01-0790111-02, Piper Code 683-504 b. Cables/Harnesses and Hardware, Piper Drawing 104296-003 Tail Strobe Installation Total Weight		0.240 1.29 1.53	243.790 195.03 202.7	58.630 251.26 309.89



PA-28-181, ARCHER III EQUIPMENT LIST S/N 2843415 and UP

Item No.	Item	Mark if Option Installed	Weight (Pounds)	Arm (In.) Aft Datum	Moment (LbsIn.)
	(j) Auto Pilots (Optional Equipment)				
203.	S-TEC System 55X Autopilot, Piper Drawing 104580-2 a. S-TEC Turn Coordinator 6405-28L, Piper Code 694-102		1.80	60.40	108.72
	b. Turn Coordinator Hardware, Piper Drawing 104580-002		0.01	62.99	0.89
	c. S-TEC Programmer /Computer 01192-1-48TP, Piper Code 651-921		2.70	58.20	157.14
	d. S-TEC Programmer Computer Bracket and Hardware Kit 901401-1 and Piper Drawing 104580-002		0.39	58.26	22.62
	e. S-TEC Transducer 0111, Piper Code 651-911		0.20	192.40	38.48
	f. S-TEC Transducer Installation Kit 90401-2, Piper Code 651-911		0.32	192.40	61.38
	g. Transducer Hardware, Piper Drawing 104580-002		0.10	191.00	18.81
	h. S-TEC Roll Servo 0106-R9, Piper Code 651-912		2.90	125.70	364.53
	i. S-TEC Roll Servo Brackets and Cable 90401-3		0.72	125.70	90.85
	k. Roll Servo Hardware, Piper Drawing 104580-002		0.09	122.23	11.04
	1. S-TEC Pitch Servo 0108-P4, Piper Code 651-913		2.90	120.90	350.61
	m. S-TEC Pitch Servo Bracket 60200		0.40	120.90	48.66
	n. Pitch Servo Hardware, Piper Drawing 104580-002		0.37	119.87	43.81
	o. S-TEC Trim Servo 0106-11-T6		2.90	113.90	330.31
	p. S-TEC Trim Servo Brackets and Hardware 90401-5		0.65	113.90	74.59
	q. Trim Servo Hardware, Piper Drawing 104580-2		0.07	111.49	7.29
	r. S-TEC Monitor/Sonalert, Sonalert 6542		0.10	57.50	5.75
	u. S-TEC Potentiometer Installation Kit 90401-6, Piper Code 651-951		0.11	123.78	14.17
	v. Potentiometer Hardware, Piper Drawing 104580-2		0.04	123.78	5.23
	w. S-TEC Switch Installation Kit 90401-7, Piper Code 651-916		0.07	63.04	4.11
	x. S-TEC Directional Gyro 6406-28L, Piper Code 694-103		3.40	59.00	200.60
	y. S-TEC Autopilot Cables 901401-009		4.737	80.97	383.53
	z. Installation Hardware, Piper Drawing 104580-002		0.33	61.20	19.94
	Removed Standard Directional Gyro, Piper PS50126-5 Removed Standard Turn Coordinator, Piper PS50030-3-5 S-TEC Autopilot Installation Weight (Delta)		-2.40 -1.20 22.23	59.7 59.7 97.99	-143.30 -71.60 2178.60

REVISED: 1/16/01

240-0177 8 of 24



No. Item Option (Pounds) Aft Datum (LbsIn: Installed (Pounds) Aft Datum (LbsIn: Installed (Pounds) (Pounds) (Pounds) Aft Datum (LbsIn: Installed (Pounds) (Pou	Item		Mark if	Weight	Arm (In.)	Moment
(j) Auto Pilots (Optional Equipment) - continued 205. S-TEC Autopilot Installation with Heading System (HSI), Piper Drawing 104580-003 a. S-TEC System 55X Autopilot, Piper Drawing 104580-2 (Delta Weight)	No.	Item		(Pounds)	Aft Datum	(LbsIn.)
205. S-TEC Autopilot Installation with Heading System (HSI), Piper Drawing 104580-003 a. S-TEC System 55X Autopilot, Piper Drawing 104580-2 (Delta Weight)			Installed			
Piper Drawing 104580-003 a. S-TEC System 55X Autopilot, Piper Drawing 104580-2 (Delta Weight)		(j) Auto Pilots (Optional Equipment) - continued				
a. S-TEC System 55X Autopilot, Piper Drawing 104580-2 (Delta Weight)	205.					
c. Compass ST-180/ HSI Installation, Piper Drawing 101259-005 1. S-TEC 6443-PA Horizontal Situation Indicator 2. S-TEC 6444 Remote Gyro 3. A0 186.58 634.39 3. S-TEC 01171-P Slaving Panel 0.10 60.94 6.09 4. S-TEC 6446 Flux Sensor 3. S-TEC 90480-1 Hardware Installation Kit 6. Harnesses, Brackets and Hardware, Piper Drawing 101259-005 d. Remove S-TEC Directional Gyro 6406-28L, Piper Code 694-103 S-TEC Autopilot Installation with Heading System (HSI) weight 3. S-TEC Autopilot Installation with Heading System (HSI) weight 3. S-TEC System 55X Autopilot, Piper Drawing 104580-2 (Delta Weight) S-TEC Flight Director Steering Horizon 6413-28L c. S-TEC Flight Director Steering Horizon 6413-28L c. S-TEC Flight Director Aunuciator 01188-IPX d. S-TEC Flight Director Placards and Trim Kit 901481-1 g. Compass ST-180/ HSI Installation, Piper Drawing 101259-005 1. S-TEC 6443-PA Horizontal Situation Indicator 2. S-TEC 6448-PA Horizontal Situation Indicator 3. A0 59.00 4. S-TEC Flight Director Aunuciator 01188-IPX 3. A0 59.00 5. S-TEC Flight Director Placards and Trim Kit 901481-1 g. Compass ST-180/ HSI Installation, Piper Drawing 101259-005 1. S-TEC 6443-PA Horizontal Situation Indicator 3. A0 58.00 3. A0 186.58 3. A0 58.90 3. S-TEC O1171-P Slaving Panel 4. S-TEC 90480-1 Hardware Installation Kit A S-TEC 90480-1 Hardware Installation Kit A S-TEC 4046-Flux Sensor 3. A0 59.00 3. A0 58.90 3. A0 58.90 3. A110.219 3. S-TEC Autopilot Installation, Piper Drawing 101259-005 3. A0 58.90 4. S-TEC 6446-Flux Sensor 3. A0 58.90 3.		a. S-TEC System 55X Autopilot, Piper Drawing 104580-2 (Delta Weight)				
1. S-TEC 6443-PA Horizontal Situation Indicator 2. S-TEC 6444 Remote Gyro 3. 40 186.58 634.39 3. S-TEC 01171-P Slaving Panel 0.10 60.94 6.09 4. S-TEC 6466 Flux Sensor 5. S-TEC 90480-1 Hardware Installation Kit 6. Harnesses, Brackets and Hardware, Piper Drawing 101259-005 6. Harnesses, Brackets and Hardware, Piper Drawing 101316-002 2. S-TEC Autopilot Installation with Heading System (HSI) and Flight Director, Piper Drawing 104580-004 a. S-TEC System 55X Autopilot, Piper Drawing 10316-002 C. S-TEC Autopilot Cable Weight 90401-11, Delta from standard d. S-TEC Flight Director Steering Horizon 6413-28L e. S-TEC Flight Director Steering Horizon 6413-28L e. S-TEC Flight Director Placards and Trim Kit 901481-1 g. Compass ST-180/ HSI Installation, Piper Drawing 101259-005 1. S-TEC 6443-PA Horizontal Situation Indicator 2. S-TEC 6444 Remote Gyro 3. 40 186.58 634.39 3. S-TEC 1171-P Slawing Panel 4. S-TEC 90480-1 Hardware Installation Kit 6. Harnesses, Brackets and Hardware, Piper Drawing 101259-005 a. S-TEC 90480-1 Hardware Installation Kit 6. Harnesses, Brackets and Hardware, Piper Drawing 101259-005 a. S-TEC Mutopilot Installation Kit 6. Harnesses, Brackets and Hardware, Piper Drawing 101259-005 a. S-TEC 90480-1 Hardware Installation Kit 6. Harnesses, Brackets and Hardware, Piper Drawing 101259-005 Altitude Selector/Alerter Installation, Piper Drawing 104580-005 a. S-TEC Altitude Selector/Alerter 10279-PX, Piper Code 662-158 b. S-TEC Altitude Selector/Alerter Cable and Hardware 901482 90. 90 61.20 55.08 5. S-TEC Altitude Selector/Alerter Cable and Hardware 901482			Ш	0.040	60.39	2.416
2. S-TEC 6444 Remote Gyro 3. S-TEC 01171-P Slaving Panel 4. S-TEC 6446 Flux Sensor 5. S-TEC 90480-1 Hardware Installation Kit 6. Harnesses, Brackets and Hardware, Piper Drawing 101259-005 d. Remove S-TEC Directional Gyro 6406-28L, Piper Code 694-103 S-TEC Autopilot Installation with Heading System (HSI) Weight 207. S-TEC Autopilot Installation with Heading System (HSI) and Flight Director, Piper Drawing 104580-004 a. S-TEC System 55X Autopilot, Piper Drawing 101316-002 b. Switch Assembly with Post Light, Piper Drawing 101316-002 c. S-TEC Flight Director Steering Horizon 6413-28L c. S-TEC Flight Director Steering Horizon 6413-28L c. S-TEC Flight Director Placards and Trim Kit 901481-1 g. Compass ST-180/ HSI Installation, Piper Drawing 101259-005 1. S-TEC 6443-PA Horizontal Situation Indicator 2. S-TEC 6444 Remote Gyro 3. S-TEC 6444 Remote Gyro 3. S-TEC G444 Remote Gyro 3. S-TEC G444 Remote Gyro 4. S-TEC G446 Flux Sensor 5. S-TEC G446 Flux Sensor 5. S-TEC G446 Flux Sensor 5. S-TEC G466-28L, Piper Drawing 101259-005 1. Removed Standard Attitude Gyro 99002-9, RCA 22-15 S-TEC Autopilot Installation with Heading System (HSI) and Flight Director Weight 3. G63 58.94 3. G740 59.00 3. S-TEC Autopilot G50-004 3. S-TEC Autopilot G60-28L, Piper Drawing 101259-005 5. S-TEC G444 Remote Gyro 5. S-TEC G466-28L, Piper Drawing 101259-005 6. Harnesses, Brackets and Hardware, Piper Drawing 101259-005 7. S-TEC Autopilot Installation Kit 8. G63 58.94 3. G63 58.94				2.00	57.10	165.05
3. S-TEC 01171-P Slaving Panel 4. S-TEC 6446 Flux Sensor 5. S-TEC 90480-1 Hardware Installation Kit 6. Harnesses, Brackets and Hardware, Piper Drawing 101259-005 d. Remove S-TEC Directional Gyro 6406-28L, Piper Code 694-103 S-TEC Autopilot Installation with Heading System (HSI) Weight 207. S-TEC Autopilot Installation with Heading System (HSI) and Flight Director, Piper Drawing 104580-004 a. S-TEC System 55X Autopilot, Piper Drawing 104580 - 2 (Delta Weight) b. Switch Assembly with Post Light, Piper Drawing 101316-002 c. S-TEC Autopilot Cable Weight 90401-11, Delta from standard d. S-TEC Flight Director Steering Horizon 6413-28L e. S-TEC Flight Director Annunciator 01188-1PX d. S-TEC Flight Director Annunciator 01188-1PX g. Compass ST-180/ HSI Installation, Piper Drawing 101259-005 1. S-TEC 6443-PA Horizontal Situation Indicator 2. S-TEC 6444 Remote Gyro 3. S-TEC 6446 Flux Sensor 5. S-TEC 6446 Flux Sensor 5. S-TEC O1171-P Slaving Panel 4. S-TEC 6466 Flux Sensor 5. S-TEC O440pilot Installation Kit 6. Harnesses, Brackets and Hardware, Piper Drawing 101259-005 1. Removed Standard Attitude Gyro 99002-9, RCA 22-15 S-TEC Autopilot Installation with Heading System (HSI) and Flight Director Weight 32.57 110.219 3589.55 209. Altitude Selector/Alerter Installation, Piper Drawing 104580-005 a. S-TEC Altitude Selector/Alerter Cable and Hardware 901482 200. 60.94 60.95 60.			H			
4. S-TEC 6446 Flux Sensor 5. S-TEC 90480-1 Hardware Installation Kit 6. Harnesses, Brackets and Hardware, Piper Drawing 101259-005 d. Remove S-TEC Directional Gyro 6406-28L, Piper Code 694-103 S-TEC Autopilot Installation with Heading System (HSI) Weight 207. S-TEC Autopilot Installation with Heading System (HSI) and Flight Director, Piper Drawing 104580-004 a. S-TEC System 55X Autopilot, Piper Drawing 104580-2 (Delta Weight) b. Switch Assembly with Post Light, Piper Drawing 101316-002 c. S-TEC Autopilot Cable Weight 90401-11, Delta from standard d. S-TEC Flight Director Steering Horizon 6413-28L e. S-TEC Flight Director Annunciator 01188-1PX f. S-TEC Flight Director Annunciator 01188-1PX g. Compass ST-180/ HSI Installation, Piper Drawing 101259-005 1. S-TEC 6443-PA Horizontal Situation Indicator 2. S-TEC 6444 Remote Gyro 3. S-TEC 6444 Remote Gyro 3. S-TEC 6446 Flux Sensor 5. S-TEC 90480-1 Hardware Installation Kit 6. Harnesses, Brackets and Hardware, Piper Drawing 101259-005 h. Remove S-TEC Directional Gyro 6406-28L, Piper Code 694-103 a. S-TEC Autopilot Installation with Heading System (HSI) and Flight Director Weight 209. Altitude Selector/Alerter Installation, Piper Drawing 104580-005 a. S-TEC Altitude Selector/Alerter O279-PX, Piper Code 652-158 b. S-TEC Altitude Selector/Alerter Cable and Hardware 901482 203. 40. 46.287 21.12						
5. S-TEC 90480-1 Hardware Installation Kit 6. Harnesses, Brackets and Hardware, Piper Drawing 101259-005 d. Remove S-TEC Directional Gyro 6406-28L, Piper Code 694-103 S-TEC Autopilot Installation with Heading System (HSI) Weight 31.58 111.573 3523.36 207. S-TEC Autopilot Installation with Heading System (HSI) and Flight Director, Piper Drawing 104580-004 a. S-TEC System 55X Autopilot, Piper Drawing 104580-2 (Delta Weight) b. Switch Assembly with Post Light, Piper Drawing 101316-002 c. S-TEC Autopilot Cable Weight 90401-11, Delta from standard d. S-TEC Flight Director Steering Horizon 6413-28L d. S-TEC Flight Director Steering Horizon 6413-28L d. S-TEC Flight Director Placards and Trim Kit 901481-1 g. Compass ST-180/ HSI Installation, Piper Drawing 101259-005 1. S-TEC 6443-PA Horizontal Situation Indicator 2. S-TEC 6444 Remote Gyro 3. S-TEC 6446 Flux Sensor 5. S-TEC 90480-1 Hardware Installation Kit 6. Harnesses, Brackets and Hardware, Piper Drawing 101259-005 h. Remove S-TEC Directional Gyro 6406-28L, Piper Code 694-103 i. Removed Standard Attitude Gyro 99002-9, RCA 22-15 S-TEC Autopilot Installation, Piper Drawing 104580-005 a. S-TEC Altitude Selector/Alerter Installation, Piper Drawing 104580-005 a. S-TEC Altitude Selector/Alerter Cable and Hardware 901482 3. S-TEC Altitude Selector/Alerter Cable and Hardware 901482 3. S-TEC Altitude Selector/Alerter Cable and Hardware 901482 3. S-TEC Altitude Selector/Alerter Cable and Hardware 901482						
6. Harnesses, Brackets and Hardware, Piper Drawing 101259-005 d. Remove S-TEC Directional Gyro 6406-28L, Piper Code 694-103 S-TEC Autopilot Installation with Heading System (HSI) Weight 207. S-TEC Autopilot Installation with Heading System (HSI) and Flight Director, Piper Drawing 104580-004 a. S-TEC System 55X Autopilot, Piper Drawing 104580-2 (Delta Weight) b. Switch Assembly with Post Light, Piper Drawing 101316-002 c. S-TEC Autopilot Cable Weight 90401-11, Delta from standard d. S-TEC Flight Director Steering Horizon 6413-28L e. S-TEC Flight Director Steering Horizon 6413-28L e. S-TEC Flight Director Placards and Trim Kit 901481-1 g. Compass ST-180/ HSI Installation, Piper Drawing 101259-005 1. S-TEC 6444-PA Horizontal Situation Indicator 2. S-TEC 6445-PA Horizontal Situation Indicator 3. S-TEC 6446-Plux Sensor 5. S-TEC 6446-Plux Sensor 5. S-TEC 90480-1 Hardware Installation Kit 6. Harnesses, Brackets and Hardware, Piper Drawing 101259-005 1. Removed Standard Attitude Gyro 99002-9, RCA 22-15 S-TEC Autopilot Installation, Piper Drawing 104580-005 a. S-TEC Altitude Selector/Alerter Cable and Hardware 901482 2. 0.90 61.20 60.94 60.90 61.20 5.08 6.287 6.2124 6.287 6.2124 6.287 6.280 6.287 6.290 6.200 6						
d. Remove S-TEC Directional Gyro 6406-28L, Piper Code 694-103 S-TEC Autopilot Installation with Heading System (HSI) Weight 207. S-TEC Autopilot Installation with Heading System (HSI) and Flight Director, Piper Drawing 104580-004 a. S-TEC System 55X Autopilot, Piper Drawing 104580-2 (Delta Weight) b. Switch Assembly with Post Light, Piper Drawing 101316-002 c. S-TEC Autopilot Cable Weight 90401-11, Delta from standard c. S-TEC Flight Director Steering Horizon 6413-28L d. S-TEC Flight Director Steering Horizon 6413-28L e. S-TEC Flight Director Annunciator 01188-1PX f. S-TEC Flight Director Placards and Trim Kit 901481-1 g. Compass ST-180/ HSI Installation, Piper Drawing 101259-005 1. S-TEC 6443-PA Horizontal Situation Indicator 2. S-TEC 6444 Remote Gyro 3. S-TEC 6444 Remote Gyro 3. S-TEC 6446 Flux Sensor 3. S-TEC 6446 Flux Sensor 3. S-TEC 90480-1 Hardware Installation Kit 6. Harnesses, Brackets and Hardware, Piper Drawing 101259-005 b. Remove S-TEC Directional Gyro 6406-28L, Piper Code 694-103 i. Removed Standard Attitude Gyro 99002-9, RCA 22-15 S-TEC Autopilot Installation with Heading System (HSI) and Flight Director Weight 2. 0.90 Altitude Selector/Alerter Installation, Piper Drawing 104580-005 a. S-TEC Altitude Selector/Alerter 0279-PX, Piper Code 652-158 b. S-TEC Altitude Selector/Alerter Cable and Hardware 901482 2. 0.34 2. 0.54 3. 0.59.00 3. 2. 2. 2. 2. 2. 2. 2. 2. 2. 2. 2. 2. 2.						
S-TEC Autopilot Installation with Heading System (HSI) Weight 31.58 111.573 3523.36 207. S-TEC Autopilot Installation with Heading System (HSI) and Flight Director, Piper Drawing 104580-004 a. S-TEC System 55X Autopilot, Piper Drawing 104580-2 (Delta Weight) b. Switch Assembly with Post Light, Piper Drawing 101316-002 c. S-TEC Autopilot Cable Weight 90401-11, Delta from standard d. S-TEC Flight Director Steering Horizon 6413-28L e. S-TEC Flight Director Annunciator 01188-1PX s. TEC Flight Director Placards and Trim Kit 901481-1 g. Compass ST-180/ HSI Installation, Piper Drawing 101259-005 1. S-TEC 6443-PA Horizontal Situation Indicator 2. S-TEC 6444 Remote Gyro 3. S-TEC 01171-P Slaving Panel 4. S-TEC 90480-1 Hardware Installation Kit 6. Harnesses, Brackets and Hardware, Piper Drawing 101259-005 5. S-TEC 90480-1 Hardware Installation Kit 6. Harnesses, Brackets and Hardware, Piper Drawing 101259-005 1. Removed Standard Attitude Gyro 99002-9, RCA 22-15 S-TEC Autopilot Installation, Piper Drawing 104580-005 a. S-TEC Altitude Selector/Alerter 0279-PX, Piper Code 652-158 D. 90 61.20 55.08 D. 91 D. 110 D. 110 D. 111 D. 22.23 D. 97.99 D. 2178.60 D. 22.23 D. 97.99 D. 2178.60 D. 22.23 D. 97.99 D. 2178.60 D. 25.39 D. 25.89 D. 25.80 D. 25						
207. S-TEC Autopilot Installation with Heading System (HSI) and Flight Director, Piper Drawing 104580-004 a. S-TEC System 55X Autopilot, Piper Drawing 104580-2 (Delta Weight)						
Piper Drawing 104580-004 a. S-TEC System 55X Autopilot, Piper Drawing 104580 - 2 (Delta Weight) ≥ 22.23 97.99 2178.60 b. Switch Assembly with Post Light, Piper Drawing 101316-002 ≥ 0.01 63.038 0.643 c. S-TEC Autopilot Cable Weight 90401-11, Delta from standard ≥ 0.18 131.985 23.295 d. S-TEC Flight Director Steering Horizon 6413-28L ≥ 3.00 58.20 174.6 e. S-TEC Flight Director Annunciator 01188-1PX ≥ 0.539 58.20 31.37 f. S-TEC Flight Director Placards and Trim Kit 901481-1 ≥ 0.113 62.94 7.11 g. Compass ST-180/ HSI Installation, Piper Drawing 101259-005 ≥ 2.90 57.19 165.85 2. S-TEC 6443-PA Horizontal Situation Indicator ≥ 2.90 57.19 165.85 2. S-TEC 6444 Remote Gyro ≥ 3.40 186.58 634.39 3. S-TEC 01171-P Slaving Panel ≥ 0.10 60.94 6.09 4. S-TEC 6446 Flux Sensor ≥ 0.30 104.06 31.22 5. S-TEC 90480-1 Hardware Installation Kit ≥ 0.63 58.94 37.13 6. Harnesses, Brackets and Hardware, Piper Drawing 101259-005 ≥ 5.37 124.41 667.55 h. Remove S-TEC Directional Gyro 6406-28		S-TEC Autopilot Installation with Heading System (HSI) Weight		31.58	111.573	3523.36
a. S-TEC System 55X Autopilot, Piper Drawing 104580 - 2 (Delta Weight)	207.					
c. S-TEC Autopilot Cable Weight 90401-11, Delta from standard				22.23	97.99	2178.60
c. S-TEC Autopilot Cable Weight 90401-11, Delta from standard d. S-TEC Flight Director Steering Horizon 6413-28L e. S-TEC Flight Director Annunciator 01188-1PX f. S-TEC Flight Director Placards and Trim Kit 901481-1 g. Compass ST-180/ HSI Installation, Piper Drawing 101259-005 1. S-TEC 6443-PA Horizontal Situation Indicator 2. S-TEC 6444 Remote Gyro 3. S-TEC 64171-P Slaving Panel 4. S-TEC 6446 Flux Sensor 5. S-TEC 90480-1 Hardware Installation Kit 6. Harnesses, Brackets and Hardware, Piper Drawing 101259-005 h. Remove S-TEC Directional Gyro 6406-28L, Piper Code 694-103 i. Removed Standard Attitude Gyro 99002-9, RCA 22-15 S-TEC Autopilot Installation with Heading System (HSI) and Flight Director Weight 20.90 Altitude Selector/Alerter Installation, Piper Drawing 104580-005 a. S-TEC Altitude Selector/Alerter 0279-PX, Piper Code 652-158 b. S-TEC Altitude Selector/Alerter Cable and Hardware 901482 23.295 3.00 58.20 3.00 58.20 3.00 58.20 3.174.6 6.0.53 9.8.20 31.37 0.113 62.94 7.11 9.0133 62.90 57.19 165.85 63.43 9 165.85 63.43 9 165.85 63.43 9 165.85 63.43 9 165.85 63.43 9 165.85 63.43 9 165.85 63.43 9 165.85 63.43 9 165.85 63.43 9 165.85 63.43 9 165.85 63.43 9 165.85 63.43 9 165.8	-	b. Switch Assembly with Post Light, Piper Drawing 101316-002	\boxtimes	0.01	63.038	0.643
e. S-TEC Flight Director Annunciator 01188-IPX f. S-TEC Flight Director Placards and Trim Kit 901481-1 g. Compass ST-180/ HSI Installation, Piper Drawing 101259-005 1. S-TEC 6443-PA Horizontal Situation Indicator 2. S-TEC 6444 Remote Gyro 3. S-TEC 01171-P Slaving Panel 4. S-TEC 6446 Flux Sensor 5. S-TEC 90480-1 Hardware Installation Kit 6. Harnesses, Brackets and Hardware, Piper Drawing 101259-005 h. Remove S-TEC Directional Gyro 6406-28L, Piper Code 694-103 i. Removed Standard Attitude Gyro 99002-9, RCA 22-15 S-TEC Autopilot Installation with Heading System (HSI) and Flight Director Weight 2. 9.0 2. 90 31.37 2. 90 57.19 165.85 3.40 186.58 634.39 3. 104.06 31.22 3. 0.30 104.06 31.22 3. 37 124.41 667.55 4. 37 13 4. 467.55 4. 37 13 4. 59.00 4. 200.60 5. 37 124.41 667.55 6-2.80 59.90 167.70 32.57 110.219 3589.55 209. Altitude Selector/Alerter Installation, Piper Drawing 104580-005 a. S-TEC Altitude Selector/Alerter 0279-PX, Piper Code 652-158 □ 0.90 61.20 55.08 55.08 5-TEC Altitude Selector/Alerter Cable and Hardware 901482			\boxtimes	0.18	131.985	23.295
e. S-TEC Flight Director Annunciator 01188-1PX f. S-TEC Flight Director Placards and Trim Kit 901481-1 g. Compass ST-180/ HSI Installation, Piper Drawing 101259-005 1. S-TEC 6443-PA Horizontal Situation Indicator 2. S-TEC 6444 Remote Gyro 3. S-TEC 01171-P Slaving Panel 4. S-TEC 6446 Flux Sensor 5. S-TEC 90480-1 Hardware Installation Kit 6. Harnesses, Brackets and Hardware, Piper Drawing 101259-005 h. Remove S-TEC Directional Gyro 6406-28L, Piper Code 694-103 i. Removed Standard Attitude Gyro 99002-9, RCA 22-15 S-TEC Autopilot Installation with Heading System (HSI) and Flight Director Weight 2. S-TEC Altitude Selector/Alerter 10279-PX, Piper Code 652-158 b. S-TEC Altitude Selector/Alerter Cable and Hardware 901482 3. S-TEC Altitude Selector/Alerter Cable and Hardware 901482 3. S-TEC S-130 3. S-150		d. S-TEC Flight Director Steering Horizon 6413-28L		3.00	58.20	174.6
f. S-TEC Flight Director Placards and Trim Kit 901481-1 □ 0.113 62.94 7.11 g. Compass ST-180/ HSI Installation, Piper Drawing 101259-005 □ 2.90 57.19 165.85 1. S-TEC 6443-PA Horizontal Situation Indicator □ 2.90 57.19 165.85 2. S-TEC 6444 Remote Gyro □ 3.40 186.58 634.39 3. S-TEC 01171-P Slaving Panel □ 0.10 60.94 6.09 4. S-TEC 6446 Flux Sensor □ 0.30 104.06 31.22 5. S-TEC 90480-1 Hardware Installation Kit □ 0.63 58.94 37.13 6. Harnesses, Brackets and Hardware, Piper Drawing 101259-005 □ 5.37 124.41 667.55 h. Remove S-TEC Directional Gyro 6406-28L, Piper Code 694-103 □ -3.40 59.00 -200.60 i. Removed Standard Attitude Gyro 99002-9, RCA 22-15 □ -2.80 59.90 -167.70 S-TEC Autopilot Installation with Heading System (HSI) and Flight Director Weight 209. Altitude Selector/Alerter Installation, Piper Drawing 104580-005 □ □ 0.90 61.20 55.08 b. S-TEC Altitude Selector/Alerter Cable and Hardware 901482				0.539	58.20	31.37
g. Compass ST-180/ HSI Installation, Piper Drawing 101259-005 1. S-TEC 6443-PA Horizontal Situation Indicator			\boxtimes	0.113	62.94	7.11
1. S-TEC 6443-PA Horizontal Situation Indicator						
2. S-TEC 6444 Remote Gyro			\boxtimes	2.90	57.19	165.85
3. S-TEC 01171-P Slaving Panel			$\overline{\boxtimes}$	3.40	186.58	634.39
4. S-TEC 6446 Flux Sensor						6.09
5. S-TEC 90480-1 Hardware Installation Kit				0.30	104.06	31.22
6. Harnesses, Brackets and Hardware, Piper Drawing 101259-005						37.13
h. Remove S-TEC Directional Gyro 6406-28L, Piper Code 694-103 i. Removed Standard Attitude Gyro 99002-9, RCA 22-15 S-TEC Autopilot Installation with Heading System (HSI) and Flight Director Weight 32.57 Altitude Selector/Alerter Installation, Piper Drawing 104580-005 a. S-TEC Altitude Selector/Alerter 0279-PX, Piper Code 652-158 b. S-TEC Altitude Selector/Alerter Cable and Hardware 901482 3-3.40 59.00 -2.00.60 -2.80 59.90 -167.70 32.57 110.219 3589.55						667.55
i. Removed Standard Attitude Gyro 99002-9, RCA 22-15 S-TEC Autopilot Installation with Heading System (HSI) and Flight Director Weight 32.57 110.219 3589.55 209. Altitude Selector/Alerter Installation, Piper Drawing 104580-005 a. S-TEC Altitude Selector/Alerter 0279-PX, Piper Code 652-158 b. S-TEC Altitude Selector/Alerter Cable and Hardware 901482 0.90 61.20 55.08 21.12						
S-TEC Autopilot Installation with Heading System (HSI) and Flight Director Weight 32.57 110.219 3589.55 209. Altitude Selector/Alerter Installation, Piper Drawing 104580-005 a. S-TEC Altitude Selector/Alerter 0279-PX, Piper Code 652-158 b. S-TEC Altitude Selector/Alerter Cable and Hardware 901482						
Weight 32.57 110.219 3589.55 209. Altitude Selector/Alerter Installation, Piper Drawing 104580-005 a. S-TEC Altitude Selector/Alerter 0279-PX, Piper Code 652-158				2.00	57.70	201110
a. S-TEC Altitude Selector/Alerter 0279-PX, Piper Code 652-158 □ 0.90 61.20 55.08 b. S-TEC Altitude Selector/Alerter Cable and Hardware 901482 □ 0.34 62.87 21.12				32.57	110.219	3589.55
a. S-TEC Altitude Selector/Alerter 0279-PX, Piper Code 652-158 □ 0.90 61.20 55.08 b. S-TEC Altitude Selector/Alerter Cable and Hardware 901482 □ 0.34 62.87 21.12	209	Altitude Selector/Alerter Installation, Piper Drawing 104580-005				
b. S-TEC Altitude Selector/Alerter Cable and Hardware 901482	207.					
b. S-TEC Altitude Selector/Alerter Cable and Hardware 901482		a. 5 125 1 minute delector metter of 17 171, 11per code 002-130	\boxtimes	0.90	61.20	55.08
		b. S-TEC Altitude Selector/Alerter Cable and Hardware 901482	\boxtimes			
				1.24	61.65	76.20



Item No.	Item	Mark if Option Installed	Weight (Pounds)	Arm (In.) Aft Datum	Moment (LbsIn.)
	(j) Auto Pilots (Optional Equipment)-continued				
211.	Pilot S-TEC Trim And Mike Switch Assembly 101117-15 Removed Standard Pilot Mike Switch Assembly, Piper Drawing 101117-005 Delta Weight		0.21 -0.093 0.12	68.94 68.938 68.94	14.59 -6.399 8.19
213.	Pilot S-TEC System 55 Autopilot Switch Assembly, Piper Drawing 101117-016 Removed Standard Pilot Mike Switch Assembly, Piper Drawing 101117-005 Delta Weight		0.28 -0.093 0.19	68.94 68.938 68.94	19.45 -6.399 13.05
215.	Avionics Cooling Blower - 3 Port Installation with Single GNS 430 and Autopilot, Piper Drawing 101318-2 a. Troll Avionics Icebox FN-200 PSV 4000020 Blower, Piper Code 460-110 b. Cable, Bracket and Hardware, Piper Drawing 101318-2 Removed Standard Avionics Cooling Blower Installation 101318-2 Delta Weight		1.07 0.78 -1.64 0.21	56.54 54.57 55.90 54.25	60.44 42.45 -91.44 11.44
217.	Avionics Cooling Blower - 5 Port Installation with Dual GNS 430 and Autopilot, Piper Drawing 101318-4 a. Troll Avionics Icebox FN-400 PSV P/N 4000022-002 Blower, Piper Code 460-112 b. Cable, Bracket and Hardware, Piper Drawing 101318-4 Removed Standard Avionics Cooling Blower Installation 101318-2 Delta Weight		1.18 0.95 -1.64 0.50	56.54 54.51 55.90 54.77	66.79 51.96 -91.44 27.31
	(k) Optional Avionics Equipment				
221.	GNS 430 GPS/Nav/Com-(11-33 VDC) Single with Stormscope and Skywatch Provisions, Piper Drawing 104479-2 a. Garmin GNS430 #1 (11-33 VDC) with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229 b. Cables/harnesses and hardware, Piper Drawing 104479-2 Removed Standard GNS 430 System Installation 104479-2 Delta Weight		6.56 2.00 -8.48 0.08	58.14 55.58 57.53 58.14	381.18 111.22 -487.96 4.45
223.	GNS 430 GPS/Nav/Com - Single with Stormscope, Skywatch and Autopilot Provisions, Piper Drawing 104479-3 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 b. Cables/harnesses and hardware, Piper Drawing 104479-3 Removed Standard GNS 430 System Installation 104479-2 Delta Weight		6.48 2.16 -8.48 0.16	58.14 55.54 57.53 55.10	376.73 119.86 -487.96 8.63



Item No.	Item		Mark if Option Installed	Weight (Pounds)	Arm (In.) Aft Datum	Moment (LbsIn.)
	(k) Optional Avionics Equipment-continued					
225.	GNS 430 GPS/Nav/Com (11-33 VDC) Single with Stormscope, Autopilot Provisions, Piper Drawing 104479-3 a. Garmin GNS430 #1 (11-33 VDC) with mount, connectors an Piper PS50040-40-4, Piper Code 601-229 b. Cables/harnesses and hardware, Piper Drawing 104479-3			6.56 2.16	58.14 55.54	381.18 119.86
	Removed Standard GNS 430 System Installation 104479-2	Delta Weight		-8.48 0.23	57.53 56.10	-487.96 13.08
227.	GNS 430 GPS/Nav/Com - Single with Stormscope, Skywatch ar Provisions, Piper Drawing 104479-4 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 b. Cables/harnesses and hardware, Piper Drawing 104479-4 Removed Standard GNS 430 System Installation 104479-2	nd DME Delta Weight		6.48 2.16 -8.48 0.16	58.14 55.54 57.53 55.10	376.73 119.86 -487.96 8.63
229.	GNS 430 GPS/Nav/Com (11-33 VDC) Single with Stormscope, DME Provisions, Piper Drawing 104479-4					
	 a. Garmin GNS430 #1(11-33 VDC) with mount, connectors and Piper PS50040-40-4, Piper Code 601-229 b. Cables/harnesses and hardware, Piper Drawing 104479-4 Removed Standard GNS 430 System Installation 104479-2 	Delta Weight		6.56 2.16 -8.48 0.23	58.14 55.54 57.53 56.10	381.18 119.86 -487.96 13.08
231.	GNS 430 GPS/Nav/Com - Single with Stormscope, Skywatch, A DME Provisions, Piper Drawing 104479-5 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 b. Cables/harnesses and hardware, Piper Drawing 104479-5 Removed Standard GNS 430 System Installation 104479-2	autopilot and Delta Weight		6.48 2.27 -8.48 0.27	58.14 55.52 57.53 55.10	376.73 125.92 -487.96 14.69
235.	GNS 430 GPS/Nav/Com (11-33 VDC) Single with Stormscope, Autopilot and DME Provisions, Piper Drawing 104479-5 a. Garmin GNS430 #1 (11-33 VDC) with mount, connectors an Piper PS50040-40-4, Piper Code 601-229 b. Cables/harnesses and hardware, Piper Drawing 104479-5 Removed Standard GNS 430 System Installation 104479-2			6.56 2.27 -8.48 0.34	58.138 55.52 57.53 55.778	381.18 125.92 -487.96 19.14



Item No.	Item		Mark if Option Installed	Weight (Pounds)	Arm (In.) Aft Datum	Moment (LbsIn.)
	(k) Optional Avionics Equipment-continued					
237.	GNS 430 GPS/Nav/Com - Single with Stormscope, Skywatch at Provisions, Piper Drawing 104479-6	nd HSI				
	a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214			6.48 2.11	58.14 55.55	376.73 117.47
	b. Cables/harnesses and hardware, Piper Drawing 104479-6 Removed Standard GNS 430 System Installation 104479-2			-8.48	57.53	-487.96
	Removed Standard GNS 430 System histaniation 104417-2	Delta Weight		0.11	55.10	6.24
239.	GNS 430 GPS/Nav/Com (11-33 VDC) Single with Stormscope, HSI Provisions, Piper Drawing 104479-6	Skywatch and				
	a. Garmin GNS430 #1 (11-33 VDC) with mount, connectors an	d data card,			50 120	201.10
	Piper PS50040-40-4, Piper Code 601-229		H	6.56 2.11	58.138 55.55	381.18 117.47
	b. Cables/harnesses and hardware, Piper Drawing 104479-6			-8.48	57.53	-487.96
	Removed Standard GNS 430 System Installation 104479-2	Delta Weight		0.19	56.325	10.69
241.	GNS 430 GPS/Nav/Com - Single with Stormscope, Skywatch, F Provisions, Piper Drawing 104479-7 a. Garmin GNS430 #1 with mount, connectors and data card,	ISI and DME			ules som	
	Piper PS50040-40-1, Piper Code 601-214			6.48	58.14	376.73
	 b. Cables/harnesses and hardware, Piper Drawing 104479-7 			2.27	55.52	125.92
	Removed Standard GNS 430 System Installation 104479-2			-8.48	57.53	-487.96
		Delta Weight		0.27	55.10	14.69
243.	GNS 430 GPS/Nav/Com (11-33 VDC) Single with Stormscope, and DME Provisions, Piper Drawing 104479-7					
	a. Garmin GNS430 #1 (11-33 VDC) with mount, connectors an	d data card,		656	50 120	381.18
	Piper PS50040-40-4, Piper Code 601-229		H	6.56 2.27	58.138 55.52	125.92
	b. Cables/harnesses and hardware, Piper Drawing 104479-7 Removed Standard GNS 430 System Installation 104479-2			-8.48	57.53	-487.96
	Removed Standard GNS 430 System histaliation 1044/7-2	Delta Weight		0.34	55.78	19.14
245.	GNS 430 GPS/Nav/Com - Dual With Stormscope and Skywatch	Provisions,				
	Piper Drawing 104480-2					
	 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 			6.48	58.138	376.73
	b. Garmin GNS430 #2 with mount, connectors and data card,			6.48	58.138	376.73
	Piper PS50040-40-1, Piper Code 601-214 c. Garmin GI-106 Indicator #2, Piper Code 602-239		H	1.02	60.23	61.43
	d. Cables/harnesses and hardware, Piper Drawing 104480-2			4.02	56.37	226.56
	Removed Standard GNS 430 System Installation 104479-2			-8.48	57.53	-487.96
	Nonovod olandard 0110 450 System installation 1044/5-2	Delta Weight		9.52	18.57	176.77
		Doing Weight		7.52	10.01	1.0.11



(k) Optional Avionics Equipment - continued 247. GNS 430 GPS/Nav/Com (11-33 VDC) Dual With Stormscope and Skywatch Provisions, Piper Drawing 104480-2 a. Garmin GNS430 (11-33 VDC) # with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229	Item No.	Item		Mark if Option Installed	Weight (Pounds)	Arm (In.) Aft Datum	Moment (LbsIn.)
Provisions, Piper Drawing 104480-2 a. Garmin GNS430 (11-33 VDC) #1 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229 b. Garmin GNS430 (11-33 VDC) #2 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229 c. Garmin GI-106 Indicator #2, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-2 4. Cables/harnesses and hardware, Piper Drawing 104480-3 d. Garmin GNS430 (11-33 VDC) #1 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-224 251. GNS 430 GPS/Nav/Com (11-33 VDC) Dual with Stormscope, Skywatch and Autopilot Provisions, Piper Drawing 104480-3 a. Garmin GNS430 (11-33 VDC) #1 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-3 a. Garmin GNS430 (11-33 VDC) #1 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-214 251. GNS 430 GPS/Nav/Com (11-33 VDC) Dual with Stormscope, Skywatch and Autopilot Provisions, Piper Drawing 104480-3 a. Garmin GNS430 (11-33 VDC) #1 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229 d. Cables/harnesses and hardware, Piper Drawing 104480-3 a. Garmin GNS430 (11-33 VDC) #2 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229 d. Cables/harnesses and hardware, Piper Drawing 104480-3 d. Cables/harnesses and bardware, Piper Power and Cables defined of the Cab		(k) Optional Avionics Equipment - continued					
Piper PS50040-40-4, Piper Code 601-229 b. Garmin GNS430 (11-33 VDC) #2 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229 c. Garmin GI-106 Indicator #2, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-2 e. Garmin GNS 430 System Installation 104479-2 Delta Weight 249. GNS 430 GPS/Nav/Com - Dual with Stormscope, Skywatch and Autopilot Provisions, Piper Drawing 104480-3 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 b. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 c. Garmin GI-106 Indicator #2, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-3 a. Garmin GNS430 #3 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 b. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 c. Garmin GI-106 Indicator #2, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-3 b. Garmin GNS430 #30 System Installation 104479-2 b. GNS 430 GPS/Nav/Com (11-33 VDC) Dual with Stormscope, Skywatch and Autopilot Provisions, Piper Drawing 104480-3 b. Garmin GNS430 #1-33 VDC) #1 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229 b. Garmin GNS430 #1-33 VDC) #1 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229 c. Garmin GNS430 #1-33 VDC) #2 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229 c. Garmin GNS430 #1-35 VDC) #1 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229 c. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229 d. Cables/harnesses and hardware, Piper Drawing 104480-3 c. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-214 b. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-214 b. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-	247.		d Skywatch				
Piper PS50040-40-4, Piper Code 601-229 c. Garmin GI-106 Indicator #2, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-2 Removed Standard GNS 430 System Installation 104479-2 Delta Weight 249. GNS 430 GPS/Nav/Com - Dual with Stormscope, Skywatch and Autopilot Provisions, Piper Drawing 104480-3 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 c. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 d. Cables/harnesses and hardware, Piper Drawing 104480-3 a. Garmin GNS430 #30 #30 #30 #30 #30 #30 #30 #30 #30 #		Piper PS50040-40-4, Piper Code 601-229			6.56	58.138	381.18
c. Garmin GI-106 Indicator #2, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-2 Removed Standard GNS 430 System Installation 104479-2 249. GNS 430 GPS/Nav/Com - Dual with Stormscope, Skywatch and Autopilot Provisions, Piper Drawing 104480-3 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS5004-040-1, Piper Code 601-214 b. Garmin GNS430 #2 with mount, connectors and data card, Piper PS5004-016 Indicator #2, Piper Drawing 104480-3 d. Cables/harnesses and hardware, Piper Drawing 104480-3 a. Garmin GI-106 Indicator #2, Piper Code 601-219 b. Garmin GNS430 #30 System Installation 104479-2 b. GRAM Autopilot Provisions, Piper Drawing 104480-3 a. Garmin GNS430 (11-33 VDC) Dual with Stormscope, Skywatch and Autopilot Provisions, Piper Drawing 104480-3 a. Garmin GNS430 (11-33 VDC) #1 with mount, connectors and data card, Piper PS5004-040-4, Piper Code 601-229 c. Garmin GNS430 (11-33 VDC) #2 with mount, connectors and data card, Piper PS5004-040-4, Piper Code 601-229 c. Garmin GNS430 (11-33 VDC) #2 with mount, connectors and data card, Piper PS5004-040-4, Piper Code 601-229 c. Garmin GNS430 (11-33 VDC) #2 with mount, connectors and data card, Piper PS5004-040-4, Piper Code 601-229 c. Garmin GNS430 (11-33 VDC) #2 with mount, connectors and data card, Piper PS5004-040-4, Piper Code 601-229 c. Garmin GNS430 (11-33 VDC) #2 with mount, connectors and data card, Piper PS5004-040-4, Piper Code 601-229 c. Garmin GNS430 With MS430 With With With With With With With With			data card,		6.56	58 138	381 18
d. Cables/harnesses and hardware, Piper Drawing 104480-2 Removed Standard GNS 430 System Installation 104479-2 Delta Weight Delta Weight Delta Weight 249. GNS 430 GPS/Nav/Com - Dual with Stormscope, Skywatch and Autopilot Provisions, Piper Drawing 104480-3 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 b. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 c. Garmin Gl-106 Indicator #2, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-3 a. Garmin GNS430 (11-33 VDC) Dual with Stormscope, Skywatch and Autopilot Provisions, Piper Drawing 104480-3 a. Garmin GNS430 (11-33 VDC) #1 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229 b. Garmin GNS430 (11-33 VDC) #2 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229 b. Garmin GNS430 (11-33 VDC) #2 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229 c. Garmin GNS430 (11-33 VDC) #2 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229 d. Cables/harnesses and hardware, Piper Drawing 104480-3 Removed Standard GNS 430 System Installation 104479-2 Piper PS50040-40-4, Piper Code 601-229 Delta Weight 253. GNS 430 GPS/Nav/Com - Dual with Stormscope, Skywatch and DME Provisions, Piper Drawing 104480-4 a. Garmin GNS430 H with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 b. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 c. Garmin GNS430 #3 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 c. Garmin GNS430 #3 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 c. Garmin GNS430 #3 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 c. Garmin GNS430 #3 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 c. Garmin GNS430 #3 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214				H			
Removed Standard GNS 430 System Installation 104479-2 -8.48 57.53 -487.96				H			
Delta Weight 9.67 58.15 562.40							
249. GNS 430 GPS/Nav/Com - Dual with Stormscope, Skywatch and Autopilot Provisions, Piper Drawing 104480-3 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 b. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 c. Garmin GI-106 Indicator #2, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-3 Removed Standard GNS 430 System Installation 104479-2 Delta Weight 251. GNS 430 GPS/Nav/Com (11-33 VDC) Dual with Stormscope, Skywatch and Autopilot Provisions, Piper Drawing 104480-3 a. Garmin GNS430 (11-33 VDC) #1 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229 b. Garmin GNS430 (11-33 VDC) #2 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229 c. Garmin GI-106 Indicator #2, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-3 Removed Standard GNS 430 System Installation 104479-2 Delta Weight 253. GNS 430 GPS/Nav/Com - Dual with Stormscope, Skywatch and DME Provisions, Piper Drawing 104480-4 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-219 Delta Weight 254. GARB SS.138 376.73 Delta Weight 255. GARB SS.138 376.73 Carmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 b. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 c. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 c. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 c. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 c. Garmin Gl-106 Indicator #2, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-4 d. Cables/harnesses and hardware, Piper Drawing 104480-4 e. Garmin Gl-106 Indicator #2, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-4 e. Garmin Gl-106 Indicator		Removed Standard GNS 430 System Installation 1044/9-2					
Provisions, Piper Drawing 104480-3 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 b. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 c. Garmin GI-106 Indicator #2, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-3 Removed Standard GNS 430 System Installation 104479-2 Delta Weight Delta			Delta Weight		9.67	58.15	562.40
Provisions, Piper Drawing 104480-3 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 b. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 c. Garmin GI-106 Indicator #2, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-3 Removed Standard GNS 430 System Installation 104479-2 Delta Weight Delta	249.	GNS 430 GPS/Nay/Com - Dual with Stormscope, Skywatch and	Autopilot				
a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 b. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 c. Garmin GI-106 Indicator #2, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-3 Removed Standard GNS 430 System Installation 104479-2 Delta Weight 251. GNS 430 GPS/Nav/Com (11-33 VDC) Dual with Stormscope, Skywatch and Autopilot Provisions, Piper Drawing 104480-3 a. Garmin GNS430 (11-33 VDC) #1 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229 b. Garmin GNS430 (11-33 VDC) #2 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229 c. Garmin GI-106 Indicator #2, Piper Drawing 104480-3 d. Cables/harnesses and hardware, Piper Drawing 104480-3 Removed Standard GNS 430 System Installation 104479-2 Delta Weight 253. GNS 430 GPS/Nav/Com - Dual with Stormscope, Skywatch and DME Provisions, Piper Drawing 104480-4 a. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229 Delta Weight 254. GARMEN SARMEN S							
b. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 c. Garmin GI-106 Indicator #2, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-3 Removed Standard GNS 430 System Installation 104479-2 251. GNS 430 GPS/Nav/Com (11-33 VDC) Dual with Stormscope, Skywatch and Autopilot Provisions, Piper Drawing 104480-3 a. Garmin GNS430 (11-33 VDC) #1 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229 b. Garmin GNS430 (11-33 VDC) #2 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229 c. Garmin GI-106 Indicator #2, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-3 Removed Standard GNS 430 System Installation 104479-2 253. GNS 430 GPS/Nav/Com - Dual with Stormscope, Skywatch and DME Provisions, Piper Drawing 104480-4 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 b. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 c. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 d. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 d. Garmin GI-106 Indicator #2, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-4 d. Carbin GI-106 Indicator #2, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-4 Removed Standard GNS 430 System Installation 104479-2 d. Cables/harnesses and hardware, Piper Drawing 104480-4 Removed Standard GNS 430 System Installation 104479-2 d. Cables/harnesses and hardware, Piper Drawing 104480-4 Removed Standard GNS 430 System Installation 104479-2 d. Cables/harnesses and hardware, Piper Drawing 104480-4 d. Cables/harnesses and har							
Piper PS50040-40-1, Piper Code 601-214 c. Garmin GI-106 Indicator #2, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-3 Removed Standard GNS 430 System Installation 104479-2 251. GNS 430 GPS/Nav/Com (11-33 VDC) Dual with Stormscope, Skywatch and Autopilot Provisions, Piper Drawing 104480-3 a. Garmin GNS430 (11-33 VDC) #1 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229 b. Garmin GNS430 (11-33 VDC) #2 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229 c. Garmin GI-106 Indicator #2, Piper Drawing 104480-3 d. Cables/harnesses and hardware, Piper Drawing 104480-3 Removed Standard GNS 430 System Installation 104479-2 Delta Weight 253. GNS 430 GPS/Nav/Com - Dual with Stormscope, Skywatch and DME Provisions, Piper Drawing 104480-4 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 b. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 c. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 c. Garmin GI-106 Indicator #2, Piper Drawing 104480-4 c. Garmin GI-106 Indicator #2, Piper Code 601-214 c. Garmin GI-106 Indicator #2, Piper Prawing 104480-4 d. Cables/harnesses and hardware, Piper Drawing 104480-4 Removed Standard GNS 430 System Installation 104479-2 -8.48 -8.18 -8.138 -7.53		Piper PS50040-40-1, Piper Code 601-214			6.48	58.138	376.73
c. Garmin GI-106 Indicator #2, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-3 Removed Standard GNS 430 System Installation 104479-2 251. GNS 430 GPS/Nav/Com (11-33 VDC) Dual with Stormscope, Skywatch and Autopilot Provisions, Piper Drawing 104480-3 a. Garmin GNS430 (11-33 VDC) #1 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229 b. Garmin GINS430 (11-33 VDC) #2 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229 c. Garmin GI-106 Indicator #2, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-3 Removed Standard GNS 430 System Installation 104479-2 253. GNS 430 GPS/Nav/Com - Dual with Stormscope, Skywatch and DME Provisions, Piper Drawing 104480-4 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 b. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 c. Garmin GI-106 Indicator #2, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-4 c. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 c. Garmin GI-106 Indicator #2, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-4 Removed Standard GNS 430 System Installation 104479-2 d. Cables/harnesses and hardware, Piper Drawing 104480-4 Removed Standard GNS 430 System Installation 104479-2 -8.48 57.53 -8.73 -8.73.54 -8.75.53 -8.73.54 -8.75.53 -8.73.57.53 -8		b. Garmin GNS430 #2 with mount, connectors and data card,					
d. Cables/harnesses and hardware, Piper Drawing 104480-3 Removed Standard GNS 430 System Installation 104479-2 Delta Weight D		Piper PS50040-40-1, Piper Code 601-214					
Removed Standard GNS 430 System Installation 104479-2 Delta Weight Delta Weight Delta Weight Removed Standard GNS 430 System Installation 104479-2 Delta Weight Delta Weight Delta Weight Removed Standard GNS 430 System Installation 104479-2 Delta Weight Delta Weight Delta Weight Removed Standard GNS 430 System Installation 104479-2 Delta Weight Delta Weight Delta Weight Removed Standard GNS 430 System Installation 104479-2 Removed Standard GNS 430 System Installation 104479-2 Delta Weight Delta Weight Delta Weight Removed Standard GNS 430 System Installation 104479-2 Removed Standard GNS 430 System Installation 104479-2 Removed Standard GNS 430 System Installation 104479-2 Removed Standard GNS 430 System Installation Installat		c. Garmin GI-106 Indicator #2, Piper Code 602-239					
Delta Weight 9.75 19.452 189.72 251. GNS 430 GPS/Nav/Com (11-33 VDC) Dual with Stormscope, Skywatch and Autopilot Provisions, Piper Drawing 104480-3 a. Garmin GNS430 (11-33 VDC) #1 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229		d. Cables/harnesses and hardware, Piper Drawing 104480-3					
251. GNS 430 GPS/Nav/Com (11-33 VDC) Dual with Stormscope, Skywatch and Autopilot Provisions, Piper Drawing 104480-3 a. Garmin GNS430 (11-33 VDC) #1 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229		Removed Standard GNS 430 System Installation 104479-2			-8.48	57.534	
Autopilot Provisions, Piper Drawing 104480-3 a. Garmin GNS430 (11-33 VDC) #1 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229			Delta Weight		9.75	19.452	189.72
Autopilot Provisions, Piper Drawing 104480-3 a. Garmin GNS430 (11-33 VDC) #1 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229	251	GNS 430 GPS/Nay/Com (11-33 VDC) Dual with Stormscope Sk	wwatch and				
a. Garmin GNS430 (11-33 VDC) #1 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229	231.		y waten and				
Piper PS50040-40-4, Piper Code 601-229 6.56 58.138 381.18 b. Garmin GNS430 (11-33 VDC) #2 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229 6.56 58.138 381.18 c. Garmin GI-106 Indicator #2, Piper Code 602-239 1.02 60.23 61.43 d. Cables/harnesses and hardware, Piper Drawing 104480-3 4.25 56.297 239.506 Removed Standard GNS 430 System Installation 104479-2 -8.48 57.534 -487.96 Delta Weight 9.91 58.080 575.34 253. GNS 430 GPS/Nav/Com - Dual with Stormscope, Skywatch and DME Provisions, Piper Drawing 104480-4 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 6.48 58.138 376.73 b. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 6.48 58.138 376.73 c. Garmin GI-106 Indicator #2, Piper Code 602-239 1.02 60.23 61.43 d. Cables/harnesses and hardware, Piper Drawing 104480-4 4.27 56.34 240.65 Removed Standard GNS 430 System Installation 104479-2 -8.48 57.53 -487.96			data card.				
b. Garmin GNS430 (11-33 VDC) #2 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229			000001000000000000000000000000000000000		6.56	58.138	381.18
Piper PS50040-40-4, Piper Code 601-229 □ 6.56 58.138 381.18 c. Garmin GI-106 Indicator #2, Piper Code 602-239 □ 1.02 60.23 61.43 d. Cables/harnesses and hardware, Piper Drawing 104480-3 □ 4.25 56.297 239.506 Removed Standard GNS 430 System Installation 104479-2 -8.48 57.534 -487.96 Delta Weight 9.91 58.080 575.34 253. GNS 430 GPS/Nav/Com - Dual with Stormscope, Skywatch and DME Provisions, Piper Drawing 104480-4 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 □ 6.48 58.138 376.73 b. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 □ 6.48 58.138 376.73 c. Garmin GI-106 Indicator #2, Piper Code 602-239 □ 1.02 60.23 61.43 d. Cables/harnesses and hardware, Piper Drawing 104480-4 □ 4.27 56.34 240.65 Removed Standard GNS 430 System Installation 104479-2 -8.48 57.53 -487.96			data card,				
d. Cables/harnesses and hardware, Piper Drawing 104480-3 Removed Standard GNS 430 System Installation 104479-2 Delta Weight 253. GNS 430 GPS/Nav/Com - Dual with Stormscope, Skywatch and DME Provisions, Piper Drawing 104480-4 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 b. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 c. Garmin GI-106 Indicator #2, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-4 Removed Standard GNS 430 System Installation 104479-2 4.25 56.297 239.506 -8.48 57.534 -487.96					6.56	58.138	381.18
d. Cables/harnesses and hardware, Piper Drawing 104480-3 4.25 56.297 239.506 Removed Standard GNS 430 System Installation 104479-2 -8.48 57.534 -487.96 Delta Weight 9.91 58.080 575.34 253. GNS 430 GPS/Nav/Com - Dual with Stormscope, Skywatch and DME Provisions, Piper Drawing 104480-4 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 b. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 c. Garmin GI-106 Indicator #2, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-4 Removed Standard GNS 430 System Installation 104479-2 -8.48 57.53 -487.96		c. Garmin GI-106 Indicator #2, Piper Code 602-239			1.02	60.23	61.43
Removed Standard GNS 430 System Installation 104479-2					4.25	56.297	239.506
Delta Weight 9.91 58.080 575.34 253. GNS 430 GPS/Nav/Com - Dual with Stormscope, Skywatch and DME Provisions, Piper Drawing 104480-4 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 b. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 c. Garmin GI-106 Indicator #2, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-4 Removed Standard GNS 430 System Installation 104479-2 56.34 240.65 Removed Standard GNS 430 System Installation 104479-2					-8.48	57.534	-487.96
Provisions, Piper Drawing 104480-4 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 b. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 c. Garmin GI-106 Indicator #2, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-4 Removed Standard GNS 430 System Installation 104479-2 Pious Drawing 104480-4 A.27 56.34 240.65 Removed Standard GNS 430 System Installation 104479-2			Delta Weight		9.91	58.080	575.34
Provisions, Piper Drawing 104480-4 a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 b. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 c. Garmin GI-106 Indicator #2, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-4 Removed Standard GNS 430 System Installation 104479-2 Pious Drawing 104480-4 A.27 56.34 240.65 Removed Standard GNS 430 System Installation 104479-2							
a. Garmin GNS430 #1 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 b. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 c. Garmin GI-106 Indicator #2, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-4 Removed Standard GNS 430 System Installation 104479-2 a 56.34 58.138 376.73	253.		OME				
b. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214							
b. Garmin GNS430 #2 with mount, connectors and data card, Piper PS50040-40-1, Piper Code 601-214 c. Garmin GI-106 Indicator #2, Piper Code 602-239 d. Cables/harnesses and hardware, Piper Drawing 104480-4 Removed Standard GNS 430 System Installation 104479-2 d. 6.48 58.138 376.73 6.43 4.27 56.34 240.65 -8.48 57.53 -487.96		Piper PS50040-40-1, Piper Code 601-214			6.48	58.138	376.73
c. Garmin GI-106 Indicator #2, Piper Code 602-239				701 70			
d. Cables/harnesses and hardware, Piper Drawing 104480-4 4.27 56.34 240.65 Removed Standard GNS 430 System Installation 104479-2 -8.48 57.53 -487.96		Piper PS50040-40-1, Piper Code 601-214			6.48	58.138	
Removed Standard GNS 430 System Installation 104479-2 -8.48 57.53 -487.96		c. Garmin GI-106 Indicator #2, Piper Code 602-239			1.02	60.23	61.43
Removed Standard GNS 430 System Installation 104479-2 -8.48 57.53 -487.96		d. Cables/harnesses and hardware, Piper Drawing 104480-4			4.27	56.34	240.65
		Removed Standard GNS 430 System Installation 104479-2			-8.48	57.53	-487.96
			Delta Weight		9.77	19.53	190.86



Item			Mark if	Weight	Arm (In.)	Moment
No.	Item		Option Installed	(Pounds)	Aft Datum	(LbsIn.)
	(k) Optional Avionics Equipment - continued					
255.	GNS 430 GPS/Nav/Com (11-33 VDC) Dual with Stormscope, Sk DME Provisions, Piper Drawing 104480-4					
	 a. Garmin GNS430 (11-33 VDC) #1 with mount, connectors and Piper PS50040-40-4, Piper Code 601-229 			6.56	58.138	381.18
	b. Garmin GNS430 (11-33 VDC) #2 with mount, connectors and	data card,			50 120	201 10
	Piper PS50040-40-4, Piper Code 601-229		H	6.56	58.138	381.18
	c. Garmin GI-106 Indicator #2, Piper Code 602-239			1.02	60.23	61.43
	d. Cables/harnesses and hardware, Piper Drawing 104480-4		Ш	4.27	56.34	240.65
	Removed Standard GNS 430 System Installation 104479-2			-8.48	57.53	-487.96
		Delta Weight		9.92	58.09	576.49
257.	GNS 430 GPS/Nav/Com - Dual with Stormscope, Skywatch, Aut DME Provisions, Piper Drawing 104480-5	opilot and				
	a. Garmin GNS430 #1 with mount, connectors and data card,					
	Piper PS50040-40-1, Piper Code 601-214			6.48	58.138	376.73
	b. Garmin GNS430 #2 with mount, connectors and data card,					
	Piper PS50040-40-1, Piper Code 601-214			6.48	58.138	376.73
	c. Garmin GI-106 Indicator #2, Piper Code 602-239			1.02	60.23	61.43
	d. Cables/harnesses and hardware, Piper Drawing 104480-5			4.38	56.30	246.58
	Removed Standard GNS 430 System Installation 104479-2			-8.48	57.53	-487.96
		Delta Weight		9.88	19.92	196.79
259.	GNS 430 GPS/Nav/Com (11-33 VDC) Dual with Stormscope, Sk	vwatch				
20).	Autopilot and DME Provisions, Piper Drawing 104480-5	J				
	a. Garmin GNS430 (11-33 VDC) #1 with mount, connectors and	data card.				
	Piper PS50040-40-4, Piper Code 601-229	Day Tietes		6.56	58.138	381.18
	b. Garmin GNS430 (11-33 VDC) #2 with mount, connectors and	data card,				
	Piper PS50040-40-4, Piper Code 601-229			6.56	58.138	381.18
	c. Garmin GI-106 Indicator #2, Piper Code 602-239			1.02	60.23	61.43
	d. Cables/harnesses and hardware, Piper Drawing 104480-5			4.38	56.30	246.58
	Removed Standard GNS 430 System Installation 104479-2			-8.48	57.53	-487.96
	tomorou sumano cris iso system momanion rovini a	Delta Weight		10.03	58.06	582.42
		ror n				
261.	GNS 430 GPS/Nav/Com, Dual with Stormscope, Skywatch and F Piper Drawing 104480-6	ISI Provisions,				
	a. Garmin GNS430 #1 with mount, connectors and data card,					
	Piper PS50040-40-1, Piper Code 601-214			6.48	58.138	376.73
	b. Garmin GNS430 #2 with mount, connectors and data card,					
	Piper PS50040-40-1, Piper Code 601-214			6.48	58.138	376.73
	c. Cables/harnesses and hardware, Piper Drawing 104480-6			4.17	56.32	234.96
	Removed Standard GNS 430 System Installation 104479-2		()	-8.48	57.53	-487.96
	· · · · · · · · · · · · · · · · · · ·	Delta Weight		8.65	57.85	500.47
		John Weight		0.00	20	



Item No.	Item	Mark if Option Installed	Weight (Pounds)	Arm (In.) Aft Datum	Moment (LbsIn.)
	(k) Optional Avionics Equipment - continued				
263.	GNS 430 GPS/Nav/Com (11-33 VDC) Dual with Stormscope, Skywatch and HSI Provisions, Piper Drawing 104480-6 a. Garmin GNS430 (11-33 VDC) #1 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229		6.56	58.138	381.18
	b. Garmin GNS430 (11-33 VDC) #2 with mount, connectors and data card,				
	Piper PS50040-40-4, Piper Code 601-229		6.56	58.138	381.18 234.96
	c. Cables/harnesses and hardware, Piper Drawing 104480-6 Removed Standard GNS 430 System Installation 104479-2		4.17 -8.48	56.32 57.53	-487.96
	Delta Wei	aht	8.80	57.86	509.37
	Della Wei	gnt	0.00	37.00	505.51
265.	GNS 430 GPS/Nav/Com, Dual with Stormscope, Skywatch, HSI and DME Provisions, Piper Drawing 104480-7 a. Garmin GNS430 #1 with mount, connectors and data card,		C 10	50.120	276.72
	Piper PS50040-40-1, Piper Code 601-214 b. Garmin GNS430 #2 with mount, connectors and data card,		6.48	58.138	376.73
	Piper PS50040-40-1, Piper Code 601-214		6.48	58.138	376.73
	c. Cables/harnesses and hardware, Piper Drawing 104480-7		4.38	56.30	246.58
	Removed Standard GNS 430 System Installation 104479-2		-8.48	57.53	-487.96
	Delta Wei	ght	8.86	57.81	512.09
267.	GNS 430 GPS/Nav/Com (11-33 VDC) Dual with Stormscope, Skywatch, HS and DME Provisions, Piper Drawing 104480-7 a. Garmin GNS430 (11-33 VDC) #1 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229 b. Garmin GNS430 (11-33 VDC) #2 with mount, connectors and data card, Piper PS50040-40-4, Piper Code 601-229 c. Cables/harnesses and hardware, Piper Drawing 104480-7		6.56 6.56 4.38	58.138 58.138 56.30	381.18 381.18 246.58
	Removed Standard GNS 430 System Installation 104479-2		-8.48	57.53	-487.96
	Delta Wei	ght	9.01	57.82	520.98
269.	Garmin GTX-327 Transponder Installation with AR-850, and Dual GPS, Piper Drawing 104438-003 a. Garmin GTX327 Transponder Unit 011-00490-10, Piper PS50040-12-12,				
	a. Gamin Connector/Rack Kit 011-00338-00, Piper PS50040-12-12, b. Garmin Connector/Rack Kit 011-00338-00, Piper PS50040-12-12,		2.90	59.24	171.79
	Piper Code 651-938		0.64	59.24	37.91
	c. Garmin Transponder Antenna 010-10160-00, Piper Code 683-724		0.21	55.11	11.57
	d. Harness, Backing plate, and Hardware, Piper Drawing 104438-003		1.47	52.63	77.20
	Removed Standard GTX 327 System Installation, Piper Drawing 104438-002		-4.85	57.63	-279.31
	Delta Wei		0.37	51.80	19.17



Item No.	Item	Mark if Option Installed	Weight (Pounds)	Arm (In.) Aft Datum	Moment (LbsIn.)
	(k) Optional Avionics Equipment - continued				
271.	Garmin GTX-327 Transponder Installation with AR-850, Dual GPS and Alt Preselect, Piper Drawing 104438-004 a. Garmin GTX327 Transponder Unit 011-00490-10, Piper PS50040-12-12, Piper Code 651-938 b. Garmin Connector/Rack Kit 011-00338-00, Piper PS50040-12-12, Piper Code 651-938 c. Garmin Transponder Antenna 010-10160-00, Piper Code 683-724 d. Harness, Backing Plate, and Hardware, Piper Drawing 104438-004 Removed Standard GTX 327 System Installation, Piper Drawing 104438-002 Delta Weight		2.90 0.64 0.21 1.36 -4.85 0.26	59.24 59.24 55.11 52.69 57.63 51.80	171.79 37.91 11.57 71.50 -279.31 13.47
273.	Garmin GTX-327 Transponder Installation with AR-850, GPS and Skywatch Provisions, Piper Drawing 104438-005 a. Garmin GTX327 Transponder Unit 011-00490-10, Piper PS50040-12-12, Piper Code 651-938 b. Garmin Connector/Rack Kit 011-00338-00, PS50040-12-12, Piper Code 651-938 c. Garmin Transponder Antenna 010-10160-00, Piper Code 683-724 d. Harness, Backing Plate, and Hardware, Piper Drawing 104438-004 Removed Standard GTX 327 System Installation, Piper Drawing 104438-002		2.90 0.64 0.21 1.35 -4.85	59.24 59.24 55.11 52.70 57.63	37.91 11.57 70.99 -279.31
	Delta Weight		0.25	51.80	12.95
275.	Garmin GTX-327 Transponder Installation with AR-850, Dual GPS and Skywatch Provisions, Piper Drawing 104438-006 a. Garmin GTX327 Transponder Unit 011-00490-10, Piper PS50040-12-12, Piper Code 651-938 b. Garmin Connector/Rack Kit 011-00338-00, Piper PS50040-12-12, Piper Code 651-938 c. Garmin Transponder Antenna 010-10160-00, Piper Code 683-724 d. Harness, Backing Plate, and Hardware, Piper Drawing 104438-006 Removed Standard GTX 327 System Installation, Piper Drawing 104438-002 Delta Weight		2.90 0.64 0.21 1.35 -4.85 0.25	59.24 59.24 55.11 52.70 57.63 51.80	171.79 37.91 11.57 70.99 -279.31 12.95



REVISED: 1/16/01

THE NEW PIPER AIRCRAFT, INC

(k) Optional Avionics Equipment - continued 277. Garmin GTX-327 Transponder Installation with AR-850, Dual GPS, Skywatch and All. Preselect Provisions, Piper Drawing 104438-007 a. Garmin GTX-327 Transponder Unit 011-00490-10, Piper PS50040-12-12, Piper Code 651-938 b. Garmin Connector/Rack Kit 011-00338-00, Piper PS50040-12-12, Piper Code 651-938 c. Garmin Transponder Antenna 010-10160-00, Piper PS50040-12-12, Piper Code 651-938 c. Garmin Transponder Antenna 010-10160-00, Piper Code 683-724 d. Harness, Backing Plate, and Hardware, Piper Drawing 104438-007 d. Harness, Backing Plate, and Hardware, Piper Drawing 104438-007 l. Ha 52.62 T.77.2 Removed Standard GTX 327 System Installation Piper Drawing 104438-002 a. WX-500 System (Istormscope, Piper Drawing 104448-002 a. WX-500 System (Istormscope, Piper Drawing 104448-002 a. WX-500 System (Istormscope, BF Goodrich 805-11500-001, Piper Code 601-225 1. WX-500 System (Istormscope Antenna, BF Goodrich 805-10930-001, Piper Code 601-225 3. WX-500 System (Stormscope Antenna Cable, BF Goodrich 810-11500-001, Piper Code 601-225 4. WX-500 Stormscope Antenna Cable, BF Goodrich 810-11500-001, Piper Code 601-227 b. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-002 a. WX-500 System (Istormscope System Installation Total Weight 281. System Installation WX-500 Stormscope with Skywatch Provisions, Piper Drawing 104484-003 a. WX-500 System (Istormscope System Installation Total Weight 281. System Installation WX-500 Stormscope with Skywatch Provisions, Piper Code 601-225 1. WX-500 System (Istormscope Antenna, BF Goodrich 805-11500-001, Piper Code 601-225 2. WX-500 System (Istormscope Antenna, BF Goodrich 805-11500-001, Piper Code 601-226 2. WX-500 Stormscope Processor, BF Goodrich 805-11500-001, Piper Code 601-227 3. WX-500 Stormscope Antenna, BF Goodrich 805-11500-001, Piper Code 601-226 3. WX-500 Stormscope Installation Kit, BF Goodrich 805-10930-001, Piper Code 601-227 3. WX-500 Stormscope Installation Kit, BF Goodrich 805-10930-001, Piper Code 601-227 3. WX-500 St	Item		Mark if	Weight	Arm (In.)	Moment
277. Garmin GTX-327 Transponder Installation with AR-850, Dual GPS, Skywatch and Alt. Preselect Provisions, Piper Drawing 104438-007 a. Garmin GTX327 Transponder Unit 011-00490-10, Piper PS50040-12-12, Piper Code 651-938 b. Garmin Connector/Rack Kit 011-00338-00, Piper PS50040-12-12, Piper Code 651-938 c. Garmin Transponder Antenna 010-10160-00, Piper Code 683-724 d. Harness, Backing Plate, and Hardware, Piper Drawing 104438-007 Removed Standard GTX 327 System Installation Piper Drawing 104438-002 a. WX-500 System (Stormscope), BF Goodrich 830-11500-001, Piper Code 661-225 1. WX-500 System (Stormscope Antenna, BF Goodrich 805-10930-001, Piper Code 633-728 3. WX-500 Stormscope Antenna Cable, BF Goodrich 817-11500-001, Piper Code 601-227 b. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-002 a. WX-500 Stormscope Processor, BF Goodrich 805-10950-004, Piper Code 601-227 b. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-002 b. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-002 c. WX-500 Stormscope Processor, BF Goodrich 805-10950-004, Piper Code 601-227 c. WX-500 Stormscope Installation Kit, BF Goodrich 805-10950-004, Piper Code 601-227 c. WX-500 Stormscope Bracket and Hardware, Piper Drawing 104484-002 c. WX-500 Stormscope Bracket and Hardware, Piper Drawing 104884-002 c. WX-500 Stormscope System Installation Total Weight c. System Installation WX-500 Stormscope, BF Goodrich 805-11500-001, Piper Code 601-225 c. WX-500 Stormscope Processor, BF Goodrich 805-11500-001, Piper Code 601-225 c. WX-500 Stormscope Processor, BF Goodrich 805-10930-001, Piper Code 601-225 c. WX-500 Stormscope Processor, BF Goodrich 805-10930-001, Piper Code 601-225 c. WX-500 Stormscope Processor, BF Goodrich 805-10930-001, Piper Code 601-225 c. WX-500 Stormscope Processor, BF Goodrich 805-10930-001, Piper Code 601-225 c. WX-500 Stormscope Processor, BF Goodrich 805-10930-001, Piper Code 601-225 c. WX-500 Stormscope Processor, BF Goodrich 805-10930-001, Piper Code 601-225 c. WX-500 Stormscope Processor, BF Go	No.	Item	Option Installed	(Pounds)	Aft Datum	(LbsIn.)
and Alt. Preselect Provisions, Piper Drawing 104438-007 a. Garmin GTX327 Transponder Unit 011-00490-10, Piper PS50040-12-12, Piper Code 651-938 b. Garmin Connector/Rack Kit 011-00338-00, Piper PS50040-12-12, Piper Code 651-938 c. Garmin Transponder Antenna 010-10160-00, Piper Code 683-724		(k) Optional Avionics Equipment - continued				
Piper Code 651-938	277.					
Piper Code 651-938 c. Garmin Transponder Antenna 010-10160-00, Piper Code 683-724		Piper Code 651-938		2.90	59.24	171.79
c. Garmin Transponder Antenna 010-10160-00, Piper Code 683-724 d. Harness, Backing Plate, and Hardware, Piper Drawing 104438-002 Removed Standard GTX 327 System Installation Piper Drawing 104438-002 Delta Weight 279. System Installation WX500 Stormscope, Piper Drawing 104484-002 a. WX-500 System (Stormscope), BF Goodrich 805-11500-001, Piper Code 601-225 1. WX-500 Stormscope Processor, BF Goodrich 805-11500-001, Piper Code 661-226 2. WX-500 NY163 Stormscope Antenna, BF Goodrich 803-10950-004, Piper Code 663-728 3. WX-500 Stormscope Installation Kit, BF Goodrich 817-11500-001, Piper Code 601-227 b. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-002 a. WX-500 Stormscope System Installation Total Weight 281. System Installation WX-500 Stormscope National BF Goodrich 805-11500-001, Piper Code 601-227 b. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-002 Piper Code 601-225 1. WX-500 Stormscope National BF Goodrich 805-11500-001, Piper Code 601-225 1. WX-500 Stormscope National BF Goodrich 805-11500-001, Piper Code 601-226 2. WX-500 Nyl63 Stormscope Antenna, BF Goodrich 805-11500-001, Piper Code 601-226 2. WX-500 Stormscope Processor, BF Goodrich 805-10930-004, Piper Code 663-728 3. WX-500 Stormscope Antenna, BF Goodrich 805-10930-004, Piper Code 663-688 4. WX-500 Stormscope Antenna, BF Goodrich 805-10930-004, Piper Code 663-688 4. WX-500 Stormscope Installation Kit, BF Goodrich 803-10950-004, Piper Code 663-688 4. WX-500 Stormscope Installation Kit, BF Goodrich 817-11500-001, Piper Code 601-227 b. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-003 1.152 1.153 1.39.67 2.12.28				0.64	59.24	37.91
Removed Standard GTX 327 System Installation Piper Drawing 104438-002 0.38 51.80 19.69				0.21	55.11	11.57
Delta Weight Delt		d. Harness, Backing Plate, and Hardware, Piper Drawing 104438-007		1.48	52.62	77.72
279. System Installation WX500 Stormscope, Piper Drawing 104484-002 a. WX-500 System (Stormscope), BF Goodrich 830-11500-001, Piper Code 601-225 1. WX-500 Stormscope Processor, BF Goodrich 805-11500-001, Piper Code 601-226 2. WX-500 NY163 Stormscope Antenna, BF Goodrich 805-10930-001, Piper Code 683-728 3. WX-500 Stormscope Antenna Cable, BF Goodrich 803-10950-004, Piper Code 653-688 4. WX-500 Stormscope Installation Kit, BF Goodrich 817-11500-001, Piper Code 601-227 b. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-002 281. System Installation WX-500 Stormscope with Skywatch Provisions, Piper Drawing 104484-003 a. WX-500 Stormscope Processor, BF Goodrich 805-11500-001, Piper Code 601-225 1. WX-500 Stormscope Processor, BF Goodrich 805-11500-001, Piper Code 601-225 2. WX-500 Stormscope Antenna, BF Goodrich 805-10930-001, Piper Code 601-226 2. WX-500 Stormscope Antenna Cable, BF Goodrich 803-10950-004, Piper Code 601-226 3. WX-500 Stormscope Antenna Cable, BF Goodrich 803-10950-004, Piper Code 601-226 2. WX-500 Stormscope Antenna Cable, BF Goodrich 803-10950-004, Piper Code 601-226 3. WX-500 Stormscope Installation Kit, BF Goodrich 817-11500-001, Piper Code 601-227 4. WX-500 Stormscope Installation Kit, BF Goodrich 817-11500-001, Piper Code 601-227 5. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-003 1. 1. 15 203.34 233.84 1. 206.00 165.83		Removed Standard GTX 327 System Installation Piper Drawing 104438-002		-4.85	57.63	-279.31
a. WX-500 System (Stormscope), BF Goodrich 830-11500-001, Piper Code 601-225 1. WX-500 Stormscope Processor, BF Goodrich 805-11500-001, Piper Code 601-226 2. WX-500 NY163 Stormscope Antenna, BF Goodrich 805-10930-001, Piper Code 683-728 3. WX-500 Stormscope Antenna Cable, BF Goodrich 803-10950-004, Piper Code 653-688 4. WX-500 Stormscope Installation Kit, BF Goodrich 817-11500-001, Piper Code 601-227 b. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-002 WX-500 Stormscope System Installation Total Weight 281. System Installation WX-500 Stormscope with Skywatch Provisions, Piper Code 601-225 1. WX-500 System (Stormscope), BF Goodrich 805-11500-001, Piper Code 601-225 1. WX-500 System (Stormscope Antenna, BF Goodrich 805-11930-001, Piper Code 601-226 2. WX-500 NY163 Stormscope Antenna, BF Goodrich 805-10930-001, Piper Code 663-728 3. WX-500 Stormscope Antenna Cable, BF Goodrich 803-10950-004, Piper Code 661-227 D. As 1 206.00 165.83 WX-500 Stormscope Installation Kit, BF Goodrich 817-11500-001, Piper Code 601-227 Piper Code 601-227 D. 1.15 203.34 233.84 b. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-003 1.52 139.67 212.28		Delta Weight		0.38	51.80	19.69
a. WX-500 System (Stormscope), BF Goodrich 830-11500-001, Piper Code 601-225 1. WX-500 Stormscope Processor, BF Goodrich 805-11500-001, Piper Code 601-226 2. WX-500 NY163 Stormscope Antenna, BF Goodrich 805-10930-001, Piper Code 683-728 3. WX-500 Stormscope Antenna Cable, BF Goodrich 803-10950-004, Piper Code 653-688 4. WX-500 Stormscope Installation Kit, BF Goodrich 817-11500-001, Piper Code 601-227 b. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-002 281. System Installation WX-500 Stormscope with Skywatch Provisions, Piper Code 601-225 1. WX-500 System (Stormscope), BF Goodrich 805-11500-001, Piper Code 601-226 2. WX-500 System (Stormscope Antenna, BF Goodrich 805-10930-001, Piper Code 601-226 2. WX-500 Ny163 Stormscope Antenna, BF Goodrich 805-10930-001, Piper Code 663-728 3. WX-500 Stormscope Antenna Cable, BF Goodrich 803-10950-004, Piper Code 661-227 4. WX-500 Stormscope Installation Kit, BF Goodrich 817-11500-001, Piper Code 601-227 b. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-003 1. 1. 1. 202.04 2. WX-500 Stormscope Installation Kit, BF Goodrich 803-10950-004, Piper Code 601-227 1. 1. 1. 203.34 2. 233.84 2. WX-500 Stormscope Installation Kit, BF Goodrich 817-11500-001, Piper Code 601-227 1. 1. 1. 203.34 2. 233.84 2. 233.84 2. 233.84 2. 233.84 2. 233.84 2. 233.84 2. 233.84 2. 233.84 2. 233.84 2. 233.84 2. 233.84 2. 233.84	270	System Installation WVS00 Stormscone Piper Drawing 104484-002				
1. WX-500 Stormscope Processor, BF Goodrich 805-11500-001, Piper Code 601-226 2. WX-500 NY163 Stormscope Antenna, BF Goodrich 805-10930-001, Piper Code 683-728 3. WX-500 Stormscope Antenna Cable, BF Goodrich 803-10950-004, Piper Code 653-688 4. WX-500 Stormscope Installation Kit, BF Goodrich 817-11500-001, Piper Code 601-227 b. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-002 WX500 Stormscope System Installation Total Weight 281. System Installation WX-500 Stormscope with Skywatch Provisions. Piper Drawing 104484-003 a. WX-500 System (Stormscope), BF Goodrich 805-11500-001, Piper Code 601-225 1. WX-500 Stormscope Processor, BF Goodrich 805-11500-001, Piper Code 601-226 2. WX-500 NY163 Stormscope Antenna, BF Goodrich 805-10930-001, Piper Code 683-728 3. WX-500 Stormscope Antenna Cable, BF Goodrich 803-10950-004, Piper Code 661-227 b. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-003 1.152 139.67 121.28	219.					
Piper Code 601-226 2. WX-500 NY163 Stormscope Antenna, BF Goodrich 805-10930-001, Piper Code 683-728 3. WX-500 Stormscope Antenna Cable, BF Goodrich 803-10950-004, Piper Code 653-688 4. WX-500 Stormscope Installation Kit, BF Goodrich 817-11500-001, Piper Code 601-227 b. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-002 WX-500 Stormscope System Installation Total Weight 281. System Installation WX-500 Stormscope with Skywatch Provisions, Piper Drawing 104484-003 a. WX-500 System (Stormscope), BF Goodrich 805-11500-001, Piper Code 601-225 1. WX-500 Stormscope Processor, BF Goodrich 805-11500-001, Piper Code 601-226 2. WX-500 NY163 Stormscope Antenna, BF Goodrich 805-10930-001, Piper Code 683-728 3. WX-500 Stormscope Antenna Cable, BF Goodrich 803-10950-004, Piper Code 653-688 4. WX-500 Stormscope Installation Kit, BF Goodrich 817-11500-001, Piper Code 601-227 b. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-003 1. 1.70 202.00 343.40 1.70 202.00 343.40 1.70 202.00 343.40 1.70 202.00 343.40 206.00 165.83						
2. WX-500 NY163 Stormscope Antenna, BF Goodrich 805-10930-001, Piper Code 683-728 3. WX-500 Stormscope Antenna Cable, BF Goodrich 803-10950-004, Piper Code 653-688 4. WX-500 Stormscope Installation Kit, BF Goodrich 817-11500-001, Piper Code 601-227 b. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-002 WX500 Stormscope System Installation Total Weight 281. System Installation WX-500 Stormscope with Skywatch Provisions, Piper Drawing 104484-003 a. WX-500 System (Stormscope), BF Goodrich 805-11500-001, Piper Code 601-225 1. WX-500 Stormscope Processor, BF Goodrich 805-11500-001, Piper Code 601-226 2. WX-500 NY163 Stormscope Antenna, BF Goodrich 805-10930-001, Piper Code 683-728 3. WX-500 Stormscope Antenna Cable, BF Goodrich 803-10950-004, Piper Code 653-688 4. WX-500 Stormscope Installation Kit, BF Goodrich 817-11500-001, Piper Code 601-227 □ 1.15 203.34 233.84 b. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-003 □ 1.52 139.67 212.28				1.70	202.00	242.40
Piper Code 683-728 3. WX-500 Stormscope Antenna Cable, BF Goodrich 803-10950-004, Piper Code 653-688 4. WX-500 Stormscope Installation Kit, BF Goodrich 817-11500-001, Piper Code 601-227 b. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-002				1.70	202.00	343.40
3. WX-500 Stormscope Antenna Cable, BF Goodrich 803-10950-004, Piper Code 653-688 4. WX-500 Stormscope Installation Kit, BF Goodrich 817-11500-001, Piper Code 601-227 b. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-002				0.81	206.00	165.83
Piper Code 653-688 4. WX-500 Stormscope Installation Kit, BF Goodrich 817-11500-001, Piper Code 601-227 b. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-002 WX500 Stormscope System Installation Total Weight 281. System Installation WX-500 Stormscope with Skywatch Provisions, Piper Drawing 104484-003 a. WX-500 System (Stormscope), BF Goodrich 830-11500-001, Piper Code 601-225 1. WX-500 Stormscope Processor, BF Goodrich 805-11500-001, Piper Code 601-226 2. WX-500 NY163 Stormscope Antenna, BF Goodrich 805-10930-001, Piper Code 683-728 3. WX-500 Stormscope Antenna Cable, BF Goodrich 803-10950-004, Piper Code 653-688 4. WX-500 Stormscope Installation Kit, BF Goodrich 817-11500-001, Piper Code 601-227 D.39 193.74 74.59 WX-500 Stormscope Installation Kit, BF Goodrich 817-11500-001, Piper Code 601-227 D.39 193.74 74.59 Labele, Harness, Bracket and Hardware, Piper Drawing 104484-003 D.39 193.74 233.84				0.61	200.00	105.65
4. WX-500 Stormscope Installation Kit, BF Goodrich 817-11500-001, Piper Code 601-227 b. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-002 WX500 Stormscope System Installation Total Weight 281. System Installation WX-500 Stormscope with Skywatch Provisions, Piper Drawing 104484-003 a. WX-500 System (Stormscope), BF Goodrich 830-11500-001, Piper Code 601-225 1. WX-500 Stormscope Processor, BF Goodrich 805-11500-001, Piper Code 601-226 2. WX-500 NY163 Stormscope Antenna, BF Goodrich 805-10930-001, Piper Code 683-728 3. WX-500 Stormscope Antenna Cable, BF Goodrich 803-10950-004, Piper Code 653-688 4. WX-500 Stormscope Installation Kit, BF Goodrich 817-11500-001, Piper Code 601-227 □ 1.15 203.34 233.84 b. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-003 □ 1.52 139.67 212.28			П	0.39	193.74	74.59
Piper Code 601-227 b. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-002						
WX500 Stormscope System Installation Total Weight 5.47 186.12 1018.08				1.15	203.34	
281. System Installation WX-500 Stormscope with Skywatch Provisions, Piper Drawing 104484-003 a. WX-500 System (Stormscope), BF Goodrich 830-11500-001, Piper Code 601-225 1. WX-500 Stormscope Processor, BF Goodrich 805-11500-001, Piper Code 601-226 2. WX-500 NY163 Stormscope Antenna, BF Goodrich 805-10930-001, Piper Code 683-728 3. WX-500 Stormscope Antenna Cable, BF Goodrich 803-10950-004, Piper Code 653-688 4. WX-500 Stormscope Installation Kit, BF Goodrich 817-11500-001, Piper Code 601-227		 Cable, Harness, Bracket and Hardware, Piper Drawing 104484-002 		1.43	140.15	
Piper Drawing 104484-003 a. WX-500 System (Stormscope), BF Goodrich 830-11500-001, Piper Code 601-225 1. WX-500 Stormscope Processor, BF Goodrich 805-11500-001, Piper Code 601-226 2. WX-500 NY163 Stormscope Antenna, BF Goodrich 805-10930-001, Piper Code 683-728 3. WX-500 Stormscope Antenna Cable, BF Goodrich 803-10950-004, Piper Code 653-688 4. WX-500 Stormscope Installation Kit, BF Goodrich 817-11500-001, Piper Code 601-227 5. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-003 1. 1. 15		WX500 Stormscope System Installation Total Weight	t	5.47	186.12	1018.08
Piper Drawing 104484-003 a. WX-500 System (Stormscope), BF Goodrich 830-11500-001, Piper Code 601-225 1. WX-500 Stormscope Processor, BF Goodrich 805-11500-001, Piper Code 601-226 2. WX-500 NY163 Stormscope Antenna, BF Goodrich 805-10930-001, Piper Code 683-728 3. WX-500 Stormscope Antenna Cable, BF Goodrich 803-10950-004, Piper Code 653-688 4. WX-500 Stormscope Installation Kit, BF Goodrich 817-11500-001, Piper Code 601-227 5. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-003 1. 1. 15						
Piper Code 601-225 1. WX-500 Stormscope Processor, BF Goodrich 805-11500-001, Piper Code 601-226 1.70 202.00 343.40 2. WX-500 NY163 Stormscope Antenna, BF Goodrich 805-10930-001, Piper Code 683-728 0.81 206.00 165.83 3. WX-500 Stormscope Antenna Cable, BF Goodrich 803-10950-004, Piper Code 653-688 0.39 193.74 74.59 4. WX-500 Stormscope Installation Kit, BF Goodrich 817-11500-001, Piper Code 601-227 1.15 203.34 233.84 b. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-003 1.52 139.67 212.28	281.					
1. WX-500 Stormscope Processor, BF Goodrich 805-11500-001, Piper Code 601-226						
2. WX-500 NY 163 Stormscope Antenna, BF Goodrich 805-10930-001, Piper Code 683-728						
Piper Code 683-728 0.81 206.00 165.83 3. WX-500 Stormscope Antenna Cable, BF Goodrich 803-10950-004, Piper Code 653-688 0.39 193.74 74.59 4. WX-500 Stormscope Installation Kit, BF Goodrich 817-11500-001, Piper Code 601-227 1.15 203.34 233.84 b. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-003 1.52 139.67 212.28				1.70	202.00	343.40
3. WX-500 Stormscope Antenna Cable, BF Goodrich 803-10950-004, Piper Code 653-688						
Piper Code 653-688 0.39 193.74 74.59 4. WX-500 Stormscope Installation Kit, BF Goodrich 817-11500-001, Piper Code 601-227 1.15 203.34 233.84 b. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-003 1.52 139.67 212.28				0.81	206.00	165.83
4. WX-500 Stormscope Installation Kit, BF Goodrich 817-11500-001, Piper Code 601-227				0.20	102.74	74.50
Piper Code 601-227 1.15 203.34 233.84 b. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-003 1.52 139.67 212.28				0.39	193.74	74.39
b. Cable, Harness, Bracket and Hardware, Piper Drawing 104484-003 1.52 139.67 212.28				1.15	203 34	233 84
······································			Н			
		WX500 Stormscope System with Skywatch Provisions Installation Total Weight		5.56	185.25	1029.95



PA-28-181, ARCHER III EQUIPMENT LIST S/N 2843415 and UP

Item No.	Item		Weight (Pounds)	Arm (In.) Aft Datum	Moment (LbsIn.)
	(k) Optional Avionics Equipment - continued				
283.	System Installation WX-500 Stormscope without Heading system, Piper Drawing 104484-004 a. WX-500 System (Stormscope), BF Goodrich 830-11500-001,				
	Piper Code 601-225 1. WX-500 Stormscope Processor, BF Goodrich 805-11500-001,		1.70	202.00	242.40
	Piper Code 601-226 2. WX-500 NY163 Stormscope Antenna, BF Goodrich 805-10930-001, Piper Code 683-728		0.81	202.00	343.40 165.83
	3. WX-500 Stormscope Antenna Cable, BF Goodrich 803-10950-004, Piper Code 653-688		0.39	193.74	74.59
	 WX-500 Stormscope Installation Kit, BF Goodrich 817-11500-001, Piper Code 601-227 Cable, Harness, Bracket and Hardware, Piper Drawing 104484-004 		1.15 1.52	203.34 139.66	233.84 212.29
	WX500 Stormscope System without Heading System Installation Total Weight		5.56	185.24	1029.96
285.	System Installation SKY 497 Skywatch, Piper Drawing 104486-002 a. SKY 497 System (Skywatch), Piper Drawing 72496-280 1. TRC-497 Transmitter/Receiver Computer (Skywatch), PIP Condition 905 10890 (2014) in the Manufactor Transmitter (Sp. 10870)				
	BF Goodrich 805-10800-001 with Mounting Tray Assembly 805-10870- 001, Piper Code 601-223		9.86	183.88	1813.09
	 TRC-497 Installation Kit, BF Goodrich 817-10800-003, Piper Code 601-224 TRC-497 NY164 Directional Antenna, BF Goodrich 805-10890-001, 		0.51	183.88	93.78
	Piper Code 683-726 4. TRC-497 NY 164 Directional Antenna Installation Kit.		2.31	116.50	269.12
	BF Goodrich 817-10009-006, Piper Code 683-727 b.) Cable, Harness, Bracket and Hardware, Piper Drawing 104486-002		0.76 4.68	116.50 130.81	87.96 611.80
	TRC-497 Skywatch System Installation Total Weight		18.11	158.77	2875.74
287.	System Installation SKY 497 Skywatch with WX-500 Stormscope Provisions, Piper Drawing 104486-003 a. SKY 497 System (Skywatch), Piper Drawing 72496-280				
	 TRC-497 Transmitter/Receiver Computer (Skywatch), BF Goodrich 805-10800-001 with Mounting Tray Assembly 805-10870- 001, Piper Code 601-223 	П	9.86	183.88	1813.09
	 TRC 497 Installation Kit, BF Goodrich 817-10800-003, Piper Code 601-224 		0.51	183.88	93.78
	3. TRC-497 NY164 Directional Antenna, BF Goodrich 805-10890-001, Piper Code 683-726		2.31	116.50	269.12
	4. TRC-497 NY164 Directional Antenna Installation Kit, BF Goodrich 817-10009-006, Piper Code 683-727	R	0.76 4.78	116.50 130.60	87.96 623.89
	 b. Cable, Harness, Bracket and Hardware, Piper Drawing 104486-003 TRC-497 Skywatch System with WX-500 Stormscope Provisions Installation Total Weight 		18.21	158.57	2887.83

REVISED: 1/16/01

240-0177 18 of 24



Item No.	Item	Mark if Option Installed	Weight (Pounds)	Arm (In.) Aft Datum	Moment (LbsIn.)
	(k) Optional Avionics Equipment - continued				
289.	System Installation SKY 497 Skywatch without Heading system, Piper Drawing 104486-004				
	a. SKY -497 System (Skywatch), Piper Drawing 72496-280				
	 TRC-497 Transmitter/Receiver Computer (Skywatch), BF Goodrich 805-10800-001 with Mounting Tray Assembly 805-10870- 				
	001, Piper Code Number 601-223		9.86	183.88	1813.09
	 TRC-497 Installation Kit, BF Goodrich 817-10800-003, Piper Code 601-224 	П	0.51	183.88	93.78
	3. TRC-497 NY164 Directional Antenna, BF Goodrich 805-10890-001,		0.51	105.00	75.70
	Piper Code 683-726		2.31	116.50	269.12
	 TRC-497 NY164 Directional Antenna Installation Kit, BF Goodrich 817-10009-006, Piper Code 683-727 	П	0.76	116.50	87.96
	b. Cable, Harness, Bracket and Hardware, Piper Drawing 104486-004		4.59	131.00	600.92
	TRC-497 Skywatch System Installation without Heading System Total Weight		18.02	158.96	2864.86
291.	Shelf Installation (Required with DME and WX-500 Stormscope options),				
271.	Piper Drawing 99466-026				
	a. Shelf assembly Piper Drawing 101253-004		1.10	201.60	220.85
293.	S-TEC Manual Electric Trim Installation, Piper Drawing 100831-2 a. S-TEC Trim Servo 0106-11-T6		2.90	113.90	330.31
	b. S-TEC Monitor/Sonalert Trim Monitor 01240	Н	0.30	57.50	17.25
	c. S-TEC Monitor/Sonalert, Sonalert 6551	ñ	0.10	58.18	5.82
	d. S-TEC Trim Servo Installation Kit-Hardware 90402-1		0.58	113.54	66.27
	e. S-TEC Trim Switch and Cable Installation Kit 90402-2		0.80	82.71	66.07
	f. S-TEC Monitor/Sonalert Installation Kit Hardware 90402-3		0.17	58.04	9.90
	g. Harnesses, Brackets and Hardware, Piper Drawing 100831-2		0.54	72.97	39.38
	h. Pilot S-TEC Trim And Mike Switch Assembly, Piper Drawing 101117-015		0.21	68.94	14.59
	Removed Pilot Mike Switch Assembly, Piper Drawing 101117-005		-0.09	68.94	-6.399
	Delta Weigh	t	5.51	98.56	543.19
295.	Audio Amp/Marker Installation with Autopilot, Piper Drawing 101193-2				
	a. Garmin GMA 340 Audio Selector Panel, Piper PS50040-15-25, Piper Code 601-210				
	Garmin 011-00401-10 GMA Audio Panel Marker/Receiver	\boxtimes	1.57	59.838	93.95
	2. Garmin 011-00403-00 Connector/Rack Kit	\boxtimes	0.17	59.838	10.17
	b. Harnesses, Brackets and Hardware, Piper Drawing 101193-2	\boxtimes	2.18	65.901	143.97
	Removed Standard Audio/Amp System Installation, Piper Drawing 101193-3		-3.93	63.210	-248.22
	Delta Weight	t	0.00	57.24	-0.13



Item No.	Item	Mark if Option Installed	Weight (Pounds)	Arm (In.) Aft Datum	Moment (LbsIn.)
	(k) Optional Avionics Equipment - continued				
297.	S-TEC ADF RCR-650A Installation, Piper Drawing 101195-2 a. S-TEC ADF Kit (RCR-650A), Piper PS50040-31-27, Piper Code 601-213				
	1. S-TEC Receiver RCR-650A 690108-P		2.44	58.04	141.61
	S-TEC Receiver Installation Kit 690212	\boxtimes	0.55	61.24	33.68
	3. S-TEC Indicator IND-650A 690113-P	\boxtimes	0.66	61.24	40.42
	4. S-TEC Indicator Installation Kit 690217	\boxtimes	0.18	61.24	11.02
	5. S-TEC Antenna ANT-650A 690124	\boxtimes	2.3	162.8	371.1
	6. S-TEC Antenna Installation Kit 690215	\boxtimes	0.0	161.8	3.2
	7. S-TEC Power Adapter 01255	\boxtimes	0.52	164.50	85.54
	b. Harness, Bracket and Hardware, Piper Drawing 101195-2	\boxtimes	3.22	89.90	289.83
	S-TEC ADF RCR-650A Installation Total Weight		9.87	98.89	976.43
299.	S-TEC ADF RCR 650D Installation, Piper Drawing 101195-3				
	a. S-TEC ADF Kit (RCR 650D), Piper PS50040-31-27, Piper Code 652-168				
	 S-TEC Receiver RCR 650D, p/n 690108-4 		2.484	58.04	144.17
	2. S-TEC Receiver Installation Kit, p/n 690212		0.55	61.238	33.6809
	3. S-TEC Indicator IND 650D, p/n 690113-P		0.66	61.238	40.4171
	4. S-TEC Indicator Installation Kit. p/n 690217		0.18	61.238	11.0228
	5. S-TEC Antenna ANT 650D, p/n 690124		2.28	162.76	371.093
	S-TEC Antenna Installation Kit, p/n 690215		0.02	161.78	3.2356
	7. S-TEC Power Adapter, p/n 01255		0.52	164.5	85.54
	b. Harness, Bracket and Hardware, Piper Drawing 101195-3		3.22	89.894	289.76
	S-TEC ADF RCR 650D Installation Total Weight		9.917	98.71	978.914
301.	S-TEC DME 451 with /450 Indicator Installation, Piper Drawing 101245-3 a. S-TEC DME Installation Kit, Piper PS50040-31-26, Piper Code 601-212				
	1.) S-TEC Transceiver TCR-451 690109	\boxtimes	2.71	57.19	154.98
	2.) S-TEC Transceiver Installation Kit 690224	\boxtimes	3.38	186.58	630.65
	3.) S-TEC Indicator IND-450 690111-P	\boxtimes	0.10	60.94	6.09
	4.) S-TEC Indicator Installation Kit 690221		0.38	104.059	39.54242
	5.) S-TEC Antenna ANT-451 690126	\boxtimes	0.08	62.94	5.04
	6.) S-TEC Antenna Installation Kit 690218	\boxtimes	0.63	58.94	37.13
	b.) Harness and Hardware, Piper Drawing 101245-3	\boxtimes	5.37	124.41	667.55
	S-TEC DME 451 with /450 Indicator Installation Total Weight		12.65	121.86	1540.99
202	Antenna Installation - Dual GPS and Com, Piper Drawing 101311-003				
303.			0.40	264.9	105.96
	a. NAV Receiving AV12-PPR Antenna, Piper Code 451-802	\boxtimes	0.862	169.431	146.025
	1. Nav Antenna Cable Assembly and Hardware, Piper Drawing 101311-003		0.002	107.431	170.023
	b. VHF Comm Comant CI-121 Antenna, Piper PS50040-18-2, Piper Code 596-664	\boxtimes	0.543	158.500	85.986



Item No.	Item	Mark if Option Installed	Weight (Pounds)	Arm (In.) Aft Datum	Moment (LbsIn.)
	(k) Optional Avionics Equipment - continued				
303.	Antenna Installation - Dual GPS and Com, Piper Drawing 101311-003 - continued				
	1. Comm #1 Antenna Cable Assembly and Hardware, Piper Drawing 101311-003 c. Comant CI-1125 Antenna Coupler, Piper Code 556-753 1. Antenna Coupler Hardware, Piper Drawing 101311-003 d. VHF Comm Antenna #2 Comant CI-122, Piper Code 683-725 1. Comm #2 Antenna Cable Assembly and Hardware, Piper Drawing 101311-003 e. Installation Hardware, Piper Drawing 101311-003		0.802 0.191 0.007 0.60 0.831 0.07	99.892 54.938 58.938 123.355 83.960 66.35	80.114 10.466 0.383 74.1 69.8 4.584
	f. GPS Antenna (Dual) Installation, Piper Drawing 101273-3				
	1. 010-10040-01 Antenna Kit #2 683-721 a. Garmin 011-00134-00 GA56 Antenna #2, Piper Code 683-721 b. Garmin 115-00031-00 Backing plate #2, Piper Code 683-721 2. Coax Cable #2, Piper Drawing 101266-004		0.24 0.09 0.50	96.26 96.26 77.98	23.29 8.47 38.99
	Removed Standard Antenna Installation - Single Com, Piper Drawing 101311-002		-2.84	151.85	-432.01
	Delta Weight		2.29	94.42	216.17
305.	Avionics Cooling Blower - 3 Port Installation With Dual GNS 430 and Without Autopilot, Piper Drawing 101318-2 a. Troll Avionics Icebox FN-200 PSV 4000020 Blower, Piper Code 460-110 b. Cable, Bracket and Hardware, Piper Drawing 101318-2 Removed Standard Avionics Cooling Blower Installation 101318-2 Delta Weight		1.07 0.78 -1.64 0.21	56.54 54.57 55.90 54.25	60.44 42.45 -91.44 11.44
307.	DC-AC Inverter Installation (Required with SKY-497 Skywatch and HSI and/or WX-500 Stormscope and HSI options) Piper Drawing 104490-002 a. DC-AC Inverter MD26-28, Piper Code 602-248 b. Cable, Harness, Bracket and Hardware, Piper Drawing 104490-002 DC-AC Inverter Installation Total Weight		0.471 0.36 0.83	160.167 113.08 139.69	75.358 40.94 116.30
309.	Pilot's Boom Mike Headset (Telex Airman 750) replaces standard Pilot's Headset 5161A Telex Airman 760				
	a. Pilot's Headset, Telex Airman 750, Piper Code 464-448		0.26	80.5	20.89
	 Removed Standard Pilot's Headset Telex 5161A Airman 760 Headset, Piper Code 692-205 Delta Weight 		-0.20 0.06	80.5 80.500	-16.34 4.55



Item No.	Item	Mark if Option Installed	Weight (Pounds)	Arm (In.) Aft Datum	Moment (LbsIn.)
	(I) Optional Instrumentation Equipment				
321.	Dual Altimeter Installation, Piper Drawing 85518-2 (Altimeter Piper PS50008-10-2D) Cert. Basis - TSO C10b		1.2	60.9	73.1
323.	Carburetor Ice Detector, Piper Drawing 85519-2		0.5	62.1	31.1
325.	Compass ST-180/HSI Installation without Autopilot Installation, Piper Drawing 101259-004 a. S-TEC 6443-PA Horizontal Situation Indicator b. S-TEC 6444 Remote Gyro c. S-TEC 01171-P Slaving Panel d. S-TEC 6446 Flux Sensor e. S-TEC 90480-1 Hardware Installation Kit f. Harnesses, Brackets and Hardware, Piper Drawing 101259-004 Compass ST-180/HSI Installation without Autopilot Installation Total Weight		2.900 3.400 0.100 0.300 0.630 5.37 12.70	57.19 186.58 60.94 104.06 58.94 124.41 121.477	165.85 634.39 6.09 31.22 37.13 667.55 1542.23
327.	Turn and Stip Indicator, Piper PS50030-2-4, replaces the standard Turn Coordinator, Piper PS50030-3-5 Turn and Slip Indicator, Piper PS50030-2-4 Removed Turn Coordinator, Piper PS50030-3-5, Cert. Basis TSO C3b Delta Weight		1.2 -1.2 0.0	59.7 59.7 59.7	71.6 -71.6 0.0
	(m) Cabin Interior (Optional)				
351.	All Leather Pilot Adjustable Seat with Headrest (lumbar support) replaces Standard Pilot Adjustable Seat with Cloth Pilot Adjustable Seat (leather) with Headrest and Lumbar Support, Piper Drawing 89026-2 Replace Pilot Adjustable Seat (cloth) with Headrest and Lumbar Support, Piper Drawing 89026-2 Delta Weight		24.96 -24.46 0.50	83.00 83.00 83.00	2071.68 -2030.18 41.50



Item No.	Item	Mark if Option Installed	Weight (Pounds)	Arm (In.) Aft Datum	Moment (LbsIn.)	
	(m) Cabin Interior (Optional) - continued					
353.	All Leather CoPilot Adjustable Seat with Headrest (lumbar support) replaces Standard CoPilot Adjustable Seat with Cloth CoPilot Adjustable Seat (leather) with Headrest and Lumbar Support,					
	Piper Drawing 89026-3 Replace CoPilot Adjustable Seat (cloth) with Headrest and Lumbar Support,		24.96	82.80	2066.69	
	Piper Drawing 89026-3 Delta Weigh	t	-24.46 0.50	82.80 82.80	-2025.29 41.40	
355.	All Leather Aft Right Seat with Headrest replaces Standard Aft Right Seat with Cloth					
	Aft Rear Seat (leather) (right) with Headrest, Piper Drawing 89027-3		16.19	123.00	1991.37	
	Replace Aft Rear Seat (cloth) (right) with Headrest, Piper Drawing 89027-3		-15.79	123.00	-1942.17	
	Delta Weigh	it	0.40	123.00	49.20	
357.	All Leather Aft Left Seat with Headrest replaces Standard Aft Left Seat with Cloth					
	Aft Rear Seat (leather) (left) with Headrest, Piper Drawing 89027-2		16.19	123.00	1991.37	-
	Replace Aft Rear Seat (cloth) (left) with Headrest, Piper Drawing 89027-2		-15.79	123.00	-1942.17	
	Delta Weigh	it	0.40	123.00	49.20	
	(n) Miscellaneous Optional Equipment					
371.			11.01	170.60	2140.7	
	a. Condenser Installation (Piper Drawing 99855-4)		11.91 4.60	179.69 179.94	827.7	
	b. Condenser-Heathcraft 979495 (Piper Code 552-250)c. Condenser Frame Assembly (Piper Drawing 99549-19)	H	3.34	182.15	608.4	
	d. Refrigerant Lines Installation (Piper Drawing 99576-7)	H	12.57	70.26	883.47	
	e. Electrical Installation (Piper Drawing 99979-9)		3.34	118.23	394.862	
	f. Compressor Installation (Piper Drawing 99109-12)		3.23	11.86	38.31	
	g. Air Conditioning Compressor Assembly Compressor, York EF209-25019, HFC134A with Pitts 14214 Clutch		21.83	13.61	297.15	
	h. Bulkhead Installation (Piper Drawing 78734-10) Evaporator Installation		3.87	172.79	668.80	
	Items i. Evaporator-Heathcraft C-6177 (Piper Code 552-201)	H	3.77	160.60	604.67	
	i. Evaporator-Heatheratt C-01/7 (Fiper Code 332-201) i. Blower Assembly, Piper Drawing 99642-4		3.90	174.72	681.42	
	k. Receiver-Dehydrator-AMA 37781 (Piper Code 602-275)	Ħ	1.36	168.01	228.49	
	Removed Standard Fresh Air Blower Installation,		(505)		-0746424400(0)	
	Piper Drawing 36983-17, Aft		-8.71	186.44	-1624.8	
	M. Removed Standard Cable Assembly, Piper Drawing 89402-2		-1.88	165.50	-310.48	
	Delta Weigh	ıt	63.13	165.15	5438.70	



PA-28-181, ARCHER III EQUIPMENT LIST S/N 2843415 and UP

Item		Mark if	Weight	Arm (In.)	Moment	
No.	Item	Option Installed	(Pounds)	Aft Datum	(LbsIn.)	
	(n) Miscellaneous Optional Equipment					
373.	Low Noise Exhaust Resonator Assembly replaces Standard Tail Pipe Assembly					
	Low Noise Muffler Assembly, Piper Drawing 85577-2		4.34	33.23	144.22	
	Standard Tail Pipe Assembly, Piper Drawing 85477-2		-1.60	33.23	-53.17	
	Delta Weight		2.74	33.23	91.05	
	END FACTORY INSTALLED OPTIONS					
	TOTAL OPTIONAL EQUIPMENT		<u>73.0</u>	102.2918	7467.3	
	END OF ORIGINAL EQUIPMENT INSTALLATION					

REVISED: 1/16/01

TABLE OF CONTENTS SECTION 7

DESCRIPTION AND OPERATION OF THE AIRPLANE AND ITS SYSTEMS

Parag No.	graph	Page No.
7.1	The Airplane	7-1
7.3	Airframe	7-1
7.5	Engine and Propeller	7-1
7.7	Landing Gear	7-3
7.9	Flight Controls	7-5
7.11	Engine Controls	7-7
7.13	Fuel System	7-7
7.15	Electrical System	7-9
7.17	Vacuum System	7-12
7.19	Instrument Panel	7-13
7.21	Pitot-Static System	7-18
7.23	Heating and Ventilating System	7-21
7.25	Cabin Features	7-21
7.27	Baggage Area	7-22
7.29	Stall Warning	7-22
7.31	Finish	7-23
7.33	Air Conditioning	7-23
7.35	External Power	7-24
7.37	Emergency Locator Transmitter	7-25
7.39	Carburetor Ice Detection System	7-27

REPORT: VB-1611

REVISED: APRIL 3, 1997

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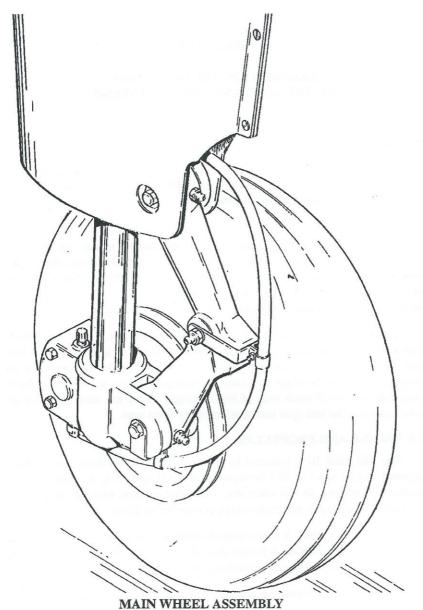


Figure 7-1 (Wheel fairing removed for clarity.)

REPORT: VB-1611

7.7 LANDING GEAR

The three landing gears use Cleveland 6.00×6 wheels, the main gear wheels (Figure 7-1) being provided with brake drums and Cleveland single disc hydraulic brake assemblies. All three wheels use 6.00×6 , four-ply rating, Type III tires with tubes.

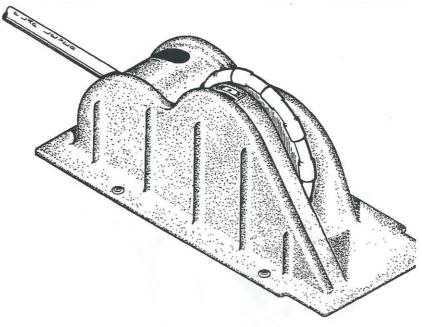
A spring device is incorporated in the rudder pedal torque tube assembly to provide rudder trim. A bungee in the nose gear steering mechanism reduces steering effort and dampens bumps and shocks during taxiing. By using the rudder pedals and brakes the nose gear is steerable through a 30 degree arc each side of center. Later aircraft have the bungee removed from the nose gear steering mechanism and are steerable through a 20 degree arc each side of center. A shimmy dampener is also included in the nose gear.

The three struts are of the air-oil type, with a normal extension of 3.25 inches for the nose gear and 4.50 inches for the main gear.

The standard brake system consists of dual toe brakes attached to the rudder pedals and a hand lever and master cylinder located below and behind the left center of the instrument sub-panel. The toe brakes and the hand brake have their own brake cylinders, but they share a common reservoir. The brake fluid reservoir is installed on the top left front face of the fire wall. The parking brake is incorporated in the master cylinder and is actuated by pulling back on the brake lever, depressing the knob attached to the left side of the handle, and releasing the brake lever. To release the parking brake, pull back on the brake lever to disengage the catch mechanism and allow the handle to swing forward (refer to Figure 7-5).

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REPORT: VB-1611 7-4



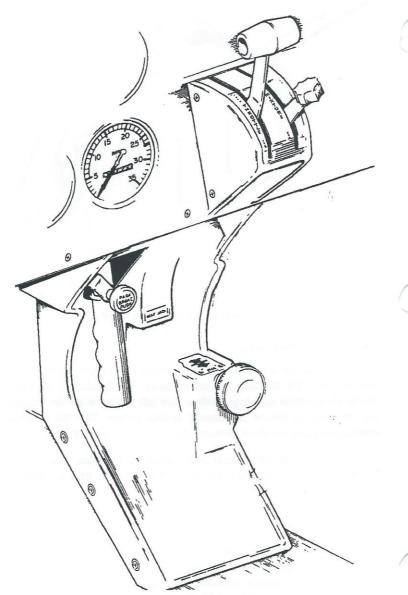
FLIGHT CONTROL CONSOLE
Figure 7-3

7.9 FLIGHT CONTROLS

Dual controls are provided as standard equipment, with a cable system used between the controls and the surfaces. The horizontal tail (stabilator) is of the all-movable slab type with a trim tab mounted on the trailing edge of the stabilator to reduce the control system forces. This tab is actuated by a control wheel on the floor between the front seats (Figure 7-3).

A rudder trim adjustment is mounted on the right side of the pedestal below the throttle quadrant and permits directional trim as needed in flight (refer to Figure 7-5).

The flaps are manually operated and spring-loaded to return to the up position. A past-center lock incorporated in the actuating linkage holds the flap when it is in the up position so that it may be used as a step on the right side. The flap will not support a step load except when in the full up position, so it must be completely retracted when used as a step. The flaps have three extended positions, 10, 25 and 40 degrees.



CONTROL QUADRANT AND CONSOLE Figure 7-5

REPORT: VB-1611

7.11 ENGINE CONTROLS

Engine controls consist of a throttle control and a mixture control lever. These controls are located on the control quadrant on the lower center of the instrument panel (Figure 7-5) where they are accessible to both the pilot and the copilot. The controls utilize teflon-lined control cables to reduce friction and binding.

The throttle lever is used to adjust engine RPM. The mixture control lever is used to adjust the air to fuel ratio. The engine is shut down by the placing of the mixture control lever in the full lean position. For information on the leaning procedure, see Section 4 of this Handbook.

The friction adjustment lever on the right side of the control quadrant may be adjusted to increase or decrease the friction holding the throttle and mixture controls or to lock the controls in a selected position.

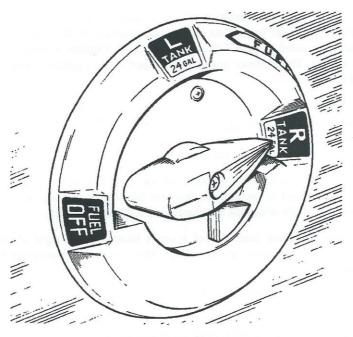
The carburetor heat control lever is located to the right of the control quadrant on the instrument panel. The control is placarded with two positions: "ON" (down), "OFF" (up).

7.13 FUEL SYSTEM

Fuel is stored in two twenty-five gallon (24 gallons usable) tanks which are secured to the leading edge structure of each wing by screws and nut plates. Each tank is equipped with a filler neck indicator tab to aid in determining fuel remaining when the tanks are not full. Usable capacity to the bottom of the indicator tab is 17 gallons.

The fuel selector control (Figure 7-7) is located on the left side-panel, forward of the pilot's seat. The button on the selector cover must be depressed and held while the handle is moved to the OFF position. The button releases automatically when the handle is moved back into the ON position.

An auxiliary electric fuel pump is provided in case of failure of the engine driven pump. The electric pump should be on for all takeoffs and landings, and when switching tanks. The pump switch is located in the switch panel above the throttle quadrant.



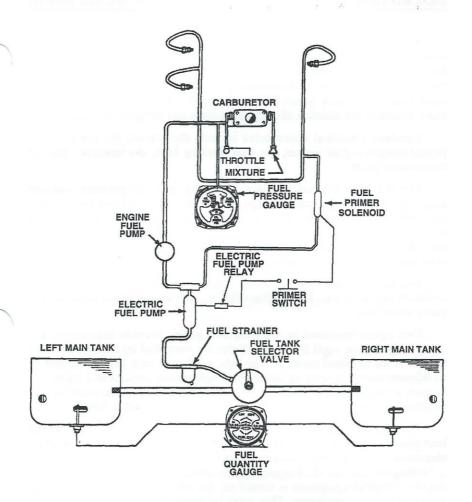
FUEL SELECTOR
Figure 7-7

The fuel drains should be opened daily prior to first flight to check for water or sediment and proper fuel. Each tank has an individual drain at the bottom, inboard rear corner.

A fuel strainer, located on the lower left front of the fire wall, has a drain which is accessible from outside the nose section. The strainer should also be drained before the first flight of the day. Refer to paragraph 8.21 for the complete fuel draining procedure.

A dual fuel quantity gauge is located in lower center of the instrument panel.

An electric engine priming system is provided to facilitate starting. The primer switch is located in the far left side of the overhead switch panel (refer to Figure 7-15A).



FUEL SYSTEM SCHEMATIC

Figure 7-9

7.15 ELECTRICAL SYSTEM

The 28-volt electrical system includes a 24-volt battery for starting and to back up alternator output. Electrical power is supplied by a 70 ampere alternator. The battery is mounted in a box on the battery shelf located in the aft fuselage A voltage regulator with integral overvoltage relay is located on the forward left side of the fuselage behind the instrument panel.

All powerplant and exterior lighting switches are grouped in a overhead switch panel, with all avionics switches grouped in a switch panel just above the throttle quadrant (figure 7-15). The circuit breaker panel is located on the lower right side of the instrument panel (figure 7-15). Each breaker is clearly marked to show which circuit it protects. Also, circuit provisions are made to handle the addition of communications and navigational equipment.

Standard electrical accessories include the starter, the electric fuel pump, electric engine primer, the stall warning horn, the ammeter, and the annunciator panel.

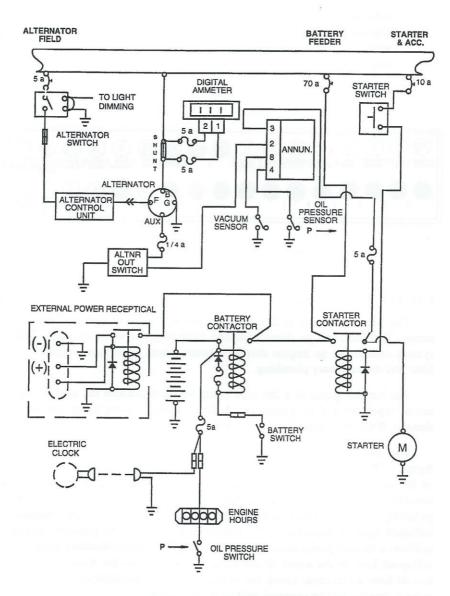
The annunciator panel includes, alternator inop, oil pressure, vacuum inop., low bus voltage, start engage, pitot heat and provisions for optional air conditioner door open. The annunciator panel lights are provided only as a warning to the pilot that a system may not be operating properly, and that the applicable system gauge should be checked and monitored to determine when or if any corrective action is required.

Standard electrical accessories include the navagation lights, anti collision strobe lights, landing/taxi lights, instrument panel lighting and cabin dome light.

Two lights, mounted in the overhead panel, provide instrument and cockpit lighting for night flying. The lights are controlled by rheostat switches located in the overhead panel. A map light window in each lens is actuated by an adjacent switch. A wing tip landing/taxi light system consists of 2 lights (one in each wing tip) and is operated by a rocker type switch mounted on the overhead switch panel. (Wing tip lights also used as recognition lights.)

The digital ammeter in the alternator system displays in amperes the load placed on the alternator. It does not indicate battery discharge. With all electrical equipment off (except the master switch) the ammeter will be indicating the amount of charging current demanded by the battery. As each item of electrical equipment is turned on, the current will increase to a total appearing on the ammeter. This total includes the battery. The average continuous load for night flight, with radios on, is about 32 amperes. This 32 ampere value, plus approximately 2 amperes for a fully charged battery, will appear continuously under these flight conditions.

WARNING Anti-collision lights should not be operating when flying through cloud, fog or haze, since the reflected light can produce spatial disorien-tation. Strobe lights should not be used in close proximity to the ground such as during taxiing, takeoff or landing.

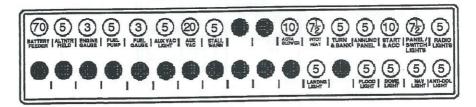


ALTERNATOR AND STARTER SCHEMATIC Figure 7-11

ISSUED: JULY 12, 1995

CAUTION: Do not use cigar lighter receptacles as power sources for any devices other than the cigar lighters supplied with the airplane. Any other device plugged into these receptacles may be damaged.

For abnormal and/or emergency operation and procedure, see Section 3.



CIRCUIT BREAKER PANEL

Figure 7-13

7.17 VACUUM SYSTEM

The vacuum system is designed to operate the air driven gyro instruments. This includes the directional and attitude gyros when installed. The system consists of an engine driven vacuum pump, a vacuum regulator, a filter and the necessary plumbing.

The vacuum pump is a dry type pump which eliminates the need for an air/oil separator and its plumbing. A shear drive protects the pump from damage. If the drive shears, the gyros will become inoperative.

The vacuum gauge, mounted on the left instrument panel (refer to figure 7-15), provides valuable information to the pilot about the operation of the vacuum system. A decrease in pressure in a system that has remained constant over an extended period may indicate a dirty filter, dirty screens, possibly a sticking vacuum regulator or leak in system (a low vacuum indicator light is provided in the annunciator panel). Zero pressure would indicate a sheared pump drive, defective pump, possibly a defective gauge or collapsed line. In the event of any gauge variation from the norm, the pilot should have a mechanic check the system to prevent possible damage to the system components or eventual failure of the system.

A vacuum regulator is provided in the system to protect the gyros. The valve is set so the normal vacuum reads 4.8 to 5.2 inches of mercury, a setting which provides sufficient vacuum to operate all the gyros at their rated RPM. Higher settings will damage the gyros and with a low setting the gyros will be unreliable. The regulator is located behind the instrument panel and is accessible from below the instrument panel.

7.19 INSTRUMENT PANEL

The instrument panel (Figure 7-15) is designed to accommodate the customary advanced flight instruments and the normally required powerplant instruments. The artificial horizon and directional gyro are vacuum operated and are located in the center of the left hand instrument panel. The vacuum gauge is located on the upper left hand instrument panel with the electric standby vacuum pump switch located directly below. The turn indicator the left side is electrically operated.

The radios are located in the center section of the panel, and the circuit breakers located in he lower right corner of the panel. All avionics switches plus pitot heat are grouped below the left radio stack.

Incorporated in the over head switch panel (7-15A) are all the engine related switches, grouped to the left of center, with exterior lighting switches grouped to the right of center.

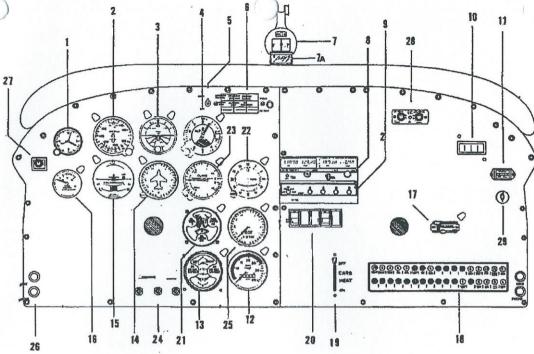
Eengine gauges are installed to the left of the throttle quadrant for monitoring engine operation. These gauges consist of a combination oil pressure, oil temperature and fuel pressure gauge, optional exhaust gas temperature (EGT), and a tachometer (RPM) gauge.

The normal operating range for ground and flight operation is indicated on the instruments by a green arc. Yellow arcs indicate either a takeoff or precautionary range. Red radial lines identity the established maximum or minimum limits. When an instrument needle point touches the edge of the red radial nearest the yellow or green arc; the limit is met.

ISSUED: JULY 12, 1995 REVISED: FEBRUARY 5, 2010

REPORT: VB-1611

7-13



INSTRUMENT PANEL
Figure 7-15

REPORT: VB-1611 7-14

ISSUED: JULY 12, 1995

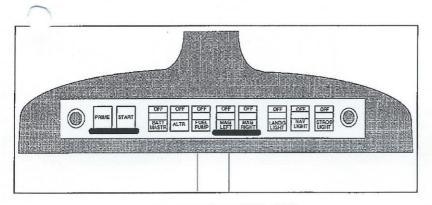
REPORT: VB-1611

PA-28-181, ARCHER III

1.	CLOCK
2.	AIRSPEED INDICATOR
3.	ATTITUDE GYRO
4.	ALTIMETER
5.	DAY/NIGHT SWITCH
6.	ANNUNCIATOR PANEL (with Press to Test)
7.	COMPASS (MAGNETIC)
7a.	COMPASS CORRECTION CARD
8.	COMM / NAV RADIO
9.	TRANSPONDER
10	AMMETER (DIGITAL)
11.	HOUR METER
12.	TACHOMETER (RPM)
13.	FUEL QUANTITY
14.	DIRECTIONAL GYRO
15.	TURN & BANK
16.	VACUUM GAUGE or Optional EGT (Exhaust Gas
	Temperature Gauge) when Garmin G500 installed.

- 17. CABIN AIR CONTROL
 WINDSHIELD DEFROST AND HEAT
- 18. CIRCUIT BREAKER PANEL
- 19. CARB HEAT
- 20. SWITCH PANEL (Avionics Pitot Heat)
- 21. ENGINE GAUGE, OIL TEMP
- OIL AND FUEL PRESSURE, .
- 22. VOR/LOC NAVIGATION INDICATOR
- 23. VERTICAL SPEED INDICATOR
- 24. LIGHT CONTROL AND DIMMING SWITCH, INST.PANEL, & RADIOS
- OPTIONAL EGT (Exhaust Gas Temprature Gauge) when Standard Instrument Package installed.
- 26. MIC/PHONE JACKS
- 27. ELT CONTROL
- 28. INTERCOM CONTROL
- 29 CIGAR LIGHTER

Typical VFR Panel



OVERHEAD SWITCH PANEL Figure 7-15A

Overhead switches: (left to right)

Left Panel Flood Light Control

Engine Primer

Engine Starter

Battery Master

Alternator

Fuel Pump

Left Magneto

Right Magneto

Landing Light / Taxi Light

Nav Light

Strobe Light

Right Panel Flood Light Control

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ISSUED: JULY 12, 1995

7.21 PITOT-STATIC SYSTEM

The system supplies both pitot and static pressure for the airspeed indicator, altimeter and the-vertical speed indicator (Figure 7-17).

Pitot and static pressure are picked up by a pitot head installed on the bottom of the left wing and carried through pitot and static lines within the wing and fuselage to the gauges on the instrument panel.

An alternate static source is standard equipment. The control valve is located below the left side of the instrument panel. When the valve is set in the alternate position, the altimeter, vertical speed indicator and airspeed indicator will be using cabin air for static pressure. The storm window and cabin vents must be closed and the cabin heater and defroster must be on during alternate static source operation. The altimeter error is less than 50 feet unless otherwise placarded.

Both the pitot and static lines can be drained through separate drain valves located on the left lower side of the fuselage interior.

A heated pitot head, which alleviates problems with icing and heavy rain, is standard equipment. The switch for the heated pitot head is located on the electrical switch panel above the throttle quadrant.

To prevent bugs and water from entering the pitot and static pressure holes, a cover should be placed over the pitot head. A partially or completely blocked pitot head will give erratic or zero readings on the instruments.

NOTE

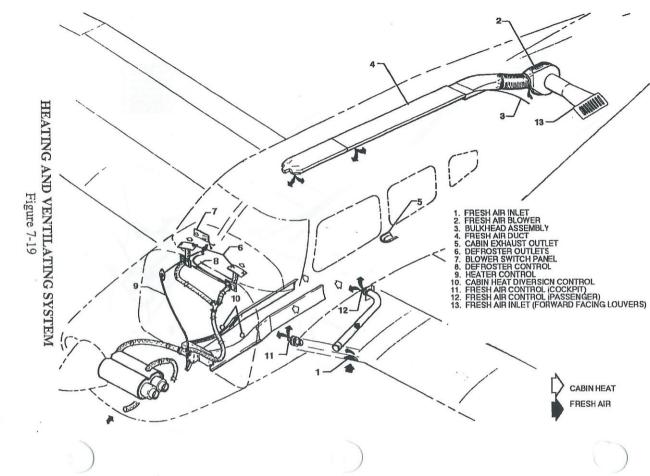
During the preflight, check to make sure the pitot cover is removed.

PITOT-STATIC SYSTEM Figure 7-17

DESCRIPTION & OPERATION SECTION 7

PA-28-181, ARCHER III

REPORT: VB-1611 7-19



7.23 HEATING AND VENTILATING SYSTEM

Heat for the cabin interior and the defroster system is provided by a heater muff attached to the exhaust system (Figure 7-19). The amount of heat desired can be regulated with the controls located on the far right side of the instrument panel.

The air flow can be regulated between the front and rear seats by levers located on top of the heat ducts next to the console.

Fresh air inlets are located in the leading edge of the wing near the fuselage. An adjustable outlet is located on the side of the cabin near the floor at each seat location; overhead air outlets are offered as optional equipment. Air is exhausted through an outlet under the rear seat. A cabin air blower, incorporated in the ventilating system, is also available as optional equipment. An optional overhead ventilating system with a cabin air blower is available on models without air conditioning. This blower is operated by a FAN switch with 3 positions - "OFF," "LOW," "HIGH."

CAUTION

When cabin heat is operated, heat duct surface becomes hot. This could result in burns if arms or legs are placed too close to heat duct outlets or surface.

7.25 CABIN FEATURES

For ease of entry and exit and pilot-passenger comfort, the front seats are adjustable fore and aft. The rear seats may be removed to provide room for bulky items. Rear seat installations incorporate leg retainers with latching mechanisms which must be released before the rear seats can be removed. Releasing the retainers is accomplished on by depressing the plunger behind each rear leg. Armrests are also provided for the front seats. All seats are available with optional headrests and optional vertical adjustment may be added to the front seats.

A cabin interior includes a pilot storm window, two sun visors, ash trays, two map pockets, and pockets on the backs of each front seat.

Shoulder harnesses with inertia reels are provided as standard equipment for the occupants of both front and rear seats. A check of the inertia reel mechanism can be made by pulling sharply on the strap and checking that the reel will lock in place under sudden stress. This locking feature prevents the strap from extending, and holds the occupant in place. Under normal movement the strap will extend and retract as required. The shoulder strap is routed over the shoulder adjacent to the windows and attached to the lap belt in the general area of the person's inboard hip. Adjust this fixed strap so that all controls are accessible while maintaining adequate restraint for the occupant. Shoulder harnesses should be routinely worn during takeoff, landing, turbulent air, and whenever an inflight emergency situation occurs.

7.27 BAGGAGE AREA

A 24 cubic foot baggage area, located behind the rear seats, is accessible either from the cabin or through an outside baggage door on the right side of the aircraft. Maximum capacity is 200 pounds. Tie-down straps are provided and should be used at all times.

NOTE

It is the pilot's responsibility to be sure when the baggage is loaded that the aircraft C.G. falls within the allowable C.G. Range (refer to Section 6 - Weight and Balance).

7.29 STALL WARNING

An approaching stall is indicated by a stall warning horn which is activated between five and ten knots above stall speed. Mild airframe buffeting and gentle pitching may also precede the stall. Stall speeds are shown on graphs in the Performance Section. The stall warning horn emits a continuous sound and is activated by a lift detector installed on the leading edge of the left wing. During preflight, the stall warning system should be checked by turning the master switch ON, lifting the detector and checking to determine if the horn is actuated.

7.31 FINISH

All exterior surfaces are primed with etching primer and finished with a polyurethane finish.

7.33 AIR CONDITIONING*

The air conditioning system is a recirculating air system. The major items include: evaporator, condenser, compressor, blower, switches and temperature controls.

The evaporator is located behind the left rear side of the baggage compartment. This cools the air that is used for air conditioning.

The condenser is mounted on a retractable scoop located on the bottom of the fuselage and to the rear of the baggage compartment area. The scoop extends when the air conditioner is ON and retracts to a flush position when the system is OFF.

The compressor is mounted on the forward right underside of the engine. It has an electric clutch which automatically engages or disengages the compressor to the belt drive system of the compressor.

An electrical blower is mounted on the aft side of the rear cabin panel. Air from the baggage area is drawn through the evaporator by the blower and distributed through an overhead duct to individual outlets located adjacent to each occupant.

The switches and temperature control are located on the lower right side of the instrument panel in the climate control center panel. The temperature control regulates the desired temperature of the cabin. Turn the control clockwise for increased cooling, counterclockwise for decreased cooling.

*Optional equipment

ISSUED: JULY 12, 1995

Located inboard of the temperature control is the fan speed switch and the air conditioning ON-OFF switch. The fan can be operated independently of the air conditioning. However, it must be on for air conditioner operation. Turning either switch off will disengage the compressor clutch and retract the condenser door. Cooling air should be felt within one minute after the air conditioner is turned on.

NOTE

If the system is not operating in 5 minutes, turn the system OFF until the fault is corrected.

The FAN switch allows operation of the fan with the air conditioner turned OFF to aid cabin air circulation if desired. A LOW or HIGH flow of air can be selected to the air conditioner outlets located in the overhead duct. The outlets can be adjusted or turned off by each occupant to regulate individual cooling effect.

The "DOOR OPEN" indicator light is located in the annunciator panel. The light illuminates whenever the condenser door is open and remains on until the door is closed.

A circuit breaker located on the circuit breaker panel protects the air conditioning electrical system.

Whenever the throttle is in the full throttle position, it actuates a micro switch which disengages the compressor and retracts the scoop. This is done to obtain maximum power and maximum rate of climb. The fan continues to operate and the air will remain cool for approximately one minute. When the throttle is retarded approximately 1/4 inch, the clutch will engage and the scoop will extend, again supplying cool, dry air.

7.35 EXTERNAL POWER

An external power installation is accessible through a receptacle located on the right side of the fuselage aft of the wing. An external battery can be connected to the socket, thus allowing the operator to crank the engine without having to gain access to the airplane's battery.

ISSUED: JULY 12, 1995

7.37 EMERGENCY LOCATOR TRANSMITTER*

The Emergency Locator Transmitter (ELT), is located in the aft portion of the fuselage just below the stabilator leading edge and is accessible through a plate on the right side of the fuselage. This plate is attached with slotted-head nylon screws for ease of removal; these screws may be readily removed with a variety of common items such as a dime, a key, a knife blade, etc. If there are no tools available in an emergency the screw heads may be broken off by any means.

A battery replacement date is marked on the transmitter to comply with FAA regulations, the battery must be replaced on or before this date. The battery must also be replaced if the transmitter has been used in an emergency situation or if the accumulated test time exceeds one hour, or if the unit has been inadvertently activated for an undetermined time period.

NOTE

If for any reason a test transmission is necessary, the test transmission should be conducted only in the first five minutes of any hour and limited to three audio sweeps. If the tests must be made at any other time, the tests should be coordinated with the nearest FAA tower or flight service station.

*Optional equipment

TEX ELT OPERATION

On the ELT unit itself is a two position switch placarded ON and OFF. The OFF position is selected when the transmitter is installed at the factory and the switch should remain in that position whenever the unit is installed in the airplane.

A pilots remote switch, placarded ON and ARM is located on the left hand side of the pilot's instrument panel to allow the transmitter to be armed or turned on from inside the cabin. The switch is normally in ARM position. Moving the switch to ON will activate the transmitter. A warning light located above the remote switch will alert you when ever the ELT is activated.

The ME-406 ELT (406 MHz), if installed, is equipped with a warning buzzer. This warning buzzer, which receives power from the ELT itself, is mounted in the tailcone. When the ELT is activated the buzzer "beeps" periodically. The time between pulses lengthens after a predetermined transmitter "ON" time. The buzzer is loud enough to be heard from outside the aircraft when the engine is not running.

Should the ELT be activated inadvertently it can be reset by either partioning the remote switch to the ON then immediately relocating it to the I position, or by setting the switch on the ELT to ON and then back to OFF.

In the event the transmitter is activated by an impact, it can be turned off by moving the switch on the ELT to ON and then back to OFF. Normal operation can then be restored by resetting the switch to ARM. It may also be turned off and reset by positioning the remote switch to the ON and then immediately to the ARM position.

The transmitter can be activated manually at any time by placing either the remote switch or the ELT switch to the ON position.

NOTE:

Three sweeps of the emergency tone and an illuminated warning light indicates a normally functioning unit. The warning light must illuminate during the first 3 second test period. If it does not illuminate, a problem is indicated such as a "G" switch failure.

The ELT should be checked during postflight to make certain the unit has not been activated. Check by selecting 121.50 MHz on an operating receiver. It lownward sweeping audio tone is heard the ELT may have been activated. The remote switch to ON. If there is no change in the volume of the signal, your airplane's ELT is probably transmitting. Setting the remote switch back to OFF will automatically reset the ELT and should stop the signal being received on 121.50 MHz.

REPORT: VB-1611

7-26

ISSUED: JULY 12, 1995 REVISED: JULY 29, 2010

7.39 *CARBURETOR ICE DETECTION SYSTEM

A carburetor ice detection system is available as optional equipment.

The system consists of a control box mounted on the instrument panel, a probe sensor mounted in the carburetor and a red warning light to indicate the presence of ice in the carburetor. If ice is present apply full carburetor heat. Refer to Carburetor Icing, Section 3, Emergency Procedures. To adjust the system for critical ice detection, first turn on the airplanes master switch and then turn on the ice detection unit. Turn the sensitivity knob fully counterclockwise causing the carb. ice light to come on. Now rotate the sensitivity knob back (clockwise) until the ice light just goes out. This establishes the critical setting.

WARNING

This instrument is approved as optional equipment only and Flight Operations should not be predicated on its use.

ISSUED: JULY 12, 1995 REVISED: APRIL 3, 1997 REPORT: VB-1611

7-27

^{*}Optional equipment

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REPORT: VB-1611

7-28

ISSUED: JULY 12, 1995 REVISED: APRIL 3, 1997

TABLE OF CONTENTS SECTION 8

AIRPLANE HANDLING, SERVICING AND MAINTENANCE

Parag No.	graph	Page No.
8.1	General	8-1
8.3	Airplane Inspection Periods	8-2
8.5	Preventive Maintenance	8-3
8.7	Airplane Alterations	8-4
8.9	Ground Handling	8-5
8.11	Engine Air Filter	8-8
8.13	Brake Service	8-8
8.15	Landing Gear Service	8-10
8.17	Propeller Service	8-11
8.19	Oil Requirements	8-12
8.21	Fuel System	8-12
8.23	Tire Inflation	8-16
8.25	Battery Service	8-16
8.27	Cleaning	8-17
8.29	Cold Weather Operation	8-20

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8.1 GENERAL (CONTINUED)

Every owner should stay in close contact with an authorized Piper Service Center or Piper's Customer Service Department to obtain the latest information pertaining to their airplane, and to avail themselves of Piper's support systems.

Piper takes a continuing interest in having owners get the most efficient use from their airplane and keeping it in the best mechanical condition. Consequently, Piper, from time to time, issues service releases including Service Bulletins, Service Letters, Service Spares Letters, and others relating to the airplane.

Piper Service Bulletins are of special importance and Piper considers compliance mandatory. These are available on the Piper.com website. Depending on the nature of the release, material and labor allowances may apply. This information is provided to all authorized Piper Service Centers.

Service Letters deal with product improvements and servicing techniques pertaining to the airplane. They are available on the Piper.com website. Owners should give careful attention to Service Letter information.

Service Spares Letters offer improved parts, kits, and optional equipment which were not available originally, and which may be of interest to the owner.

Maintenance manuals, parts catalogs, and revisions to both, are available from Piper Service Centers.

Any correspondence regarding the airplane should include the airplane model and serial number to ensure proper response.

ISSUED: JULY 12, 1995 REVISED: June 15, 2009

REPORT: VB-1611 8-1b

8. AIRPLANE INSPECTION PERIODS

WARNING

All inspection intervals, replacement time limits, overhaul time limits, the method of inspection, life limits, cycle limits, etc., recommended by PIPER are solely based on the use of new, remanufactured or overhauled PIPER approved parts. If parts are designed, manufactured, remanufactured, overhauled and/or approved by entities other than PIPER, then the data in PIPER'S maintenance/service manuals and parts catalogs are no longer applicable and the purchaser is warned not to rely on such data for non-PIPER parts. All inspection intervals, replacement time limits, overhaul time limits, the method of inspection, life limits, cycle limits, etc., for such non-PIPER parts must be obtained from the manufacturer and/or seller of such non-PIPER parts.

Piper has developed inspection items and required inspection intervals for the PA-28-181 (see the latest revision of the PA-28-181 Maintenance and In ion Manuals). The PA-28-181 Inspection Manual contains appropriate forms, and all inspection procedures should be complied with by a properly trained, knowledgeable, and qualified mechanic at a Piper Authorized Service Center or a reputable repair shop. Piper cannot accept responsibility for the continued airworthiness of any aircraft not maintained to these standards, and/or not brought into compliance with applicable Service Bulletins issued by Piper, instructions issued by the engine, propeller, or accessory manufacturers, or Airworthiness Directives issued by the FAA.

A programmed Inspection, approved by the Federal Aviation Administration (FAA), is also available to the owner. This involves routine and detailed inspections to allow maximum utilization of the airplane. Maintenance inspection costs are reduced, and the maximum standard of continued airworthiness is maintained. Complete details are available from Piper.

In addition, but in conjunction with the above, the FAA requires periodic inspections on all aircraft to keep the Airworthiness Certificate in effect. The owner is responsible for assuring compliance with these inspection requirements ar maintaining proper documentation in logbooks and/or maintenance records.

A spectrographic analysis of the engine oil is available from several sources. This inspection, if performed properly, provides a good check of the internal condition of the engine. To be accurate, induction air filters must be cleaned or changed regularly, and oil samples must be taken and sent in at regular intervals.

8.5 PREVENTIVE MAINTENANCE

The holder of a pilot certificate issued under Federal Aviation Regulations (FAR) Part 61 may perform certain preventive maintenance as defined in the FARs. This maintenance may be performed only on an aircraft which the pilot owns and operates, and which is not used in air carrier or air taxi/commercial operations service.

All other maintenance must be accomplished by a person or facility appropriately certificated by the Federal Aviation Administration (FAA) to perform that work.

Anytime maintenance is accomplished, an entry must be made in the appropriate aircraft maintenance records. The entry shall include:

- (a) The date the work was accomplished.
- (b) Description of the work.
- (c) Number of hours on the aircraft.
- (d) The certificate number of pilot performing the work.
- (e) Signature of the individual doing the work.

8.7 AIRPLANE ALTERATIONS

If the owner desires to have his aircraft modified, he must obtain FAA approval for the alteration. Major alterations accomplished in accordance with Advisory Circular 43.13-2, when performed by an A & P mechanic, may be approved by the local FAA office. Major alterations to the basic airframe or systems not covered by AC 43.13-2 require a Supplemental Type Certificate.

The owner or pilot is required to ascertain that the following Aircraft Papers are in order and in the aircraft.

- (a) To be displayed in the aircraft at all times:
 - (1) Aircraft Airworthiness Certificate Form FAA-8100-2.
 - (2) Aircraft Registration Certificate Form FAA-8050-3.
 - (3) Aircraft Radio Station License if transmitters are installed.
- (b) To be carried in the aircraft at all times:
 - (1) Pilot's Operating Handbook.
 - (2) Weight and Balance data plus a copy of the latest Repair and Alteration Form FAA-337, if applicable.
 - (3) Aircraft equipment list.

Although the aircraft and engine logbooks are not required to be in the aircraft, they should be made available upon request. Logbooks should be complete and up to date. Good records will reduce maintenance cost by giving the mechanic information about what has or has not been accomplished.

8.9 GROUND HANDLING

(a) Towing

The airplane may be moved on the ground by the use of the nose wheel steering bar that is stowed below the forward ledge of the baggage compartment or by power equipment that will not damage or excessively strain the nose gear steering assembly. Towing lugs are incorporated as part of the nose gear fork.

CAUTION

When towing with power equipment, do not turn the nose gear beyond its steering radius in either direction, as this will result in damage to the nose gear and steering mechanism.

CAUTION

Do not tow the airplane when the controls are secured.

In the event towing lines are necessary, ropes should be attached to both main gear struts as high up on the tubes as possible. Lines should be long enough to clear the nose and/or tail by not less than fifteen feet, and a qualified person should ride in the pilot's seat to maintain control by use of the brakes.

(b) Taxiing

Before attempting to taxi the airplane, ground personnel should be instructed and approved by a qualified person authorized by the owner. Engine starting and shut-down procedures as well as taxi techniques should be covered. When it is ascertained that the propeller back blast and taxi areas are clear, power should be applied to start the taxi roll, and the following checks should be performed:

- (1) Taxi a few feet forward and apply the brakes to determine their effectiveness.
- (2) While taxiing, make slight turns to ascertain the effectiveness of the steering.
- (3) Observe wing clearance when taxiing near buildings or other stationary objects. If possible, station an observer outside the airplane.
- (4) When taxiing over uneven ground, avoid holes and ruts.
- (5) Do not operate the engine at high RPM when running up or taxiing over ground containing loose stones, gravel, or any loose material that may cause damage to the propeller blades.

(c) Parking

When parking the airplane, be sure that it is sufficiently protected from adverse weather conditions and that it presents no danger to other aircraft. When parking the airplane for any length of time or overnight, it is suggested that it be moored securely.

- (1) To park the airplane, head it into the wind if possible.
- (2) Set the parking brake by pulling back on the brake lever and depressing the knob on the handle. To release the parking brake, pull back on the handle until the catch disengages; then allow the handle to swing forward.

CAUTION

Care should be taken when setting brakes that are overheated or during cold weather when accumulated moisture may freeze a brake. (3) Aileron and stabilator controls should be secured with the front seat belt and chocks used to properly block the wheels.

(d) Mooring

The airplane should be moored for immovability, security and protection. The following procedures should be used for the proper mooring of the airplane:

- (1) Head the airplane into the wind if possible.
- (2) Retract the flaps.
- (3) Immobilize the ailerons and stabilator by looping the seat belt through the control wheel and pulling it snug.
- (4) Block the wheels.
- (5) Secure tie-down ropes to the wing tie-down rings and to the tail skid at approximately 45 degree angles to the ground. When using rope of non-synthetic material, leave sufficient slack to avoid damage to the airplane should the ropes contract.

CAUTION

Use bowline knots, square knots or locked slip knots. Do not use plain slip knots.

NOTE

Additional preparations for high winds include using tie-down ropes from the landing gear forks and securing the rudder.

- (6) Install a pitot head cover if available. Be sure to remove the pitot head cover before flight.
- (7) Cabin and baggage doors should be locked when the airplane is unattended.

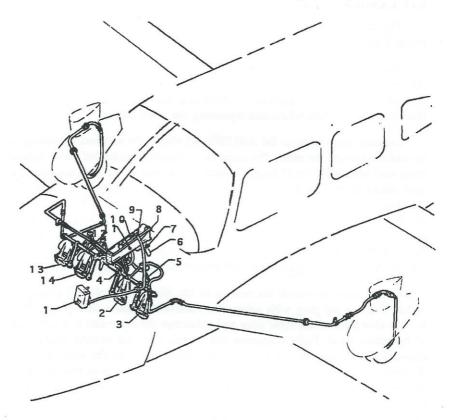
8.11 ENGINE AIR FILTER

Inspect inlet for foreign particles and obstructions. Engine Air Filshould be removed and inspected or replaced at intervals as outlined in aircraft Maintenance Manual. Operations in sever environments may require more frequent attention.

8.13 BRAKE SERVICE

The brake system is filled with MIL-H-5606 (petroleum base) hydraulic brake fluid. The fluid level should be checked periodically or at every 50-hour inspection and replenished when necessary. The brake reservoir is located on the fire wall in the engine compartment. If the entire system must be refilled, fill with fluid under pressure from the brake end of the system. This will eliminate air from the system.

No adjustment of the brake clearances is necessary. If after extended service brake blocks become excessively worn, they should be replaced with new segments.



- 1. BRAKE RESERVOIR
- 2. RIGHT BRAKE AND RUDDER PEDAL
- 3. LEFT BRAKE AND RUDDER PEDAL
- 4. RIGHT BRAKE CYLINDER
- 5. LEFT BRAKE CYLINDER
- 6. BRAKE HANDLE
- 7. HANDLE RELEASE BUTTON
- 8. LINE, INLET
- 9. CLEVIS PIN
- 10. MASTER CYLINDER ASSEMBLY
- 11. BOLT ASSEMBLY
- 12. TORQUE TUBE
- 13. COPILOTS RIGHT BRAKE AND RUDDER PEDAL
- 14. COPILOT'S LEFT BRAKE AND RUDDER PEDAL

BRAKE SYSTEM

Figure 8-1

ISSUED: JULY 12, 1995

REPORT: VB-1611

8.15 LANDING GEAR SERVICE

The three landing gears use Cleveland Aircraft Products 6.00 x 6, four-ply rating, type III tires with tubes. (Refer to paragraph 8.23).

Wheels are removed by taking off the hub cap, cotter pin, axle nut, and the two bolts holding the brake segment in place. Mark tire and wheel for reinstallation; then dismount by deflating the tire, removing the three through-bolts from the wheel and separating the wheel halves.

Landing gear oleos on the ARCHER III should be serviced according to the instructions on the units. The main oleos should be extended under normal static load until 4.50 ± 0.25 inches of oleo piston tube is exposed, and the nose gear should show 3.25 ± 0.25 inches. Should the strut exposure be below that required, it should be determined whether air or oil is required by first raising the airplane on jacks. Depress the valve core to allow air to escape from the strut housing chamber. Remove the filler plug and slowly raise the strut to full compression. If the strut has sufficient fluid, it will be visible up to the bottom of the filler plug hole and will then require only proper inflation.

Should fluid be below the bottom of the filler plug hole, oil should be added. Replace the plug with valve core removed; attach a clear plastic hose to the valve stem of the filler plug and submerge the other end in a container of hydraulic fluid. Fully compress and extend the strut several times, thus drawing fluid from the container and expelling air from the strut chamber. To allow fluid to enter the bottom chamber of the main gear strut housing, the torque link assembly must be disconnected to let the strut be extended a minimum of 10 inches (the nose gear torque links need not be disconnected). Do not allow the strut to extend more than 12 inches. When air bubbles cease to flow through the hose, compress the strut fully and again check fluid level. Reinstall the valve core and filler plug, and the main gear torque links, if disconnected.

With fluid in the strut housing at the correct level, attach a strut pump to the air valve and with the airplane on the ground, inflate the oleo strut to the correct height. In jacking the aircraft for landing gear or other service, two hydraulic jacks and a tail stand should be used. At least 250 pounds of ballast should be placed on the base of the tail stand before the airplane is jacked up. The hydraulic jacks should be placed under the jack points on the bottom of the wing and the airplane jacked up until the tail skid is at the right height to attach the tail stand. After the tail stand is attached and the ballast added, jacking may be continued until the airplane is at the height desired.

The steering arms from the rudder pedals to the nose wheel are adjusted at the nose wheel by turning the threaded rod end bearings in or out. Adjustment is normally accomplished at the forward end of the rods and should be done in such a way that the nose wheel is in line with the fore and aft axis of the plane when the rudder pedals and rudder are centered. Alignment of the nose wheel can be checked by pushing the airplane back and forth with the rudder centered to determine that the plane follows a perfectly straight line. The turning arc of the nose wheel is $30.0^{\circ} + 2^{\circ}$ in either direction and is limited by stops on the bottom of the forging.

The rudder pedal arm stops should be carefully adjusted so that the pedal arms contact the stops just after the rudder hits its stops. This guarantees that the rudder will be allowed to move through its full travel.

8.17 PROPELLER SERVICE

The spinner and backing plate should be frequently cleaned and inspected for cracks. Before each flight the propeller should be inspected for nicks, scratches, and corrosion. If found, they should be repaired as soon as possible by a rated mechanic, since a nick or scratch causes an area of increased stress which can lead to serious cracks or the loss of a propeller tip. The back face of the blades should be painted when necessary with flat black paint to retard glare. To prevent corrosion, the surface should be cleaned and waxed periodically.

ISSUED: JULY 12, 1995

REPORT: VB-1611

8.19 OIL REQUIREMENTS

The oil capacity of the engine is 8 quarts and the minimum safe quantity is 2 quarts. It is recommended that the oil be drained and renewed, and the screen cleaned, every 25 hours. However, if the full flow (cartridge type) oil filter is used, the oil and filter should be drained and renewed every 50 hours of operation. The interval between oil and oil filter change is not to exceed four (4) months. The following grades are recommended for the specified temperatures:

Average Ambient Air Temperature	MIL-L-6082B Mineral SAE Grade	MIL-L-22851 Ashless Dispersant SAE Grades		
All Temperatures		15W-50 or 20W-50		
Above 80°F	60	60		
Above 60°F	50	40 or 50		
30°F to 90°F	40	40		
0°F to 70°F	30	30, 40 or 20W-40		
Below 10°F	20	30 or 20W-30		

When operating temperatures overlap indicated ranges, use the lighter grade oil.

NOTE

Refer to the latest issue of Lycoming Service Instruction 1014 (Lubricating Oil Recommendations) for further information.

8.21 FUEL SYSTEM

(a) Servicing Fuel System

At every 50 hour inspection, the fuel screens in the strainer, in the electric fuel pump, and at the carburetor inlet must be cleaned.

(b) Fuel Requirements (AVGAS ONLY)

The minimum aviation grade fuel for the PA-28-181 is 100. Since the use of lower grades can cause serious engine damage in a short period of time, the engine warranty is invalidated by the use of lower octanes.

Whenever 100 or 100LL grade fuel is not available, commercial grade 100/130 should be used. (See Fuel Grade Comparison Chart.) Refer to the latest issue of Lycoming Service Instruction No. 1070 for additional information.

A summary of the current grades as well as the previous fuel designations is shown in the following chart:

FUEL	GRADE	COMPA	RISON	CHART

Previous Commercial Fuel Grades (ASTM-D910)			Current Commercial Fuel Grades (ASTM-D910-75)			Current Military Fuel Grades (MIL-G-5572F)		
Grade	Color	Max. TEL ml/U.S. gal	Grade	Color	Max. TEL ml/U.S. gal	Grade	Color	Max. TEL ml/U.S. gal
80/87	red	0.5	80	red	0.5	80/87	red	0.5
91/96	blue	2.0	*100LL	blue	2.0	none	none	none
100/130	green	3.0	100	green	**3.0	100/130	blue	2.0
115/145	purple	4.6	none	none	none ·	115/145	purple	4.6

^{* -}Grade 100LL fuel in some overseas countries is colored green and designated as "100L".

The operation of the aircraft is approved with an anti-icing additive in the fuel. When an anti-icing additive is used it must meet the specification MIL-1-27686, must be uniformly blended with the fuel while refueling, must not exceed .15% by volume of the refueled quantity, and to ensure its effectiveness should be blended at not less than .10% by volume. One and one half liquid ozs. per ten gallon of fuel would fall within this range. A blender supplied by the additive manufacturer should be used. Except for the information contained in this section, the manufacturer's mixing or blending instructions should be carefully followed.

CAUTION

Assure that the additive is directed into the flowing fuel stream. The additive flow should start after and stop before the fuel flow. Do not permit the concentrated additive to come in contact with the aircraft painted surfaces or the interior surfaces of the fuel tanks.

ISSUED: JULY 12, 1995

^{**-}Commercial fuel grade 100 and grade 100/130 having TEL content of up to 4 ml/U.S. gallons are approved for use in all engines certificated for use with grade 100/130 fuel.

CAUTIONS

Some fuels have anti-icing additives preblended in the fuel at the refinery, so no further blending should be performed.

Fuel additive can not be used as a substitute for preflight draining of the the fuel system drains.

(c) Filling Fuel Tanks

Observe all required precautions for handling gasoline. Fill the fuel tanks through the filler located on the forward slope of the wing. Each wing holds a maximum of 25 U.S. gallons. When using less than the standard 50 gallon capacity, fuel should be distributed equally between each tank. There is approximately 17 gallons in the fuel tank when fuel level is even with bottom of filler neck indicator.

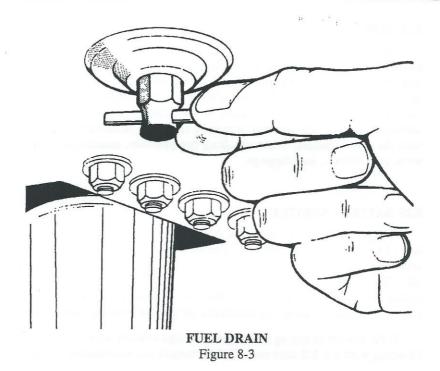
(d) Draining Fuel Strainer, Sumps and Lines

The fuel tank sumps and strainer should be drained daily prior to the first flight and after refueling to avoid the accumulation of contaminant's such as water or sediment. Each fuel tank is equipped with an individual quick drain located at the lower inboard rear corner of the tank. The fuel strainer is equipped with a quick drain located on the front lower corner of the fire wall. Each of the fuel tank sumps should be drained first. Then the fuel strainer should be drained twice, once with the fuel selector valve on each tank. Each time fuel is drained, sufficient fuel should be allowed to flow to ensure removal of contaminant's. This fuel should be collected in a suitable container, examined for contaminant's, and then discarded.

CAUTION

When draining any amount of fuel, care should be taken to ensure that no fire hazard exists before starting the the engine.

Each quick drain should be checked after closing it to make sure it has closed completely and is not leaking.



(e) Draining Fuel System

The bulk of the fuel may be drained from the system by opening the valve at the inboard end of each fuel tank. Push up on the arms of the drain valve and turn counterclockwise to hold the drain open. The remaining fuel in the system may be drained through the filter bowl. Any individual tank may be drained by closing the selector valve and then draining the desired tank.

CAUTION

Whenever the fuel system is completely drained and fuel is replenished it will be necessary to run the engine for a minimum of three minutes at 1000 RPM on each tank to insure that no air exists in the fuel supply lines.

8.23 TIRE INFLATION

For maximum service from the tires, keep them inflated to the proper pressures - 18 psi for the nose gear and 24 psi for the main gear. All wheels and tires are balanced before original installation, and the relationship of tire, tube and wheel should be maintained upon reinstallation. Unbalanced wheels can cause extreme vibration in the landing gear; therefore, in the installation of new components, it may be necessary to rebalance the wheels with the tires mounted. When checking tire pressure, examine the tires for wear, cuts, bruises, and slippage.

8.25 BATTERY SERVICE

Access to the 24-volt battery is through an access panel at the right rear side of the baggage compartment. The battery box uses a sump jar to catch acid and a plastic tube which vents gases. This vent should never be closed off. The battery should be checked for proper fluid level. DO NOT fill the battery above the baffle plates. DO NOT fill the battery with acid - use water only. A hydrometer check will determine the percent of charge in the battery.

If the battery is not up to charge, recharge starting at a 3 amp rate and finishing with a 1 1/2 amp rate. Quick charges are not recommended.

NOTE:

Initial current reduced by 1/2 when all cells start gassing and charge voltage and specific gravity of electrolyte are constant over three successive readings taken at one hour intervals.

8.27 CLEANING

(a) Cleaning Engine Compartment

Before cleaning the engine compartment, place a strip of tape on the magneto vents to prevent any solvent from entering these units.

(1) Place a large pan under the engine to catch waste.

(2) With the engine cowling removed, spray or brush the engine with solvent or a mixture of solvent and degreaser. In order to remove especially heavy dirt and grease deposits, it may be necessary to brush areas that were sprayed.

CAUTION

Do not spray solvent into the alternator, vacuum pump, starter, or air intakes.

(3) Allow the solvent to remain on the engine from five to ten minutes. Then rinse the engine clean with additional solvent and allow it to dry.

CAUTION

Do not operate the engine until excess solvent has evaporated or otherwise been removed.

(4) Remove the protective tape from the magnetos.

(5) Lubricate the controls, bearing surfaces, etc., in accordance with the Lubrication Chart.

(b) Cleaning Landing Gear

Before cleaning the landing gear, place a plastic cover or similar material over the wheel and brake assembly.

- (1) Place a pan under the gear to catch waste.
- (2) Spray or brush the gear area with solvent or a mixture of solvent and degreaser, as desired. Where heavy grease and dirt deposits have collected, it may be necessary to brush areas that were sprayed, in order to clean them.
- (3) Allow the solvent to remain on the gear from five to ten minutes. Then rinse the gear with additional solvent and allow to dry.
- (4) Remove the cover from the wheel and remove the catch pan.
- (5) Lubricate the gear in accordance with the Lubrication Chart.

(c) Cleaning Exterior Surfaces

The airplane should be washed with a mild soap and water. Harsh abrasives or alkaline soaps or detergents could make scratches on painted or plastic surfaces or could cause corrosion of metal. Cover areas where cleaning solution could cause damage. To wash the airplane, use the following procedure:

- (1) Flush away loose dirt with water.
- (2) Apply cleaning solution with a soft cloth, a sponge or soft bristle brush.
- (3) To remove exhaust stains, allow the solution to remain on the surface longer.
- (4) To remove stubborn oil and grease, use a cloth dampened with naphtha.
- (5) Rinse all surfaces thoroughly.
- (6) Any good automotive wax may be used to preserve painted surfaces. Soft cleaning cloths or a chamois should be used to prevent scratches when cleaning or polishing. A heavier coating of wax on the leading surfaces will reduce the abrasion problems in these areas.

(d) Cleaning Windshield and Windows

- Remove dirt, mud and other loose particles from exterior surfaces with clean water.
- (2) Wash with mild soap and warm water or with aircraft plastic cleaner. Use a soft cloth or sponge in a straight back and forth motion. Do not rub harshly.
- Remove oil and grease with a cloth moistened with kerosene.

CAUTION

Do not use gasoline, alcohol, benzene, carbon tetrachloride, thinner, acetone, or window cleaning sprays.

- (4) After cleaning plastic surfaces, apply a thin coat of hard polishing wax. Rub lightly with a soft cloth. Do not use a circular motion.
- (5) A severe scratch or mar in plastic can be removed by rubbing out the scratch with jeweler's rouge. Smooth both sides and apply wax.
- (e) Cleaning Headliner, Side Panels and Seats
 - (1) Clean headliner, side panels, and seats with a stiff bristle brush, and vacuum where necessary.
 - (2) Soiled upholstery, except leather, may be cleaned with a good upholstery cleaner suitable for the material. Carefully follow the manufacturer's instructions. Avoid soaking or harsh rubbing.

CAUTION

Solvent cleaners require adequate ventilation.

(3) Leather should be cleaned with saddle soap or a mild hand soap and water.

(f) Cleaning Carpets

To clean carpets, first remove loose dirt with a whisk broom or vacuum. For soiled spots and stubborn stains use a non-flammable dry cleaning fluid. Floor carpets may be removed and cleaned like any household carpet.

8.29 COLD WEATHER OPERATION

For cold weather operation a winterization plate is installed on the inlet opening of the oil cooler duct on the left rear engine baffle. This plate should be installed whenever the ambient temperature reaches $50^{\circ}F$ or less. The plate should be removed and stored in the cockpit when the ambient temperature exceeds $50^{\circ}F$.

It is recommended that an optional Engine Breather Tube Winterization Kit be installed for cold weather operation. This kit is available through your Piper Dealer/Distributor.

TABLE OF CONTENTS

SECTION 9

SUPPLEMENTS

	Paragraph No.		Page No.	
	9.1	General	9-1	
	1	Air Conditioning Installation	9-3	
	2	Bendix/King KAP 100 Series Flight Control System	9-7	
	3	Auxiliary Vacuum System	9-9	
	4	Bendix/King KLN 89 (B) GPS Navigation System(12 Pages)	9-15	
	5	Bendix/King KX 155A Comm/Nav System(12 Pages)	9-27	
	6	Bendix/King KAP 140 Series Flight Control System	9-39	
	7	Garmin GNS 430 Nav/Comm(8 Pages)	9-41 >	
	8	S-TEC System 55 Autopilot	9-49 >	
	9	S-TEC Manual Electric Trim System	9-51 >	
7	10	BF Goodrich Skywatch Traffic Advisory System Model SKY497(6 Pages)	9-53	
	11	BF Goodrich WX-500 Stormscope Series II Weather Mapping Sensor(4 Pages)	9-59	
	12	Garmin GNS 430 Nav/Comm with Traffic Advisory		
		and Lightning Strike Advisory Data(8 Pages)	9-63	
	13	Garmin GTX 327 Transponder(10 Pages)	9-71	
	14	S-TEC System 55X Autopilot	9-81	
	15	S-TEC ADF 650A System(6 Pages)	9-83	
	16	Garmin GMA 340 Audio Panel(6 Pages)	9-89	
	.17	S-TEC DME 450(4 Pages)	9-95	
	18	Garmin GTX 330 Transponder(4 Pages)	9-99	
	19	Garmin GNS 530 Nav/Comm with Traffic Advisory and Lightning Strike Advisory Data(8 Pages)	9-103	
	20	Avidyne FlightMax Entegra Primary Flight/Multi-Function Displays(30 pages)	9-111	
7	21	Mid-Continent 4300-4XX Series Electric Attitude Indicator(4 pages)	9-139	
-	22	S-TEC ADF-650D System(10 pages)	9-143	

ISSUED: JULY 12, 1995 REVISED: JANUARY 9, 2006

REPORT: VB-1611

9-i

TABLE OF CONTENTS

SECTION 9

SUPPLEMENTS (continued)

Para No.	graph/Supplement	Page No.
23	Avidyne FlightMax Entegra Primary Flight/ Multi-Function Displays With The B&C Specialties BC410 Standby Alternator(36 pages)	9-153
24.	Bendix/King KR-87 Digital ADF with KI-227 Indicator(10 pages)	9-189
25.	Bendix/King KN-63 DME(4 pages)	9-199
26_	Garmin G500 Primary Flight and Multifunction Display System(2 pages)	9-203
27.	Garmin GNS 430W VHF Communication Transceiver/VOR/ILS Receiver/GPS Receiver(12 pages)	9-205

ISSUED: JULY 12, 1995 REVISED: JULY 29, 2010

SECTION 9

SUPPLEMENTS

9.1 GENERAL

This section provides information in the form of Supplements which are necessary for efficient operation of the airplane when equipped with one or more of the various optional systems and equipment not approved with the standard airplane.

All of the supplements provided in this section are FAA Approved and consecutively numbered as a permanent part of this Handbook. The information contained in each Supplement applies only when the related equipment is installed in the airplane.

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REPORT: VB-1611

ISSUED: JULY 12, 1995

SUPPLEMENT 1

AIR CONDITIONING INSTALLATION

This supplement must be attached to the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual when the optional air conditioning system is installed in accordance with Piper Drawing 99575-10. The information contained herein supplements or supersedes the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual only in those areas listed herein. For limitations, procedures and performance information not contained in this supplement, consult the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual.

This supplement has been "FAA Approved" as a permanent part of this handbook and must remain in this handbook at all times when the optional air conditioning system is installed.

FAA APPROVED:

PETER E. PECK D.O.A. NO. SO-1

THE NEW PIPER AIRCRAFT, INC.

VERO BEACH, FLORIDA

DATE OF APPROVAL: JULY 12, 1995

SECTION 1 - GENERAL

This supplement supplies information necessary for the efficient operation of the airplane when the optional air conditioning system is installed. The information contained within this supplement is to be used ``as described" in conjunction with the complete handbook.

SECTION 2 - LIMITATIONS

- (a) To insure maximum climb performance the air conditioner must be turned OFF manually prior to takeoff to disengage the compressor and retract the condenser door. Also the air conditioner must be turned OFF manually before the landing approach in preparation for a possible go-around.
- (b) Placards

In full view of the pilot, in the area of the air conditioner controls when the air conditioner is installed:

"WARNING - AIR CONDITIONER MUST BE OFF TO INSURE NORMAL TAKEOFF CLIMB PERFORMANCE."

In the annunciator cluster (condenser door light):

ATR COND DOOR

SECTION 3 - EMERGENCY PROCEDURES

No changes to the basic Emergency Procedures provided by SECTION 3 of this Pilot's Operating Handbook are necessary for this supplement.

SECTION 4 - NORMAL PROCEDURES

Prior to takeoff, the air conditioner should be checked for proper operation as follows:

- (a) Check aircraft master switch ON.
- (b) Turn the air conditioner control switch to ON and the fan switch to one of the operating positions - the "AIR COND DOOR" warning light will turn on, thereby indicating proper air conditioner condenser door actuation.
- (c) Turn the air conditioner control switch to OFF the "AIR COND DOOR" warning light will go out, thereby indicating the air conditioner condenser door is in the up position.
- (d) If the "AIR COND DOOR" light does not respond as specified above, an air conditioner system or indicator bulb mal-function is indicated and further investigation should be conducted prior to flight.

The above operational check may be performed during flight if an in flight failure is suspected.

The condenser door light is located in the annunciator cluster in front of the pilot. The door light illuminates when the door is open and is off when the door is closed.

SECTION 5 - PERFORMANCE

Operation of the air conditioner will cause slight decreases in cruise speed and range. Power from the engine is required to run the compressor, and the condenser door, when extended, causes a slight increase in drag. When the air conditioner is turned off there is normally no measurable difference in climb, cruise or range performance of the airplane.

NOTE

To insure maximum climb performance the air conditioner must be turned off manually before takeoff to disengage the compressor and retract the condenser door. Also the air conditioner must be turned off manually before the landing approach in preparation for a possible goaround.

ISSUED: JULY 12, 1995

Although the cruise speed and range are only slightly affected by the air conditioner operation, these changes should be considered in preflight planning. To be conservative, the following figures assume that the compressor is operating continuously while the airplane is airborne. This will be the case only in extremely hot weather

- (a) The decrease in true airspeed is approximately 4 KTS at all power settings.
- (b) The decrease in range may be as much as 32 nautical miles for the 48 gallon capacity.

The climb performance is not compromised measurably with the air conditioner operating since the compressor is declutched and the condenser door is retracted, both automatically, when a full throttle position is selected. When the full throttle position is not used or in the event of a malfunction which would cause the compressor to operate and the condenser door to be extended, a decrease in rate of climb of as much as 100 fpm can be expected. Should a malfunction occur which prevents condenser door retraction when the compressor is turned off, a decrease in rate of climb of as much as 50 fpm can be expected.

SECTION 6 - WEIGHT AND BALANCE

Factory installed optional equipment is included in the licensed weight and balance data in Section 6 of the Pilot's Operating Handbook.

SECTION 7 - DESCRIPTION AND OPERATION

No change.

PILOT'S OPERATING HANDBOOK AND FAA APPROVED AIRPLANE FLIGHT MANUAL

SUPPLEMENT NO. 2 FOR KING KAP 100 SERIES FLIGHT CONTROL SYSTEM

The FAA Approved Operational Supplement to the Bendix/King 100 Series Flight Control System as installed per STC SA1565CE-D is supplied by the autopilot manufacturer. Bendix/King will be responsible to supply and revise the operational supplement. It is permitted to include the Bendix/King supplement in this location of the Pilots Operating Handbook unless otherwise stated by Bendix/King. The information contained in the Bendix/King supplement may supersede or supplement the information in the basic Pilot's Operating Handbook and FAA Approved Airplane Flight Manual with respect to the operation of the autopilot. For limitations, procedures and performance information not contained in the Bendix/King supplement, consult the basic Pilot's Operating Handbook and FAA Approved Airplane Flight Manual.

ISSUED: JULY 12, 1995

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PILOT'S OPERATING HANDBOOK AND FAA APPROVED AIRPLANE FLIGHT MANUAL

SUPPLEMENT NO. 3 FOR AUXILIARY VACUUM SYSTEM

This supplement must be attached to the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual when the Piper Auxiliary Vacuum System is installed in accordance with Piper Drawing 85387-2. The information contained herein supplements or supersedes the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual only in those areas listed herein. For limitations, procedures and performance information not contained in this supplement, consult the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual.

FAA APPROVED:

PETER E. PECK D.O.A. NO. SO-1

THE NEW PIPER AIRCRAFT, INC.

VERO BEACH, FLORIDA

DATE OF APPROVAL: JULY 12, 1995

SECTION 1 - GENERAL

This supplement supplies information necessary for the operation of the airplane when the optional Piper Auxiliary Vacuum System is installed. The information contained within this supplement is to be used in conjunction with the complete handbook.

SECTION 2 - LIMITATIONS

- 1. The auxiliary vacuum system is limited to standby function only. Do not take off with the engine driven dry air pump inoperative.
- 2. Discontinue flight in Instrument Meteorological Conditions (IMC) if vacuum pressure falls below 4.8 In. Hg.
- 3. The auxiliary pump/motor assembly and elapsed time indicator must be removed from service after 500 hours accumulated operating time or 10 years, whichever occurs first.

SECTION 3 - EMERGENCY PROCEDURES

- (a) VAC OFF or Vacuum Inop. Warning Auxiliary Vacuum Switch AUX ON.
- (b). Verify vacuum pressure of 4.8 to 5.2 inches of mercury.

CAUTION

Compass error may exceed 10 when auxiliary vacuum system is in operation.

(c). Monitor electrical load - Verify alternator capacity is not being exceeded as indicated by the ammeter. If required, turn off nonessential electrical equipment.

SECTION 4 - NORMAL PROCEDURES

A. Preflight Check.

1. Turn on battery master switch on and verify that VAC OFF lamp lights.

NOTE

Due to electrical power requirement of the auxiliary vacuum pump it is suggested that the engine be operating while making the following checks.

- 2. Turn on auxiliary vacuum pump on and verify AUX ON light is illuminated and electrical load is approximately 15 amps on ammeter.
- Turn off auxiliary vacuum pump and verify AUX ON light goes out.
- B. Inflight Check Prior to entering instrument flight conditions.
 - 1. Turn off non-essential electrical equipment.
 - Turn on auxiliary vacuum pump and verify AUX ON light illuminated and electrical load is approximately 15 amps on ammeter.
 - Turn off auxiliary vacuum pump and verify AUX ON light goes out.

NOTE

For maximum service life, avoid continuous non-emergency operation of the auxiliary vacuum pump.

SECTION 5 - PERFORMANCE

No change.

SECTION 6 - WEIGHT & BALANCE

Factory installed optional equipment is included in the licensed weight and balance data in section 6 of the Pilot's Operating Handbook.

SECTION 7 - DESCRIPTION AND OPERATION

The auxiliary dry air pump system provides an independent back-up source of pneumatic power to operate the gyro flight instruments in the event the engine driven air pump fails.

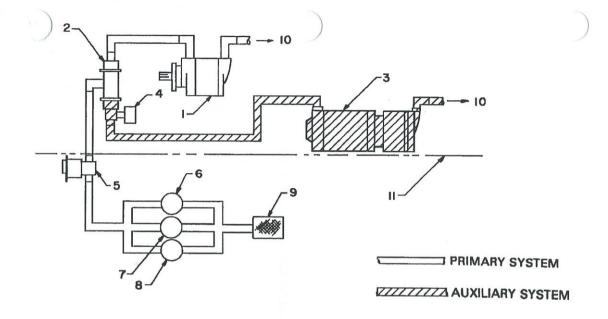
The auxiliary pump is mounted on the forward side of the firewall and connects to the primary system at a manifold downstream of the vacuum regulator. Isolation of the primary and auxiliary systems from each other is accomplished by check valves on each side of the manifold. The primary system vacuum switch is located on the regulator and senses vacuum supplied to the gyros.

A control switch (labeled AUX VAC) for the auxiliary pump system is located on the right side of the instrument panel near the vacuum suction gage.

The switch button incorporates two annunciator light sections labeled VAC OFF and AUX ON. The VAC OFF section is controlled by a vacuum switch in the primary pneumatic system and illuminates an amber light when the engine driven pump is inoperative or when the system vacuum falls below the switch activation level. The AUX ON section is controlled by a vacuum switch on the manifold and illuminates a blue light when the auxiliary pump is operating and creating a vacuum in the system. When the auxiliary pump is activated at high altitude, or if the system has developed air leaks, the AUX ON light may fail to illuminate. This indicates that the system vacuum is still below the AUX ON switch activation level even though the auxiliary pump is operating. The annunciator lights do not incorporate a press-to-test feature, if the lights do not illuminate as expected, check for burned out lamps, replace with MS25237-327 bulbs and retest the system.

System electrical protection is provided by a 20 amp circuit breaker in the pump motor circuit and a 5 amp circuit breaker in the annunciator light circuit. The breakers are mounted on the circuit breaker panel.

PA-28-181, ARCHER III



- 1. ENGINE DRIVEN DRY AIR PUMP
- 2. MANIFOLD & CHECK VALVE ASSY.
- 3. AUX. ELECTRICALLY DRIVEN DRY AIR PUMP
- 4. PRESSURE SENSING SWITCH
- 5. SYSTEM REGULATOR & PRESS. SENSING SWITCH
- 6. VACUUM (SUCTION) GAUGE

- 7. ATTITUDE GYRO
- 8. DIRECTIONAL GYRO
- 9. FILTER
- 10. OVERBOARD VENT
- 11. FIREWALL

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PILOT'S OPERATING HANDBOOK AND FAA APPROVED AIRPLANE FLIGHT MANUAL

SUPPLEMENT NO. 4 FOR BENDIX/KING KLN 89(B) GPS NAVIGATION SYSTEM

This supplement must be attached to the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual when the KLN 89 (B) GPS Navigation System is installed per the Equipment List. The information contained herein supplements or supersedes the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual only in those areas listed herein. For limitations, procedures and performance information not contained in this supplement, consult the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual.

FAA APPROVED:

PETER E. PECK D.O.A. NO. SO-1

THE NEW PIPER AIRCRAFT, INC.

VERO BEACH, FLORIDA

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9-15

SECTION 1 GENERAL

NOTE

This supplement covers both the KLN 89 (VFR) only and the KLN 89B (IFR approved for Enroute, Terminal and non-precision approach phases of flight). There are numerous places throughout this supplement which discuss features and operational characteristics which specifically apply to KLN 89B and not to KLN 89. The parts of this supplement which apply to both the KLN 89 and the KLN 89B will be shown with a generic reference to KLN 89 (B).

The KLN 89(B) GPS panel mounted unit contains the GPS sensor, the navigation computer, a CRT display, and all controls required to operate the unit. It also houses the data base card which plugs directly into the front of the unit.

NOTE

SID's, STAR's and instrument approaches, apply only to the KLN 89B.

The data base card is an electronic memory containing information on airports, navaids, intersections, SID's, STAR's, instrument approaches, special use airspace, and other items of value to the pilot.

Every 28 days, Bendix/King receives new data base information from Jeppesen Sanderson for the North American data base region. This information is processed and downloaded onto the data base cards. Bendix/King makes these data base card updates available to KLN 89(B) GPS users.

Provided the KLN 89(B) GPS navigation system is receiving adequate usable signals, it has been demonstrated capable of and has been shown to meet the accuracy specifications of:

SECTION 1 GENERAL (Cont'd)

VFR/IFR en route oceanic and remote, en route domestic, terminal, and instrument approach (GPS, VOR, VOR-DME, TACAN, NDB, NDB-DME, RNAV) operation within the U.S. National Airspace System, North Atlantic Minimum Navigation Performance Specifications (MNPS) Airspace and latitudes bounded by 74° North and 60° South using the WGS44 (or NAD 83) coordinate reference datum in accordance with the criteria of AC 20-138, AC 91-49, and AC 120-33. Navigation data is based upon use of only the global positioning system (GPS) operated by the United States.

NOTE

Aircraft using GPS for oceanic IFR operations may use the KLN 89B to replace one of the other approved means of long-range navigation. A single KLN 89B GPS installation may also be used on short oceanic routes which require only one means of longrange navigation.

NOTE

FAA approval of the KLN 89 (B) does not necessarily constitute approval for use in foreign airspace.

SECTION 2-LIMITATIONS

- A. The KLN 89 (B) GPS Pilot's Guide, P/N 006-08786-0000, dated May, 1995 (or later applicable revision) must be immediately available to the flight crew whenever navigation is predicated on the use of the system. The Operational Revision Status (ORS) of the Pilot's Guide must match the ORS level annunciated on the Self Test page.
- B. IFR Navigation is restricted as follows: (KLN 89B only.)
 - The system must utilize ORS level 01 or later FAA approved revision.
 - 2. The data on the self test page must be verified prior to use.
 - 3. IFR en route and terminal navigation is prohibited unless the pilot verifies the currency of the data base or verifies each selected waypoint for accuracy by reference to current approved data.
 - 4. Instrument approaches must be accomplished in accordance with approved instrument approach procedures that are retrieved from the KLN 89B data base. The KLN 89B data base must incorporate the current update cycle.
 - (a) The KLN 89B Quick Reference, P/N 006-08787-0000, dated 5/95 (or later applicable revision) must be immediately available to the flight crew during instrument approach operations.
 - (b) Instrument approaches must be conducted in the approach mode and RAIM must be available at the Final Approach Fix.
 - (c) APR ACTV mode must be annunciated at the Final Approach Fix.
 - (d) Accomplishment of ILS, LOC, LOC-BC, LDA, SDF, and MLS approaches are not authorized.
 - (e) When an alternate airport is required by the applicable operating rules, it must be served by an approach based on other than GPS or Loran-C navigation.
 - (f) The KLN 89B can only be used for approach guidance if the reference coordinate datum system for the instrument approach is WGS 84 or NAD-83. (All approaches in the KLN 89 (B) data base use the WGS-84 or the NAD-83 geodetic datums.)
 - 5. The aircraft must have other approved navigation equipment appropriate to the route of flight installed and operational.

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SECTION 3- EMERGENCY PROCEDURES ABNORMAL PROCEDURES

- A. If the KLN 89 (B) GPS information is not available or invalid, utilize remaining operational navigation equipment as required.
- B. If a "RAIM NOT AVAILABLE" message is displayed while conducting an instrument approach, terminate the approach. Execute a missed approach if required.
- C. If a "RAIM NOT AVAILABLE" message is displayed in the en route or terminal phase of flight, continue to navigate using the KLN 89B or revert to an alternate means of navigation appropriate to the route and phase of flight. When continuing to use GPS navigation, position must be verified every 15 minutes using another IFR approved navigation system.
- D. Refer to the KLN 89 (B) Pilot's Guide, Appendices B and C, for appropriate pilot actions to be accomplished in response to annunciated messages.

SECTION 4 - NORMAL PROCEDURES

WARNING

Familiarity with the en route operation of the KLN 89 (B) does not constitute proficiency in approach operations. Do not attempt approach operations In IMC prior to attaining proficiency in the use of the KLN 89 (B).

A. OPERATION

Normal operating procedures are outlined in the KLN 89 (B) GPS Pilot's Guide, P/N 006-08786-0000, dated May 1995, (or later applicable revision). A KLN 89 (B) Quick Reference, P/N 006-08787-0000 dated 5/95 (or later applicable revision) containing an approach sequence, operating tips and approach related messages is intended for cockpit use by the KLN 89B familiar pilot when conducting instrument approaches.

B. SYSTEM ANNUNCIATORS/SWITCHES/CONTROLS

 HSI NAV presentation (NAV/GPS) switch annunciator- May be used to select data for presentation on the pilot's HSI; either NAV data from the number one navigation receiver or GPS data from the KLN 89 (B) GPS. Presentation on the HSI is also required for autopilot coupling. NAV is green. GPS is blue.

- Message (MSG) annunciator Will flash to alert the pilot of a situation that requires attention. Press the MSG button on the KLN 89 (B) GPS to view the message. (Appendix B of the KLN 89 (B) Pilot's Guide contains a list of all of the message page messages and their meanings). MSG is amber.
- 3. Waypoint (WPT) annunciator Prior to reaching a waypoint in the active flight plan, the KLN 89 (B) GPS will provide navigation along a curved path segment to ensure a smooth transition between two adjacent legs in the flight plan. This feature is called turn anticipation. Approximately 20 seconds prior to the beginning of turn anticipation the WPT annunciator will flash, going solid upon initialization of the turn, and extinguishing upon turn completion. WPT is amber.

WARNING

Turn anticipation is automatically disabled for FAF waypoints and those used exclusively in SID/STARS where overflight is required. For waypoints shared between SID/STARS and published en route segments (requiring overflight in the SID/ STARS), proper selection on the presented waypoint page is necessary to provide adequate route protection on the SID/STARS.

4. HSI course control (1) knob - Provides analog course input to the KLN 89 (B) in OBS when the NAV/GPS switch/annunciator is in GPS. When the NAV/GPS switch annunciation is in NAV, GPS course selection in OBS mode is digital through the use of the controls and display at the KLN 89 (B). The HSI course control knob must also be set to provide proper course datum to the autopilot if coupled to the KLN 89 (B) in LEG or OBS.

NOTE

Manual HSI course centering in OBS using the control knob can be difficult, especially at long distances. Centering the dbar can best be accomplished by pressing DD and then manually setting the HSI pointer to the course value prescribed in the KLN 89 (B) displayed message.

- 5. GPS approach (GPS APR ARM/ACTV) switch/annunciator (KLN 89B only) used to (a) manually select or deselect approach ARM (or deselect approach ACTV) and (b) annunciate the stage of approach operation either armed (ARM) or activated (ACTV). Sequential button pushes if in ACTV would first result in approach ARM and then approach arm canceled. Subsequent button pushes will cycle between the armed state (if an approach is in the flight plan) and approach arm canceled. Approach ACTV cannot be selected manually. GPS APR and ARM are white. ACTV is green.
- RMI NAV presentation switch May be used to select data for presentation on the RMI; either NAV 1 data from the number one navigation receiver, NAV 2 data from the number two navigation receiver or GPS data from the KLN 89 (B) GPS.

C. PILOTS DISPLAY

Left/right steering information is presented on the pilot's HSI as a function of the NAV/GPS switch position.

D. AUTOPILOT COUPLED OPERATION

The KLN 89 (B) may be coupled to the autopilot by first selecting GPS on the NAV/GPS switch. Manual selection of the desired track on the pilot's HSI course pointer is required to provide course datum to the autopilot. (Frequent manual course pointer changes may be necessary, such as in the case of flying a DME arc.) The autopilot approach mode (APR) should be used when conducting a coupled GPS approach.

NOTE

Select HDG mode for DME arc intercepts. NAV or APR coupled DME arc intercepts can result in excessive overshoots (aggravated by high ground speeds and/or intercepts from inside the arc).

E. ALTITUDE ALERT AURAL TONES

- 1000 feet prior to reaching the selected altitude three short tones.
- Upon reaching the selected altitude two short tones.
- Deviating above or below the selected altitude by more than the warn altitude - four short tones.

F. APPROACH MODE SEQUENCING AND RAIM PREDICTION (KLN 89B only.)

NOTE

The special use airspace alert will automatically be disabled prior to flying an instrument approach to reduce the potential for message congestion.

Prior to arrival, select a STAR if appropriate from the APT 7
page. Select an approach and an initial approach fix (IAF) from
the APT 8 page.

NOTES

- Using the outer knob, select the ACT (Active Flight Plan Waypoints) pages. Pull the inner knob out and scroll to the destination airport, then push the inner knob in and select the ACT 7 or ACT 8 page.
- To delete or replace a SID, STAR or approach, select FPL 0 page. Place the cursor over the name of the procedure, press ENT to change it, or CLR then ENT to delete it.
- 2. En route, check for RAIM availability at the destination airport ETA on the OTH 3 page.

NOTE

RAIM must be available at the FAF in order to fly an instrument approach. Be prepared to terminate the approach upon loss of RAIM.

- 3. At 30 nm from the airport:
 - a. Verify automatic annunciation of APR ARM.
 - Note automatic dbar scaling change from ± 5.0 nm to ±1.0 nm over the next 30 seconds.
 - c. Update the KLN 89B altimeter baro setting as required.
 - Internally the KLN 89B will transition from en route to terminal integrity monitoring.
- 4. Select NAV 4 page to fly the approach procedure.
 - If receiving radar vectors, or need to fly a procedure turn or holding pattern, fly in OBS until inbound to the FAF.

NOTE

OBS navigation is TO-FROM (like a VOR) without waypoint sequencing.

NoPT routes including DME arc's are flown in LEG.
 LEG is mandatory from the FAF to the MAP.

NOTE

Select HDG mode for DME arc intercepts. NAV or APR coupled DME arc intercepts can result in excessive overshoots (aggravated by high ground speeds and/or intercepts from inside the arc).

WARNING

Flying final outbound from an off airport vortac on an overlay approach; beware of the DME distance increasing on final approach, and the GPS distance-to waypoint decreasing, and not matching the numbers on the approach plate!

- 5. At or before 2 nm from the FAF inbound:
 - a. <u>Select the FAF as the active waypoint</u>, if not accomplished already.
 - b. Select LEG operation.

- 6. Approaching the FAF inbound (within 2 nm.):
 - Verify APR ACTV.
 - b. Note automatic dbar scaling change from ± 1.0 nm to ± 0.3 nm over the 2 nm inbound to the FAF.
 - Internally the KLN 89B will transition from terminal to approach integrity monitoring.
- 7. Crossing the FAF and APR ACTV is not annunciated:
 - a Do not descend.
 - b. Execute the missed approach.
- Missed Approach:
 - a. Climb
 - Navigate to the MAP (in APR ARM if APR ACTV is not available).

NOTE

There is no automatic LEG sequencing at the MAP.

c. After climbing in accordance with the published missed approach procedure, press verify or change the desired holding fix and press ENT.

GENERAL NOTES

- The data base must be up to date for instrument approach operation.
- · Only one approach can be in the flight plan at a time.
- If the destination airport is the active waypoint at the time of the instrument approach selection, the active waypoint will shift automatically to the chosen IAF.
- Checking RAIM prediction for your approach while en route using the OTH 3 page is recommended. A self check occurs automatically within 2 nm of the FAF. APR ACTV is inhibited without RAIM.
- Data cannot be altered, added to or deleted from the approach procedures contained in the data base.
 (DME arc intercepts may be relocated along the arc through the NAV4 or the FPL 0 pages).
- Some approach waypoints do not appear on the approach plates (including in some instances the FAF)!

· Waypoint suffixes in the flight plan:

i - IAF

f- FAF

m - MAP

h missed approach holding fix.

- The DME arc IAF (arc intercept waypoint) will be a) on your present position radial off the arc VOR when you load the IAF into the flight plan, or b) the beginning of the arc if currently on a radial beyond the arc limit. To adjust the arc intercept to be compatible with a current radar vector, bring up the arc IAF waypoint in the NAV 4 page scanning field or under the cursor on the FPL 0 page, press CLR, then ENT. Fly the arc in LEG. adjust the HSI or CDI course pointer with reference to the desired track value on the NAV 4 page (it will flash to remind you). Left/right dbar information is relative to the arc. Displayed distance is not along the arc but direct to the active waypoint. (The ARC radial is also displayed in the lower right corner of the NAV 4 page.)
- The DME arc IAF identifier may be unfamiliar. Example: D098G where 098 stands for the 098° radial off the referenced VOR, and G is the seventh letter in the alphabet indicating a 7 DME arc.

- APR ARM to APR ACTV is automatic provided:
 - a. You are in APR ARM (normally automatic).
 - b. You are in LEG mode!
 - c. The FAF is the active waypoint!
 - d. Within 2 n.m. of the FAF.
 - e. Outside of the FAF.
 - f. Inbound to the FAF.
 - g. RAIM is available.
- Direct-To operation between the FAF and MAP cancels APR ACTV. Fly the missed approach in APR ARM.
- Flagged navigation inside the FAF may usually be restored (not guaranteed) by pressing the GPS APR button changing from ACTV to ARM. Fly the missed approach.
- The instrument approach using the KLN 89 (B) may be essentially automatic starting 30 nm out (with a manual baro setting update) or it may require judicious selection of the OBS and LEG modes.
- APR ARM may be canceled at any Time by pressing the GPS APR button. (A subsequent press will reselect it.)

SECTION 5- PERFORMANCE

No change.

SECTION 6- WEIGHT AND BALANCE

Factory installed optional equipment is included in the licensed weight and balance data in Section 6 of the Basic Pilot's Operating HAndbook.

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9-26

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PILOT'S OPERATING HANDBOOK AND FAA APPROVED AIRPLANE FLIGHT MANUAL

SUPPLEMENT NO. 5 FOR BENDIX/KING KX 155A COMM/NAV SYSTEM

This supplement must be attached to the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual when the KX 155A Comm/Nav System is installed per the Piper Drawings. The information contained herein supplements or supersedes the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual only in those areas listed herein. For limitations, procedures and performance information not contained in this supplement, consult the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual.

FAA APPROVED

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THE NEW PIPER AIRCRAFT, INC. VERO BEACH, FLORIDA

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9-27

SECTION 1 GENERAL

This supplement supplies information necessary for the operation of the airplane when the Bendix/King KX 155A Comm/Nav System is installed in accordance with FAA approved Piper data.

SECTION 2 LIMITATIONS

No change.

SECTION 3-EMERGENCY PROCEDURES

No change.

SECTION 4- NORMAL PROCEDURES

COMM TRANSCEIVER

- (a.). Rotate the volume (VOL) knob clockwise from the OFF position.
- (b.) Pull the VOL knob out and adjust for desired listening level.
- (c.) Push the VOL knob back in to actuate the automatic squelch.
- (d.) Select the desired operating frequency in the standby display by rotating the frequency select knobs either clockwise or counter-clockwise.
- (e.) Push the comm transfer button to transfer the frequency from the standby to the active display.

NAV RECEIVER

(a.) The right portion of the display is allocated to NAV receiver information. The frequency channeling is similar to the Comm when operating in the frequency mode. The NAV increment/decrement knobs are located on the right hand side of the front panel.

SECTION 5- PERFORMANCE

No change.

SECTION 6- WEIGHT AND BALANCE

See Section 6 of the basic Pilots Operating Handbook.

SECTION 7 DESCRIPTION & OPERATION

GENERAL

All controls required to operate the KX 155A are located on the unit front panel. (See Figure 3-1.)

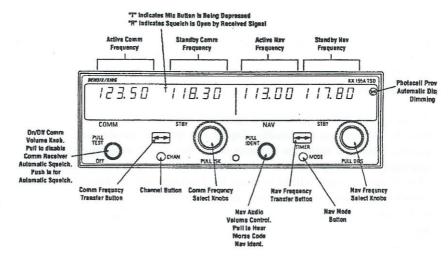


FIGURE 3-1 KX 155A CONTROL FUNCTIONS

COMM TRANSCEIVER

Rotate the VOL knob clockwise from the OFF position. Pull the VOL knob out and adjust for desired listening level. Push the VOL knob back in to actuate the automatic squelch.

The left portion of the digital display readout is allocated for COMM ACTIVE, and COMM STANDBY frequencies with a "T" between them to indicate TRANSMIT and an "R" to indicate RECEIVE modes of operation.

Select the desired operating frequency in the standby display by rotating the Frequency Select Knobs either clockwise or counter-clockwise. A clockwise rotation will increment the previous frequency while a counterclockwise rotation will decrement the previous frequency.

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COMM TRANSCEIVER (CONT'D)

The outer knob will change the MHz portion of the standby display. At one band-edge (118 or 136 MHz) the following 1 MHz change will wrap around to the other band-edge. The inner knob will change the kHz portion of the standby display. It will change in steps of 50 kHz when the knob is pushed in, and 25 kHz when the knob is pulled out. For 8.33 kHz versions, channels are incremented in 25 kHz steps with the knob pushed in and 8.33 kHz with the knob pulled out. (Both 8.33 kHz and 25 kHz frequencies are channeled when the knob is pulled out). The frequency wrap around at the edge of the band is also utilized when incrementing or decrementing the kHz portion of the standby display.

To tune the radio to the desired operating frequency, the desired frequency must be entered into the standby display and then the transfer button must be pushed. This will trade the contents of the active and standby displays. The operating frequency can also be entered by accessing the ACTIVE ENTRY (direct tune) mode which is done by pushing and holding the COMM TRANSFER button for 2 or more seconds. In the direct tune mode, only the active part of the display is visible. The desired frequency can be directly entered into the display. Push the COMM TRANSFER button again to return to the active/standby display.

The transceiver is always tuned to the frequency appearing in the ACTIVE display. It is therefore possible to have two different frequencies stored in the ACTIVE and STANDBY displays and to change back and forth between them at the simple push of the transfer button.

During the transmit mode of operation, a "T" will appear between the ACTIVE and STANDBY displays. An "R" will appear between the ACTIVE and STANDBY displays if a detected signal is strong enough to open the squelch, signifying that the transceiver is in the receive mode of operation.

A non-volatile memory stores the comm ACTIVE and STANDBY frequencies on power down. When the unit is turned on again, the COMM ACTIVE and STANDBY windows will display the same ACTIVE and STANDBY frequencies that were displayed before power down.

The KX 155A also has provision to program 32 channels. Pressing the CHAN button for 2 or more seconds will cause the unit to enter the channel program mode. Upon entering the channel program mode,"PG" is displayed next to the channel number and the channel number will flash indicating that it can be programmed. The desired channel can be selected by turning the comm kHz knob. The channel frequency can be entered by pushing the COMM TRANSFER button which will cause the standby frequency to flash. The comm frequency knobs are then used to enter the desired frequency. If dashes (displayed when rotating the outer knob between 136 MHz and 118 MHz) are entered instead of a frequency, the corresponding channel is skipped in channel selection mode. Additional channels may be programmed by pressing tne COMM TRANSFER and using the same procedure. To exit the program mode and save the channel information, momentarily push the CHAN button. This will cause the unit to return to the previous frequency entry mode. The unit will also exit the channel program mode if there is no button or knob activity for 20 seconds.

The channel selection mode can then be entered by momentarily pushing CHAN button. "CH" is displayed next to the last used channel number. The comm frequency knobs can be used to select the desired channel. The unit will automatically default to the previous mode if no channel is selected within 2 seconds after entering the channel selection mode.

The unit is placed in the transmit mode by depressing the MIC KEY button. The unit has a stuck microphone alert feature. If the microphone is keyed continuously for greater than 33 seconds, the transmitter stops transmitting and the active Comm frequency flashes to alert the pilot of the stuck microphone condition.

NAV RECEIVER

The right portion of the display is allocated to NAV receiver information. The frequency channeling is similar to the COMM when operating in the frequency mode (Figure 3-1). The NAV increment/decrement knobs are located on the right hand side of the front panel. The outer knob operates in 1 MHz steps and increments/decrements the STANDBY frequency display.

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NAV RECEIVER (CONT'D)

The inner knob operates in 50 kHz steps. The NAV receiver's lower and upper frequency limits are 108.00 MHz and 117.95 MHz. Exceeding the upper limit of frequency band will automatically return to the lower limit and vice versa.

Depressing the NAV frequency transfer button for 2 seconds or more will cause the display to go in to the ACTIVE ENTRY mode. Only the ACTIVE frequency will be displayed and it can be directly changed by using the NAV inc/dec knobs. The display will return to the ACTIVE/STANDBY mode when the NAV frequency transfer button is pushed.

Depressing the mode button will cause the NAV display to go from the ACTIVE/STANDBY format to the ACTIVE/CDI (Course Deviation Indicator) format as shown below in Figure 3-2. In the CDI mode, the increment/decrement knob (pushed in) channels the ACTIVE frequency window and depressing the frequency transfer button will cause the ACTIVE frequency to be placed in blind storage and the STANDBY frequency (in blind storage) to be displayed in the ACTIVE window display. When the ACTIVE window is tuned to a VOR frequency, the standby frequency area is replaced by a three digit OBS (Omni Bearing Selector) display. The desired OBS course can be selected by pulling out the inner NAV frequency knob and turning it. This OBS display is independent of any OBS course selected on an external CDI or HSI. An "OBS" in the middle of the NAV display will flash while the inner NAV frequency knob is pulled out. The CDI is displayed on the line below the frequency/OBS. When the ACTIVE window is tuned to a localizer frequency, the standby frequency area is replaced by "LOC" Figure 3-3. Illustrations of the display are shown on the next page.



FIGURE 3-2 NAV DISPLAY; ACTIVE VOR FREQUENCY/CDI FORMAT

ISSUED: JULY 12, 1995 REVISED: APRIL 3, 1997

REPORT: VB-1611

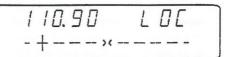


FIGURE 3-3 NAV DISPLAY; ACTIVE LOCALIZER FREQUENCY/CDI FORMAT

When the received signal is too weak to ensure accuracy the display will "flag". See Figure 3-4.

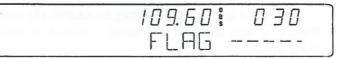


FIGURE 3-4 VOR FLAG DISPLAY

ISSUED: JULY 12, 1995 REVISED: APRIL 3, 1997

NAV RECEIVER (CONT'D)

Depressing the mode button will cause the NAV display to go from the ACTIVE/CDI format to the ACTIVE/BEARING format. In the BEARING mode, the increment/decrement knob channels the ACTIVE frequency window and depressing the frequency transfer button will cause the ACTIVE frequency to be placed in blind storage and the STANDBY frequency (in blind storage) to be displayed in the ACTIVE window display. In bearing mode of operation, the right hand window of NAV display shows the bearing TO the station. Figure 3-5 below illustrates the NAV side of the display in this mode:

9.63		
	109.60	0 30 10

FIGURE 3-5 VOR MODE; BEARING TO FUNCTION

When a too weak or invalid VOR signal is received the display flags as shown in Figure 3-6.

109.60	T0

FIGURE 3-6 VOR MODE; ACTIVE/BEARING, FLAG DISPLAY

REPORT: VB-1611

ISSUED: JULY 12, 1995

REVISED: APRIL 3, 1997

Another push of the mode button will cause the NAV display to go from the ACTIVE/BEARING format to the ACTIVE/RADIAL format as shown in Figure 3-7. In the RADIAL mode, the increment/decrement knob channels the ACTIVE frequency window and depressing the frequency transfer button will cause the ACTIVE frequency to be placed in blind storage and the STANDBY frequency (in blind storage) to be displayed in the ACTIVE window display. In radial mode of operation, the right hand window of NAV display shows the radial FROM the station. The picture below illustrates the NAV side of the display in this mode:

1/2000 110 110 110 110 110 110 110 110 110	109.60	0 30 FR

FIGURE 3-7 VOR MODE; RADIAL FROM FUNCTION

When a too weak or invalid VOR signal is received the display flags as shown in Figure 3-8.

109.60 --- FR

FIGURE 3-8 VOR MODE; ACTIVE/RADIAL, FLAG DISPLAY

ISSUED: JULY 12, 1995 REVISED: APRIL 3, 1997

NAV RECEIVER (CONT'D)

Another push of the mode button will cause the unit to go into the TIMER mode. See Figure 3-9. When the unit is turned on the elapsed timer begins counting upwards from zero. The timer can be stopped and reset to zero by pushing the NAV frequency transfer button for 2 seconds or more causing the ET on the display to flash. In this state the timer can be set as a countdown timer or the elapsed timer can be restarted. The countdown timer is set by using the NAV inc/dec knobs to set the desired time and then pushing the NAV frequency transfer button to start the timer. The outer knob selects minutes, the inner knob in the "in ~ position selects ten second intervals, and the inner knob in the ~out" position selects individual seconds. After the countdown timer reaches zero, the counter will begin to count upwards indefinitely while flashing for the first 15 seconds. The elapsed timer can also be reset to zero and started again after it has been stopped and reset to zero by pushing the NAV frequency transfer button.

110.90

FIGURE 3-9 TIMER MODE

The NAV ACTIVE and STANDBY frequencies are stored in the memory on power down and return on power up.

When the smaller increment/decrement knob is pushed in, depressing the NAV TRANSFER button will interchange the ACTIVE and STANDBY frequencies. The NAV IDENT knob is active in the pulled out position so that both voice and ident can be heard. When this knob is pushed in, the ident tone is attenuated. The volume of voice/ident can be adjusted by turning this knob.

ISSUED: JULY 12, 1995 REPORT: VB-1611 REVISED: APRIL 3, 1997

PILOT CONFIGURATION

This mode can be accessed by pressing and holding the Nav Mode Button for more than 2 seconds and then pressing the Nav Frequency Transfer Button for an additional 2 seconds, while continuing to hold the Nav Mode Button. When the Pilot Config Mode is entered the unit will show the "SWRV" mnemonic which is the unit software revision level. Adjustment pages can be accessed by MODE button presses.

The pilot may adjust two parameters in the pilot configuration, the display minimum brightness and sidetone volume level. See Table 3-1.

Minimum Brightness (BRIM) will have a range of 0 - 255. The dimmest is 0 and the brightest is 255.

Sidetone volume level is adjusted when SIDE is displayed. Values from 0 - 255 may be selected with 0 being least volume, 255 being the greatest.

Adjustment	Mnemonic	Min Level	Max Level
Software Revision Number	SWRV	I	
Minimum Display Brightness	BRIM	0	255
Sidetone Level	SIDE	0	255

Table 3-1 Pilot Configuration

Subsequent presses of the MODE button sequences through SWRV, BRIM, SIDE, and then back to SWRV.

Momentarily pressing the Nav Transfer Button exits Pilot configuration mode. The Nav returns to its pre-Pilot Config state with the new brightness and sidetone levels stored in non-volatile memory.

ISSUED: JULY 12, 1995 REPORT: VB-1611 REVISED: APRIL 3, 1997 9-37

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REPORT: VB-1611

9-38

ISSUED: JULY 12, 1995 REVISED: APRIL 3, 1997

SUPPLEMENT NO. 6 FOR KING KAP 140 SERIES FLIGHT CONTROL SYSTEM

The FAA Approved Operational Supplement to the Bendix/King 100 Series Flight Control System as installed per STC SA00444WI-D is supplied by the autopilot manufacturer. Bendix/King will be responsible to supply and revise the operational supplement. It is permitted to include the Bendix/King supplement in this location of the Pilots Operating Handbook unless otherwise stated by Bendix/King. The information contained in the Bendix/King supplement may supersede or supplement the information in the basic Pilot's Operating Handbook and FAA Approved Airplane Flight Manual with respect to the operation of the autopilot. For limitations, procedures and performance information not contained in the Bendix/King supplement, consult the basic Pilot's Operating Handbook and FAA Approved Airplane Flight Manual.

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9-39

SUPPLEMENT NO. 7 FOR GARMIN GNS 430 VHF COMMUNICATION TRANSCEIVER/VOR/ILS RECEIVER/GPS RECEIVER

This supplement must be attached to the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual when the Garmin GNS 430 VHF Communication Transceiver/VOR/ILS Receiver/Global Positioning System is installed per the Equipment List. The information contained herein supplements or supersedes the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual only in those areas listed herein. For limitations, procedures and performance information not contained in this supplement, consult the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual.

FAA APPROVED

PHTER E. PECK D.O.A. NO. SO-1 THE NEW PIPER AIRCRAFT, INC. VERO BEACH, FLORIDA

DATE OF APPROVAL: NOVEMBER 6, 1998

ISSUED: JULY 12, 1995

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REPORT: VB-1611

9-41

SECTION 1 - GENERAL

The GNS 430 System is a fully integrated, panel mounted instrument, which contains a VHF Communications Transceiver, a VOR/ILS receiver, and a Global Positioning System (GPS) Navigation computer. The system consists of a GPS antenna, GPS receiver, VHF VOR/LOC/GS antenna, VOR/ILS receiver, VHF COMM antenna and a VHF Communications transceiver. The primary function of the VHF Communication portion of the equipment is to facilitate communication with Air Traffic Control. The primary function of the VOR/ILS Receiver portion of the equipment is to receive and demodulate VOR, Localizer, and Glide Slope signals. The primary function of the GPS portion of the system is to acquire signals from the GPS system satellites, recover orbital data, make range and Doppler measurements, and process this information in real-time to obtain the user's position, velocity, and time.

Provided the GARMIN GNS 430's GPS receiver is receiving adequate usable signals, it has been demonstrated capable of and has been shown to meet the accuracy specifications for:

VFR/IFR enroute, terminal, and non-precision instrument approach (GPS, Loran-C, VOR, VOR-DME, TACAN, NDB, NDB-DME, RNAV) operation within the U.S. National Airspace System in accordance with AC 20-138.

North Atlantic Minimum Navigation Performance Specification (MNPS) Airspace in accordance with AC 91-49 and AC 120-33.

Navigation is accomplished using the WGS-84 (NAD-83) coordinate reference datum. Navigation data is based upon use of only the Global Positioning System (GPS) operated by the United States of America.

SECTION 2 - LIMITATIONS

- A. The GARMIN GNS 430 Pilot's Guide, p/n 190-00140-00, Rev. A, dated October 1998, or later appropriate revision, must be immediately available to the flight crew whenever navigation is predicated on the use of the system.
- B. The GNS 430 must utilize the following or later FAA approved software versions:

Sub-System	Software Version
Main	2.00
GPS	2.00
COMM	2.00
VOR/LOC	2.00
G/S	2.00

The main software version is displayed on the GNS 430 self test page immediately after turn-on for 5 seconds. The remaining system software versions can be verified on the AUX group sub-page 2, "SOFTWARE/DATABASE VER".

- C. IFR enroute and terminal navigation predicated upon the GNS 430's GPS Receiver is prohibited unless the pilot verifies the currency of the data base or verifies each selected waypoint for accuracy by reference to current approved data.
- D. Instrument approach navigation predicated upon the GNS 430's GPS Receiver must be accomplished in accordance with approved instrument approach procedures that are retrieved from the GPS equipment data base. The GPS equipment data base must incorporate the current update cycle.
 - Instrument approaches utilizing the GPS receiver must be conducted in the approach mode and Receiver Autonomous Integrity Monitoring (RAIM) must be available at the Final Approach Fix.

ISSUED: JULY 12, 1995 REVISED: NOVEMBER 6, 1998 REPORT: VB-1611

SECTION 2 - LIMITATIONS (continued)

- Accomplishment of ILS, LOC, LOC-BC, LDA, SDF, MLS or any other type of approach not approved for GPS overlay with the GNS 430's GPS receiver is not authorized.
- Use of the GNS 430 VOR/ILS receiver to fly approaches not approved for GPS require VOR/ILS navigation data to be present on the external indicator.
- 4. When an alternate airport is required by the applicable operating rules, it must be served by an approach based on other than GPS or Loran-C navigation, the aircraft must have the operational equipment capable of using that navigation aid, and the required navigation aid must be operational.
- VNAV information may be utilized for advisory information only. Use
 of VNAV information for Instrument Approach Procedures does not
 guarantee Step-Down Fix altitude protection, or arrival at approach
 minimums in normal position to land.
- E. If not previously defined, the following default settings must be made in the "SETUP 1" menu of the GNS 430 prior to operation (refer to Pilot's Guide for procedure if necessary):
 - 1. dis, spd...... $^{n}_{m}$ ^{k}t (sets navigation units to "nautical miles" and "knots")
 - 2. alt, vs...... f t fpm (sets altitude units to "feet" and "feet per minute")
 - 3. map datum..WGS 84 (sets map datum to WGS-84, see not below)
 - 4. posn.....deg-min (sets navigation grid units to decimal minutes)

NOTE

In some areas outside the United States, datums other than WGS-84 or NAD-83 may be used. If the GNS 430 is authorized for use by the appropriate Airworthiness authority, the required geodetic datum must be set in the GNS 430 prior to its use for navigation.

SECTION 3 - EMERGENCY PROCEDURES

ABNORMAL PROCEDURES

- A. If GARMIN GNS 430 navigation information is not available or invalid, utilize remaining operational navigation equipment as required.
- B. If "RAIM POSITION WARNING" message is displayed the system will flag and no longer provide GPS based navigational guidance. The crew should revert to the GNS 430 VOR/ILS receiver or an alternate means of navigation other than the GNS 430's GPS receiver.
- C. If "RAIM IS NOT AVAILABLE" message is displayed in the enroute, terminal, or initial approach phase of flight, continue to navigate using the GPS equipment or revert to an alternate means of navigation other than the GNS 430's GPS receiver appropriate to the route and phase of flight. When continuing to use GPS navigation, position must be verified every 15 minutes using the GNS 430's VOR/ILS receiver or another IFR-approved navigation system.
- D. If "RAIM IS NOT AVAILABLE" message is displayed while on the final approach segment, GPS based navigation will continue for up to 5 minutes with approach CDI sensitivity (0.3 nautical mile). After 5 minutes the system will flag and no longer provide course guidance with approach sensitivity. Missed approach course guidance may still be available with 1 nautical mile CDI sensitivity by executing the missed approach.
- E. In an in-flight emergency, depressing and holding the Comm transfer button for 2 seconds will select the emergency frequency of 121.500 Mhz into the "Active" frequency window.

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SECTION 4 - NORMAL PROCEDURES

WARNING

Familiarity with the enroute operation of the GNS 430 does not constitute proficiency in approach operations. Do not attempt approach operations in IMC prior to attaining proficiency in the use of the GNS 430 approach feature.

A. DETAILED OPERATING PROCEDURES

Normal operating procedures are described in the GARMIN GNS 430 Pilot's Guide, p/n 190-00140-00, Rev. A, dated October 1998, or later appropriate revision.

B. PILOT'S DISPLAY

The GNS 430 System data will appear on the Pilot's HSI. The source of data is either GPS or VLOC as annunciated on the display above the CDI key.

C. AUTOPILOT/FLIGHT DIRECTOR OPERATION

Coupling of the GNS 430 System steering information to the autopilot/flight director can be accomplished by engaging the autopilot/flight director in the NAV or APR mode.

When the autopilot/flight director system is using course information supplied by the GNS 430 System and the course pointer is not automatically driven to the desired track, the course pointer on the HSI must be manually set to the desired track (DTK) indicated by the GNS 430. For detailed autopilot/flight director operational instructions, refer to the FAA Approved Flight Manual Supplement for the autopilot/flight director.

SECTION 4 - NORMAL PROCEDURES (continued)

D. AUTOMATIC LOCALIZER COURSE CAPTURE

By default, the GNS 430 automatic localizer course capture feature is enabled. This feature provides a method for system navigation data present on the external indicators to be switched automatically from GPS guidance to localizer / glide slope guidance at the point of course intercept on a localizer at which GPS derived course deviation equals localizer derived course deviation. If an offset from the final approach course is being flown, it is possible that the automatic switch from GPS course guidance to localizer / glide slope course guidance will not occur. It is the pilot's responsibility to ensure correct system navigation data is present on the external indicator before continuing a localizer based approach beyond the final approach fix.

SECTION 5 - PERFORMANCE

No change.

SECTION 6 - WEIGHT AND BALANCE

Factory installed optional equipment is included in the licensed weight and balance data in Section 6 of the basic Pilot's Operating Handbook.

SECTION 7 - DESCRIPTION AND OPERATION

See GNS 430 Pilot's Guide for a complete description of the GNS 430 system.

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REPORT: VB-1611

9-47

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ISSUED: JULY 12, 1995 REVISED: NOVEMBER 6, 1998

SUPPLEMENT NO. 8 FOR S-TEC SYSTEM 55 TWO AXIS AUTOMATIC FLIGHT GUIDANCE SYSTEM WITH TRIM MONITOR

This supplement must be attached to the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual when the S-TEC System 55 Autopilot is installed per STC SA8402SW-D. The information contained herein supplements or supersedes the basic Pilot's Operating Handbook and FAA Approved Airplane Flight Manual only in those areas listed herein. For limitations, procedures and performance information not contained in the supplement, consult the basic Pilot's Operating Handbook and FAA Approved Airplane Flight Manual.

FAA APPROVED

PETÉR E. PECK D.O.A. NO. SO-1

THE NEW PIPER AIRCRAFT, INC.

VERO BEACH, FLORIDA

DATE OF APPROVAL: DECEMBER 18, 1998

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9-49

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SUPPLEMENT NO. 9
FOR
S-TEC MANUAL ELECTRIC TRIM SYSTEM
WITH TRIM MONITOR
(Serial numbers 2843058 and up)

The FAA approved operational supplement for the S-TEC Manual Electric Trim System, installed in accordance with STC SA8388SW-D, is required for operation of this system. S-TEC will be responsible to supply and revise the operational supplement. It is permitted to include the S-TEC supplement in this location of the Pilot's Operating Handbook unless otherwise stated by S-TEC. The information contained in the S-TEC supplement may supersede or supplement the information in the basic Pilot's Operating Handbook and FAA Approved Airplane Flight Manual with respect to the operation of the S-TEC Manual Electric Trim System. For limitations, procedures and performance information not contained in the S-TEC supplement, consult the basic Pilot's Operating Handbook and FAA Approved Airplane Flight Manual.

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9-51

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SUPPLEMENT NO. 10 FOR B.F. GOODRICH SKYWATCH TRAFFIC ADVISORY SYSTEM MODEL SKY497

This supplement must be attached to the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual when the optional BF Goodrich Skywatch Traffic Advisory System, Model SKY497 is installed per the Equipment List. The information contained herein supplements or supersedes the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual only in those areas listed herein. For limitations, procedures and performance information not contained in this supplement, consult the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual.

FAA APPROVED:

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THE NEW PIPER AIRCRAFT, INC.

VERO BEACH, FLORIDA

DATE OF APPROVAL: July 14, 2000

ISSUED: JULY 12, 1995 REVISED: JULY 14, 2000 REPORT: VB-1611 1 of 6, 9-53

SECTION 1 - GENERAL

The SKYWATCH system is an on-board traffic advisory system which monitors a radius of 10 nautical miles, of which a maximum of 6 nautical miles are displayed, about the aircraft by interrogating any "intruding" aircraft transponder, and determines if a potential conflict exists with other aircraft. This is done by computing the range, altitude, bearing, and closure rate of other transponder equipped aircraft, with respect to the SKYWATCH equipped aircraft.

SKYWATCH requires the following other equipment to be functional and operating:

No. 1 GNS 430 Encoding Altimeter or Blind Encoder

The SKYWATCH system provides a single level of threat advisory known as a Traffic Advisory (TA). The TA display indicates the relative position of an intruder when it is approximately 30 seconds from Closest Point of Approach (CPA). In addition, all aircraft detected less than 0.55 nm and +/- 800 feet from own aircraft will cause a TA to be generated.

The TA calls attention to a possible collision threat using the GNS 430 display and the voice message "TRAFFIC, TRAFFIC". The TA is intended to assist the pilot in achieving visual acquisition of the threat aircraft.

SKYWATCH is considered a backup system to the "SEE AND AVOID" concept and the ATC radar environment.

SKYWATCH data is presented on the Garmin No. 1 GNS 430 and/or No. 2 GNS 430 nav display. See the POH supplements for operating instructions for these items of equipment. The Standby/Operate feature is controlled by the No. 1 GNS 430.

SECTION 2 - LIMITATIONS

Information shown on the display is provided to the pilot as an aid to visually acquiring traffic. Pilot's should maneuver their aircraft based only on ATC guidance or positive visual acquisition of the conflicting traffic. Maneuver should be consistent with ATC instructions. No maneuvers should be made based only on a Traffic Advisory. ATC should be contacted for resolution of the Traffic conflict.

If the pilot is advised by ATC to disable transponder altitude reporting, SKYWATCH must be turned OFF.

Operation of the SKYWATCH system requires that the SKYWATCH Pilot's Guide, p/n 009-10801-001, Rev. A, or latest revision, and the Garmin 400 Series Pilot's Guide Addendum, p/n 190-00140-10, Rev. A, or latest revision, be kept on the aircraft and available to the pilot at all times.

SKYWATCH can only detect aircraft which are transponder equipped.

SECTION 3 - EMERGENCY PROCEDURES

No change.

SECTION 4 - NORMAL PROCEDURES

SELF TEST

The SKYWATCH operator initiated self test should be run prior to the first flight of the day.

After completion of self test, the "TRAFFIC ADVISORY SYSTEM TEST PASSED" audio annunciation will be heard and the display will revert to the standby screen.

ISSUED: JULY 12, 1995 REVISED: JULY 14, 2000

REPORT: VB-1611 3 of 6, 9-55

SECTION 4 - NORMAL PROCEDURES (continued)

SELF TEST (continued)

If "TRAFFIC ADVISORY SYSTEM TEST FAILED" is heard or the SKY497 FAILED screen appears, the SKYWATCH system should be turned OFF.

NOTE

The operator initiated Self-Test can only be performed when in standby or failed mode.

STANDBY CHARACTERISTICS

The SKYWATCH system will display STANDBY when in the standby mode. Selecting OPR activates the system and changes the display from the Standby screen to the Above (ABV) mode and 6 nm range. The ranges available are 6 nm, 5 nm, and 2 nm, and are selected by pressing the Display Range Button.

To go back into Standby, select STBY mode. The system will go to the STANDBY screen and will not track targets again until the system is manually switched out of Standby.

The Self Test works while in the Standby screen by pressing the Menu Button and selecting Self Test.

The SKYWATCH system, while in flight or operating on the ground, will display 4 altitude display modes. These are: Above (ABV), Normal (NRM), Below (BLW), and Unrestricted (UNR). These modes are accessed through the GNS selector knobs. Refer to the SKYWATCH Traffic Advisory System Model SKY497 pilot's guide, p/n 009-10801-001, Rev. A, or latest revision and the Garmin 400 Series Pilot's Guide Addendum, p/n 190-00140-10, Rev A, or latest revision.

SECTION 4 - NORMAL PROCEDURES (continued)

ABNORMAL PROCEDURES

If "TRAFFIC ADVISORY SYSTEM TEST FAILED" is heard or the SKY497 FAILED screen appears, the SKYWATCH system should be turned OFF.

If the barometric altimeter fails in flight and is the altitude source for the transponder, turn SKYWATCH OFF.

RESPOND TO TRAFFIC ADVISORIES

When the SKY497 issues a TA, scan outside for the intruder aircraft. Call ATC for guidance and if you visually acquire the traffic, use normal right of way procedures to maintain separation.

Do not attempt maneuvers based solely on traffic information shown on the SKY497 display. Information on the display is provided to the flight crew as an aid in visually acquiring traffic; it is not a replacement for ATC and SEE and AVOID techniques.

SECTION 5 - PERFORMANCE

No change.

SECTION 6 - WEIGHT AND BALANCE

Factory installed optional equipment is included in the licensed weight and balance data in the Equipment List attached to the Pilot's Operating Handbook.

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REPORT: VB-1611 9-58, 6 of 6

SUPPLEMENT NO. 11 FOR BF GOODRICH AEROSPACE WX-500 STORMSCOPE - SERIES II WEATHER MAPPING SENSOR

This supplement must be attached to the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual when the BF Goodrich Aerospace WX-500 Stormscope is installed per the equipment list. The information contained herein supplements or supersedes the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual only in those areas listed herein. For limitations, procedures and performance information not contained in this supplement, consult the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual.

FAA APPROVED

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VERO BEACH, FLORIDA

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REPORT: VB-1611 1 of 4, 9-59

SECTION 1 - GENERAL

This supplement provides information necessary for the operation of the aircraft with the BF Goodrich WX-500 Stormscope.

WARNING

Never use your Stormscope system to attempt a thunderstorm. The FAA Advisory Circular, Subject: Thunderstorms, and the Airman's Information Manual (AIM) recommend that a pilot "avoid by at least 20 miles any thunderstorm identified as severe or giving an intense radar echo."

CAUTION

There are several atmospheric phenomena other than nearby thunderstorms that can cause isolated discharge points in the strike display mode. Clusters of two or more discharge points in the strike display mode, however, do indicate thunderstorm activity when they reappear after clearing the screen. Avoid the clusters and you'll avoid the thunderstorms. In the cell display mode, even a single discharge point may represent thunderstorm activity and should be avoided.

SECTION 2 - LIMITATIONS

The BF Goodrich Aerospace WX-500 Stormscope Users Guide, p/n 009-11501-001, Rev. A, dated September 10, 1997, or later appropriate revision, must be immediately available to the flight crew whenever weather avoidance is predicated on the use of this system.

SECTION 3 - EMERGENCY PROCEDURES

No change.

REPORT: VB-1611 9-60, 2 of 4

SECTION 4 - NORMAL PROCEDURES

Normal operating procedures are described in the BF Goodrich Aerospace WX-500 Stormscope Users Guide, p/n 009-11501-001, Rev. A, dated September 10, 1997, or later appropriate revision.

SECTION 5 - PERFORMANCE

No change.

SECTION 6 - WEIGHT AND BALANCE

Factory installed optional equipment is included in the licensed empty weight and balance data in Section 6 of the Pilot's Operating Handbook.

SECTION 7 - DESCRIPTION AND OPERATION

A. OPERATING PROCEDURES

See the BF Goodrich Aerospace WX-500 Stormscope Users Guide for a complete description of the WX-500 system.

B. PILOT'S DISPLAY (Airplane Dependent)

The BF Goodrich Aerospace WX-500 Stormscope's data will appear on either of the Garmin GNS 430's.

ISSUED: JULY 12, 1995 REVISED: JULY 14, 2000 REPORT: VB-1611 3 of 4, 9-61

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SUPPLEMENT NO. 12 FOR GARMIN GNS 430 VHF COMMUNICATION TRANSCEIVER/VOR/ILS RECEIVER/GPS RECEIVER WITH TRAFFIC ADVISORY & LIGHTNING STRIKE ADVISORY DATA

This supplement must be attached to the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual when the Garmin GNS 430 VHF Communication Transceiver/VOR/ILS Receiver/GPS Receiver with Traffic Advisory & Lightning Strike Advisory Data is installed per the Equipment List. The information contained herein supplements or supersedes the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual only in those areas listed herein. For limitations, procedures and performance information not contained in this supplement, consult the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual.

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SECTION 1 - GENERAL

The GNS 430 System is a fully integrated, panel mounted instrument, which contains a VHF Communications Transceiver, a VOR/ILS Receiver, and a Global Positioning System (GPS) Navigation computer. The system consists of a GPS Antenna, GPS Receiver, VHF VOR/LOC/GS Antenna, VOR/ILS Receiver, VHF COMM Antenna and a VHF Communications Transceiver. The primary function of the VHF Communication portion of the equipment is to facilitate communication with Air Traffic Control. The primary function of the VOR/ILS Receiver portion of the equipment is to receive and demodulate VOR, Localizer, and Glide Slope signals. The primary function of the GPS portion of the system is to acquire signals from the GPS system satellites, recover orbital data, make range and Doppler measurements, and process this information in real-time to obtain the user's position, velocity, and time.

Provided the GARMIN GNS 430's GPS receiver is receiving adequate usable signals, it has been demonstrated capable of and has been shown to meet the accuracy specifications for:

- VFR/IFR enroute, terminal, and non-precision instrument approach (GPS, Loran-C, VOR, VOR-DME, TACAN, NDB, NDB- DME, RNAV) operation within the U.S. National Airspace System in accordance with AC 20-138.
- One of the approved sensors, for a single or dual GNS 430 installation, for North Atlantic Minimum Navigation Performance Specification (MNPS) Airspace in accordance with AC 91-49 and AC 120-33.
- The system meets RNP5 airspace (BRNAV) requirements of AC 90-96 and in accordance with AC 20-138, and JAA AMJ 20X2 Leaflet 2 Revision 1, provided it is receiving usable navigation information from the GPS receiver.

NOTE

Navigation is accomplished using the WGS-84 (NAD-83) coordinate reference datum. Navigation data is based upon use of only the Global Positioning System (GPS) operated by the United States of America.

REPORT: VB-1611 ISSUED: JULY 12, 1995 9-64. 2 of 8 REVISED: JULY 14, 2000

SECTION 2 - LIMITATIONS

A. The GARMIN GNS 430 Pilot's Guide, p/n 190-00140-00, Rev. A, dated October 1998, or later appropriate revision, must be immediately available to the flight crew whenever navigation is predicated on the use of the system.

The Garmin 400 Series Pilot's Guide Addendum, p/n 190-00140-10, Rev. A, dated October 1999, Display Interface for Traffic and Weather Data, must be immediately available to the flight crew if the BF Goodrich WX-500 Stormscope or the BF Goodrich SKYWATCH Traffic Advisory System (TAS) is installed.

B. The GNS 430 must utilize the following or later FAA approved software versions:

Sub-System	Software Version 2.00	
Main		
GPS	2.00	
Comm	1.22	
VOR/LOC	1.25	
G/S	2.00	

The main software version is displayed on the GNS 430 self test page immediately after turn-on for 5 seconds. The remaining system software versions can be verified on the AUX group sub-page 2, "SOFTWARE/DATABASE VER".

ISSUED: JULY 12, 1995 REVISED: JULY 14, 2000 REPORT: VB-1611 3 of 8, 9-65

SECTION 2 - LIMITATIONS (continued)

- C. IFR enroute and terminal navigation predicated upon the GNS 430's GPS Receiver is prohibited unless the pilot verifies the currency of the data base or verifies each selected waypoint for accuracy by reference to current approved data.
- D. Instrument approach navigation predicated upon the GNS 430's GPS Receiver must be accomplished in accordance with approved instrument approach procedures that are retrieved from the GPS equipment data base. The GPS equipment data base must incorporate the current update cycle.
- E. Instrument approaches utilizing the GPS receiver must be conducted in the approach mode and Receiver Autonomous Integrity Monitoring (RAIM) must be available at the Final Approach Fix.
- F. Accomplishment of ILS, LOC, LOC-BC, LDA, SDF, MLS or any other type of approach not approved for GPS overlay with the GNS 430's GPS receiver is not authorized.
- G. Use of the GNS 430 VOR/ILS receiver to fly approaches not approved for GPS require VOR/ILS navigation data to be present on the external indicator.
- H. When an alternate airport is required by the applicable operating rules, it must be served by an approach based on other than GPS or Loran-C navigation, the aircraft must have the operational equipment capable of using that navigation aid, and the required navigation aid must be operational.
- I. VNAV information may be utilized for advisory information only. Use of VNAV information for Instrument Approach Procedures does not guarantee Step-Down Fix altitude protection, or arrival at approach minimums in normal position to land.

SECTION 2 - LIMITATIONS (continued)

J. If not previously defined, the following default settings must be made in the "SETUP 1" menu of the GNS 430 prior to operation (refer to Pilot's Guide for procedure if necessary):

n k			
1. dis, spdm	t (sets navigation units to	"nautical miles" and	d "knots")

- 2. alt, vs......ft fpm (sets altitude units to "feet" and "feet per minute")
- 3. map datum...WGS 84 (sets map datum to WGS-84, see not below)
- 4. posn.....deg-min (sets navigation grid units to decimal minutes)

NOTE

In some areas outside the United States, datums other than WGS-84 or NAD-83 may be used. If the GNS 430 is authorized for use by the appropriate Airworthiness authority, the required geodetic datum must be set in the GNS 430 prior to its use for navigation.

ISSUED: JULY 12, 1995 REVISED: JULY 14, 2000 REPORT: VB-1611 5 of 8, 9-67

SECTION 3 - EMERGENCY PROCEDURES

ABNORMAL PROCEDURES

- A. If GARMIN GNS 430 navigation information is not available or invalid, utilize remaining operational navigation equipment as required.
- B. If "RAIM POSITION WARNING" message is displayed the system will flag and no longer provide GPS based navigational guidance. The crew should revert to the GNS 430 VOR/ILS receiver or an alternate means of navigation other than the GNS 430's GPS receiver.
- C. If "RAIM IS NOT AVAILABLE" message is displayed in the enroute, terminal, or initial approach phase of flight, continue to navigate using the GPS equipment or revert to an alternate means of navigation other than the GNS 430's GPS receiver appropriate to the route and phase of flight. When continuing to use GPS navigation, position must be verified every 15 minutes using the GNS 430's VOR/ILS receiver or another IFR-approved navigation system.
- D. If "RAIM IS NOT AVAILABLE" message is displayed while on the final approach segment, GPS based navigation will continue for up to 5 minutes with approach CDI sensitivity (0.3 nautical mile). After 5 minutes the system will flag and no longer provide course guidance with approach sensitivity. Missed approach course guidance may still be available with 1 nautical mile CDI sensitivity by executing the missed approach.
- E. In an in-flight emergency, depressing and holding the Comm transfer button for 2 seconds will select the emergency frequency of 121.500 Mhz into the "Active" frequency window.

ISSUED: JULY 12, 1995 REVISED: JULY 14, 2000

SECTION 4 - NORMAL PROCEDURES (continued)

E. DISPLAY OF LIGHTNING STRIKE DATA

Lightning strike data detected by the BF Goodrich WX-500 Stormscope will appear on the moving map and weather pages of the GNS 430. For detailed operating instructions regarding the interface of the GNS 430 with the WX-500, refer to the WX-500 Pilot's Guide and the GNS 430 Pilot's Guide Addendum for the WX-500 Stormscope interface.

F. DISPLAY OF TRAFFIC ADVISORY DATA

Traffic data detected by the BF Goodrich SKYWATCH™ Traffic Advisory System (TAS) will appear on the moving map and traffic display pages of the GNS 430. For detailed operating instructions regarding the interface of the GNS 430 with the SKYWATCH, refer to the FAA approved Flight Manual Supplement for the SKYWATCH, the Pilot's Guide for the SKYWATCH and the GNS 430 Pilot's Guide Addendum for the SKYWATCH Traffic Advisory System interface.

SECTION 5 - PERFORMANCE

No Change.

SECTION 6 - WEIGHT AND BALANCE

Factory installed optional equipment is included in the licensed weight and balance data in the Equipment List attached to the Pilot's Operating Handbook.

SECTION 7 - DESCRIPTION AND OPERATION

See the GNS 430 Pilot's Guide for a complete description of the GNS 430 system.

REPORT: VB-1611 ISSUED: JULY 12, 1995 9-70. 8 of 8 REVISED: JULY 14, 2000

PILOT'S OPERATING HANDBOOK AND FAA APPROVED AIRPLANE FLIGHT MANUAL

SUPPLEMENT NO. 13 FOR GARMIN GTX 327 TRANSPONDER

This supplement must be attached to the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual when the Garmin GTX 327 Transponder is installed per the Equipment List. The information contained herein supplements or supersedes the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual only in those areas listed herein. For limitations, procedures and performance information not contained in this supplement, consult the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual.

FAA APPROVED:

CHRISTINA L. MARSH

D.O.A. NO. SO- 1

THE NEW PIPER AIRCRAFT, INC.

VERO BEACH, FLORIDA

DATE OF APPROVAL: January 2, 2001

ISSUED: JULY 12, 1995 REVISED: JANUARY 2, 2001 REPORT: VB-1611 | 1 of 10, 9-71 |

SECTION 1 - GENERAL

This supplement supplies information necessary for the operation of the airplane when the Garmin GTX 327 Transponder is installed in accordance with FAA approved Piper data.

SECTION 2 - LIMITATIONS

No change.

SECTION 3 - EMERGENCY PROCEDURES

To transmit an emergency signal:

- · Mode Selection Key ALT
- Code Selection SELECT 7700

To transmit a signal representing loss of all communications:

- Mode Selection Key ALT
- Code Selection SELECT 7600

SECTION 4 - NORMAL PROCEDURES

BEFORE TAKEOFF:

- To transmit Mode C (Altitude Reporting) code in flight:
- Mode Selection Key ALT
- Code Selector Keys SELECT assigned code.

To transmit Mode A (Aircraft Identification) code in flight:

- · Mode Selector Key ON
- · Code Selector Keys SELECT assigned code.

NOTE

During normal operation with the ON mode selected, the reply indicator "R" flashes, indicating transponder replies to interrogations.

NOTE

Mode A reply codes are transmitted in ALT also; however, Mode C codes only are suppressed when the Function Selector ON key is selected.

SECTION 5 - PERFORMANCE

No change.

SECTION 6 - WEIGHT AND BALANCE

Factory installed optional equipment is included in the licensed weight and balance data in section 6 of the Airplane Flight Manual.

SECTION 7 - DESCRIPTION AND OPERATION



The GTX 327 transponder is powered on by pressing the STBY, ALT or ON keys, or by a remote avionics master switch (if applicable). After power on, a start-up page will be displayed while the unit performs a self test.

Mode Selection Keys

OFF - Powers off the GTX 327.

STBY - Powers on the transponder in standby mode. At power on the last active identification code will be selected. When in standby mode, the transponder will not reply to any interrogations.



ON - Powers on the transponder in Mode A. At power on the last active identification code will be selected. In this mode, the transponder replies to interrogations, as indicated by the Reply Symbol **R**. Replies do not include altitude information.

ALT -Powers on the transponder in Mode A and Mode C. At power on the last active identification code will be selected. In ALT mode, the transponder replies to identification and altitude interrogations, as indicated by the Reply Symbol . Replies to altitude interrogations include the standard pressure altitude received from an external altitude source, which is not adjusted for barometric pressure. The ALT mode may be used in aircraft not equipped with the optional altitude encoder; however, the reply signal will not include altitude information.

GTX 327 Configuration Mode

The GTX 327's configuration, which is normally done at time of installation, influences many of the unit's functions described in this manual. If you wish to view or change any of the GTX 327 configuration parameters, you may access the GTX 327 Configuration Mode. Use caution when changing configuration. When in doubt, contact your authorized GARMIN Aviation Service Center. The Configuration Mode should not be used while the aircraft is airborne.

REPORT: VB-1611 9-74, 4 of 10

GTX 327 Configuration Mode (continued)

To use the GTX 327 Configuration Mode:

- 1. Press and hold the FUNC key while powering on the unit using the STBY, ON, or ALT key (or using an avionics master switch).
- 2. Press the **FUNC** key to sequence through the configuration pages.
- 3. Use the CRSR key to highlight selectable fields on each page.
- 4. When a field is highlighted, enter numeric data using the 0 9 keys, and select items from a list using the 8 or 9 keys.
- 5. Press the CRSR key to confirm list selections.

Code Selection



Code selection is done with eight keys (0 - 7) that provide 4,096 active identification codes. Pushing one of these keys begins the code selection sequence. The new code will not be activated until the fourth digit is entered. Pressing the CLR key will move the cursor back to the previous digit. Pressing the CLR key when the cursor is on the first digit of the code, or pressing the CRSR key during code entry, will remove the cursor and cancel data entry, restoring the previous code. The numbers 8 and 9 are not used for code entry, only for entering a Count Down time, and in the Configuration Mode.



Code Selection (continued)

Important Codes:

1200 - The VFR code for any altitude in the US (Refer to ICAO standards elsewhere)

7000 - The VFR code commonly used in Europe (Refer to ICAO standards)

7500 - Hijack code (Aircraft is subject to unlawful interference)

7600 - Loss of communications

7700 - Emergency

7777 - Military interceptor operations (Never squawk this code)

0000 - Military use (Not enterable)

Care should be taken not to select the code 7500 and all codes in the 7600 - 7777 range, which trigger special indicators in automated facilities. Only the code 7500 will be decoded as the hijack code. An aircraft's transponder code (when available) is utilized to enhance the tracking capabilities of the ATC facility, therefore care should be taken when making routine code changes.

Keys for Other GTX 327 Functions



IDENT - Pressing the IDENT key activates the Special Position Identification (SPI) Pulse for 18 seconds, identifying your transponder return from others on the air traffic controller's screen. The word "IDENT" will appear in the upper left corner of the display while the IDENT mode is active.



VFR - Sets the transponder code to the pre-programmed VFR code selected in Configuration Mode (this is set to 1200 at the factory). Pressing the VFR key again will restore the previous identification code.



FUNC - Changes the page shown on the right side of the display. Displayed data includes Pressure Altitude, Flight Time, Count Up timer, Count Down timer, and may include Contrast and Display Brightness, depending on configuration (as shown in the screens below):

ISSUED: JULY 12, 1995

REVISED: JANUARY 2, 2001

SECTION 7 - DESCRIPTION AND OPERATION (continued) Keys for Other GTX 327 Functions (continued)

PRESSURE ALT: Displays the altitude data supplied to the GTX 327 in feet, hundreds of feet (i.e., flight level), or meters, depending on configuration.

FLIGHT TIME: Displays the Flight Time, which is controlled by the START/STOP key or by a squat switch as configured during installation. With squat switch control, the timer begins when lift off is sensed and pauses when landing is sensed.

COUNT UP TIMER: Controlled by START/STOP and CLR keys.

COUNT DOWN TIMER: Controlled by START/STOP, CLR, and CRSR keys. The initial Count Down time is entered with the 0 - 9 keys.

CONTRAST: This page is only displayed if manual contrast mode is selected in Configuration Mode. Contrast is controlled by the 8 and 9 keys.

DISPLAY: This page is only displayed if manual backlighting mode is selected in Configuration Mode. Backlighting is

controlled by the 8 and 9 keys.

START/STOP - Starts and stops the Count Up and Count Down timers.

CRSR - Initiates entry of the starting time for the Count Down timer and cancels transponder code entry.

CLR - Resets the Count Up and Count Down timers and cancels the previous keypress during code selection.

8 - Reduces Contrast and Display Brightness when the respective pages are displayed. Also enters the number 8 into the Count Down timer.

9 - Increases Contrast and Display Brightness when the respective pages are displayed. Also enters the number 9 into the Count Down timer.

ISSUED: JULY 12, 1995

REVISED: JANUARY 2, 2001

SECTION 7 - DESCRIPTION AND OPERATION (continued) Altitude Trend Indicator

When the "PRESSURE ALT" page is displayed, an arrow may be displayed to the right of the altitude, indicating that the altitude is increasing or decreasing. One of two sizes of arrows may be displayed depending on the rate of climb/descent. The sensitivity of these arrows is set using the GTX Configuration Mode.

Timer Operation

To operate the Flight Timer:

- 1. Press the FUNC key until "FLIGHT TIME" is displayed.
- 2. If the GTX 327 is configured as having a squat switch installed, the timer will begin counting automatically when the squat switch senses that the aircraft has become airborne.
- 3. If desired, you may press START/STOP to pause or restart the timer.
- 4. Press CLR to reset the timer to zero.
- 5. If the GTX 327 is configured as having a squat switch installed, the timer will pause automatically when the squat switch senses that the aircraft has touched down.

To operate the Count Up timer:

- 1. Press the FUNC key until "COUNT UP" is displayed.
- 2. If necessary, press CLR to reset the Count Up timer to zero.
- 3. Press START/STOP to count up.
- 4. Press START/STOP again to pause the timer.
- 5. Press CLR to reset the timer to zero.

To operate the Count Down timer:

- 1. Press the FUNC key until "COUNT DOWN" is displayed.
- 2. Press **CRSR** and use the **0 9** keys to set the initial time. All digits must be entered (use the 0 key to enter leading zeros).
- Press START/STOP to count down.
- 4. Press START/STOP again to pause the timer.
- When the Count Down timer expires, the words "COUNT DOWN' are replaced with "EXPIRED", and the time begins counting up and flashing.
- 6. Press CLR to reset the timer to the initial time value.

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REPORT: VB-1611 9-80, 10 of 10

PILOT'S OPERATING HANDBOOK AND FAA APPROVED AIRPLANE FLIGHT MANUAL

SUPPLEMENT NO. 14 FOR S-TEC SYSTEM 55X TWO AXIS AUTOMATIC FLIGHT GUIDANCE SYSTEM

The FAA approved operational supplement for the S-TEC System 55X Autopilot, installed in accordance with STC SA8402-SW-D, is required for operation of this system. S-TEC will be responsible to supply and revise the operational supplement. It is permitted to include the S-TEC supplement in this location of the Pilot's Operating Handbook unless otherwise stated by S-TEC. The information contained in the S-TEC supplement may supersede or supplement the information in the basic Pilot's Operating Handbook and FAA Approved Airplane Flight Manual with respect to the operation of the S-TEC System 55X Autopilot. For limitations, procedures and performance information not contained in the S-TEC supplement, consult the basic Pilot's Operating Handbook and FAA Approved Airplane Flight Manual.

ISSUED: JULY 12, 1995 REVISED: JANUARY 2, 2001 REPORT: VB-1611

9-81

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S-TEC (.PORATION MINERAL WELLS, TEXAS 76067

FAA/DAS APPROVED
PILOT'S OPERATING HANDBOOK AND/OR
AIRPLANE FLIGHT MANUAL SUPPLEMENT
FOR

PIPER MODEL PA-28-181 WITH

S-TEC SYSTEM 55/55X TWO AXIS AUTOMATIC FLIGHT GUIDANCE SYSTEM

WITH TRIM MONITOR (28 VOLT SYSTEM)

REG. NO. SE-ILV

SER. NO. 2843426

This Supplement must be attached to the applicable FAA Approved Airplane Flight Manual, Pilot's Operating Handbook, or Pilot's Operating Handbook and FAA Approved Airplane Flight Manual for aircraft modified by the nstallation of S-TEC System 55/55X Autopilot Model ST-548 installed in coordance with STC SA8402SW-D. The information contained herein supplements or supersedes the basic manual. For limitations, procedures and performance information not contained in this supplement, consult the basic Pilot's Operating Handbook and/or Airplane Flight Manual.

SECTION I

GENERAL

This manual is to acquaint the pilot with the features and functions of the System 55/55X Two Axis Autopilot and to provide operating instructions for the system when installed in the listed aircraft model(s). The aircraft must be operated within the limitations herein provided when the autopilot is in use.

FAA/DAS APPROVED

Iter F. Davis

S-TEC CORPORATION

DAS 5 SW P/N: 891752 DATE: 6-18-98

S-TEC C_PORATION MINERAL WELLS, TEXAS 76067

FAA/DAS APPROVED PILOT'S OPERATING HANDBOOK AND/OR AIRPLANE FLIGHT MANUAL SUPPLEMENT FOR PIPER MODEL PA-28-181

REV. NO.	PAGES AFFECTED	DESCRIPTION	APPROVED	DATE
1	Page 4	Added a Note to Normal Operating Procedures regarding altitude hold capture.	W.F.D	10-05-98
2	Pages 1, 3, 4, 6, 7, 8	Added System 55X information. Removed Optional Equipment section. Renumbered pages.	WFD	11-20-00
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FAA/DAS APPROVED P/N: 891752 DATE: 6-18-98

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PIPER MODEL PA-28-181

SECTION II

OPERATING LIMITATIONS

1. Autopilot operation prohibited above 140 KIAS.

 Autopilot coupled missed approach or go-around maneuver not authorized.

3. Autopilot must be "OFF" during take off and landing.

4. Flap limitations: Maximum flap deflection is limited to $10\,^\circ$ (one notch) with autopilot engaged.

5. Category I operations only.

Autopilot use prohibited below 200' AGL during coupled approach operations.

7. S-TEC System 55 Pilot's Operating Handbook, P/N 8747, dated 10-16-00 or later revision, or S-TEC System 55X Pilot's Operating Handbook, P/N 87109, dated 11-08-00 or later revision, must be carried in the aircraft and be available to the pilot while in flight.

SECTION III

EMERGENCY OPERATING PROCEDURES

In the event of an autopilot malfunction, or anytime the autopilot is not performing as expected or commanded, do not attempt to identify the system problem. Immediately regain control of the aircraft by overpowering the autopilot as necessary and then immediately disconnect the autopilot. Do not re-engage the autopilot until the problem has been identified and corrected.

1. The autopilot may be disconnected by:

a. Depressing the "AP Disconnect" Switch on the left horn of the pilot's control wheel.

b. Placing the "AP Master Switch" in the "OFF" position.

c. Momentarily interrupting aircraft electrical power at the battery master switch.

d. Pulling the autopilot circuit breaker.

2. Trim:

a. In the event of a trim failure, manually control aircraft and $\frac{\text{DEPRESS}}{\text{Control wheel}}$ "Trim Interrupt/AP Disconnect Switch" on control wheel.

FAA/DAS APPROVED P/N: 891752 DATE: 6-18-98

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FAA/DAS APPROVED PILOT'S OPERATING HANDBOOK AND/OR AIRPLANE FLIGHT MANUAL SUPPLEMENT FOR

PIPER MODEL PA-28-181

b. Place trim master switch in "OFF" position, pull circuit breaker, release interrupt switch.

c. Retrim aircraft. Leave trim system OFF until corrected.

3. Altitude loss during a malfunction and recovery:

a. The following altitude losses and bank angles were recorded after a malfunction with a 3 second recovery delay:

Configuration
Climb
Cruise
Descent

Bank Angle/Altitude Loss
50°/-180'
55°/-160'
55°/-320'

b. The following altitude losses and bank angles were recorded after a malfunction with a 1 second recovery delay:

Configuration Bank Angle/Altitude Loss 18°/-60' Approach (Coupled or Uncoupled) 20°/-80'

The above values are the worst case for all the models covered by this document.

SECTION IV

NORMAL OPERATING PROCEDURES

For detailed normal operating procedures, including system description, pre-flight and in flight procedures refer to S-TEC System 55 Pilot's Operating Handbook, P/N 8747, dated 10-16-00 or later revision, or S-TEC System 55X Pilot's Operating Handbook, P/N 87109, dated 11-08-00 or later revision.

CAUTION: When S-TEC Flight Director is installed and operating, the Flight Director Autopilot should be disconnected using the control wheel disconnect switch only. Any other means of disconnect (breaker, ON-OFF switch, etc.) may leave steering bars in view, but inoperable.

Dais in view, but inoperable.

NOTE: For smoother altitude captures, thus enhancing passenger comfort, engage altitude hold mode at rates of climb of 1,000 FPM or less.

FAA/DAS APPRÓVED P/N: 891752 DATE: 6-18-98

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PILOT'S OPERATING HANDBOOK AND/OR
AIRPLANE FLIGHT MANUAL SUPPLEMENT
FOR

PIPER MODEL PA-28-181

CONTROL WHEEL SWITCHES

The left grip of the pilot's control wheel will normally contain the following autopilot switches:

- Manual Electric Trim
- Trim Interrupt/A/P Disconnect Switch
- Control Wheel Steering (CWS)

ELECTRIC TRIM SYSTEM

The S-TEC Electric Trim System is designed to accept any single failure, either mechanical or electrical, without uncontrolled operation resulting during operations in the Manual Electric Trim Mode. During autotrim mode the system is designed to limit the effect of any failure causing trim operation. In order to assure proper operation of these safeguards, it is necessary to conduct a simple pre-flight test of the system. Following is a brief description and a preflight test procedure for the trim system.

TRIM SYSTEM WITH TRIM MONITOR

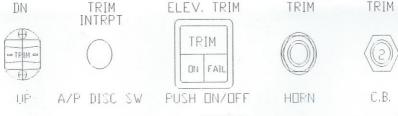


FIGURE 1

SYSTEM DESCRIPTION

The trim monitor system consists of the components pictured in Figure 1 and is designed to alert the pilot of a trim failure or trim in motion.

FAA/DAS APPROVED P/N: 891752 DATE: 6-18-98

S-TEC C PORATION MINERAL WELLS, TEXAS 76067

FAA/DAS APPROVED PILOT'S OPERATING HANDBOOK AND/OR AIRPLANE FLIGHT MANUAL SUPPLEMENT FOR

PIPER MODEL PA-28-181

The system is activated by pushing the trim master switch on. A green On light, a yellow Trim light and a red Fail light will illuminate in the witch and the trim audio horn will activate for one second, as a test. A trim fault will cause the Trim and Fail lights to illuminate along with continuous horn operation. The pilot should press and hold the red Trim Interrupt button and conduct the emergency procedures listed in Section III of this AFMS.

PREFLIGHT TRIM CHECK (With Trim Monitor)

MANUAL ELECTRIC TRIM - Test Prior To Each Flight

Check trim circuit breaker - IN 1.

Trim master switch - Push ON - confirm green light ON after 2. completion of test cycle.

A/P master switch - ON 3.

Operate trim switch (both knob sections) - NOSE DN. Check that trim 4. moves nose down and yellow trim light in trim master switch flashes while trim is in motion. The trim "in motion" indicator in the autopilot programmer should flash "TRIM" also. Conduct the same test in the NOSE UP direction.

With trim operating up or down depress the red control wheel interrupt switch for three seconds minimum. Confirm that trim action stops while switch is pressed. This action should also trigger the trim monitor horn with "Trim" steady and "Fail" flashing in the trim master switch. Recycle the trim master switch to delete the horn.

6. Overpower check - With trim operating electrically, grasp the manual trim wheel and overpower the electric trim to stop trim motion.

Operate each half of the trim switch separately - Trim should not operate unless both switch knob segments are moved together.

AUTOTRIM

Position elevator control half way aft from full forward.

2. Engage HDG and ALT modes of autopilot.

3. Grasp control and slowly apply forward pressure (nose down). After approximately 3 seconds automatic trim should run NOSE UP. yellow trim indicator in trim master switch should flash simultaneously with the trim indicator in the A/P programmer. Conduct the same test by slowly applying aft pressure on the

4. elevator control, confirming that autotrim runs $\underline{\text{NOSE DOWN}}$ and trim indicators flash while trim is in motion.

FAA/DAS APPROVED P/N: 891752 DATE: 6-18-98

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PIPER MODEL PA-28-181

Move manual trim switch up or down - Autopilot should disconnect and trim should operate in the commanded direction. (Trim switch will disconnect A/P only when a pitch mode is engaged.)

Reengage autopilot HDG and ALT modes - Press trim interrupt/AP

disconnect switch - Autopilot should disconnect.

 Retrim aircraft for take off - Check all controls for freedom of motion and determine that autopilot and trim have disconnected.

If either the manual electric or autotrim fails any portion of the above check procedure, push the Trim Master Switch "OFF" and do not attempt to use the trim system until the fault is corrected. With the Trim Master Switch "OFF" the autopilot trim indicators will return to operation. If the electric trim system suffers a power failure in flight the system will automatically revert to the trim indicator lights located in the autopilot annunciator panel. If this occurs push the Trim Master Switch "OFF" and trim manually, using the indicators until the fault can be located and corrected.

GLIDE SLOPE FLIGHT PROCEDURE

Approach the GS intercept point (usually the OM) with the flaps set to approach deflection of up to 1 notch, as desired (see Limitations section), and with the aircraft stabilized in altitude hold mode. At the glide slope intercept, adjust power for the desired descent speed. For best tracking results make power adjustments in small, smooth increments to maintain desired airspeed. At the missed approach point or the decision height, disconnect the autopilot for landing or for the go-around maneuver (See Limitations Section). If a missed approach is required, the autopilot may be reengaged after the aircraft has been reconfigured for and established in a stabilized climb.

SECTION V

PERFORMANCE

The text of this Section not affected by installation of this equipment.

SECTION VI

WEIGHT AND BALANCE

The text of this Section not affected by installation of this equipment.

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FAA/DAS APPROVED PILOT'S OPERATING HANDBOOK AND/OR AIRPLANE FLIGHT MANUAL SUPPLEMENT FOR

PIPER MODEL PA-28-181

SECTION VII

SYSTEMS DESCRIPTION AND OPERATION

The text of this Section not affected by installation of this equipment.

SECTION VIII

HANDLING, SERVICING, AND MAINTENANCE

The text of this Section not affected by installation of this equipment.

SECTION IX

SUPPLEMENTS

See information in this supplement for operation of the S-TEC System 55/55X Autopilot.

SECTION X

OPERATING TIPS

The text of this Section not affected by installation of this equipment.

FAA/DAS APPROVED P/N: 891752 DATE: 6-18-98

PILOT'S OPERATING HANDBOOK AND FAA APPROVED AIRPLANE FLIGHT MANUAL

SUPPLEMENT NO. 15 FOR S-TEC ADF-650A SYSTEM

This supplement must be attached to the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual when the S-TEC ADF-650A System is installed per the Equipment List. The information contained herein supplements or supersedes the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual only in those areas listed herein. For limitations, procedures and performance information not contained in this supplement, consult the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual.

FAA APPROVED:

CHRISTINA L. MARSH

D.O.A. NO. SO- 1

THE NEW PIPER AIRCRAFT, INC.

VERO BEACH, FLORIDA

DATE OF APPROVAL: January 2, 2001

ISSUED: JULY 12, 1995 REVISED: JANUARY 2, 2001 REPORT: VB-1611 1 of 6, 9-83

SECTION 1 - GENERAL

This supplement supplies information necessary for the operation of the airplane when the S-TEC ADF-650A System is installed in accordance with FAA approved Piper data.

SECTION 2 - LIMITATIONS

No change.

SECTION 3 - EMERGENCY PROCEDURES

No change.

REPORT: VB-1611 9-84 2 of 6

SECTION 4 - NORMAL PROCEDURES

To operate as an Automatic Direction Finder:

- OFF/VOL Control ON
- Frequency Selector Knobs SELECT desired frequency.
- ADF SPEAKER/PHONE Selector Switch (on audio control panel) -SELECT as desired.
- · OFF/VOL Control SET to desired volume level.
- ADF Mode Control Select ADF mode and note relative bearing on display.

ADF Test (Pre-flight or In-flight):

- ADF Mode Control Select ADF mode and note relative bearing on display.
- Press the TEST button and note the pointer moves to 90° from its prior position. Excessive pointer sluggishness, wavering or reversals indicate a signal that is too weak or a system malfunction.

To Operate BFO:

- OFF/VOL Control ON
- Frequency Selector Knobs SELECT desired frequency.
- ADF SPEAKER/PHONE Selector Switch (on audio control panel) -SELECT as desired.
- · ADF Mode Control Select BFO mode.
- OFF/VOL Control Set to desired volume level.

SECTION 5 - PERFORMANCE

No change.

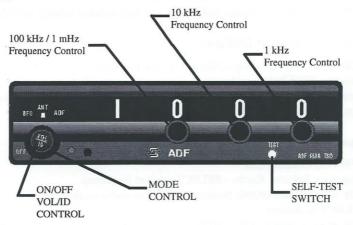
SECTION 6 - WEIGHT AND BALANCE

Factory installed optional equipment is included in the licensed weight and balance data in Section 6 of the Pilot's Operating Handbook and Airplane Flight Manual.

SECTION 7 - DESCRIPTION AND OPERATION

The S-TEC ADF-650A System operates over a frequency range of 200 through 1799 kHz in 1-kHz increments. Three operating modes are included as part of the ADF-650 System.

- BFO
- ANT
- ADF



ADF-650A Receiver, Controls, and Indicators Figure 1

BFO Mode

The BFO (beat frequency oscillator) and ADF (automatic direction finding) modes are navigation modes that result in pointing operation when in-range station is selected. The ADF mode is used with conventional nondirectional beacons and AM broadcast stations. The BFO mode is used to aurally identify stations that employ keyed cw rather than amplitude modulation techniques.

NOTE

CW signals (Morse Code) are unmodulated and no audio will be heard without use of BFO. This type of signal is not used in the United States air navigation. It is used in some foreign countries and marine beacons.

REPORT: VB-1611 9-86 4 of 6

ANT (Antenna) Mode

The ANT (antenna) mode cannot be used for navigation; this mode enhances audio reception clarity and is normally used for station identification.

ADF Mode

Automatic Direction Finder (ADF) mode is used for navigation. This mode activates the bearing pointer. The bearing pointer will point in the direction of the station relative to the aircraft heading.

Frequency Selector Controls

Three controls are used to select the system operating frequency. The right hand control selects 1 - kHz increments, the center control 10 - kHz increments, and the left hand control 100 - kHz increments.

Self Test Switch

Pressing and holding the spring loaded self test switch while in the ADF mode will cause the bearing pointer to rotate 90 degrees from its prior position if the ADF-650 system is operating properly. When the test switch is released, the bearing pointer should promptly return to its starting point. At this time, normal operation is restored.

ON/OFF/VOL/ID Control

This control performs three independent functions. In full ccw position, no power is applied to the system; rotating the control cw applies power and continued rotation increases volume. Pulling the knob out enhances the Morse code station identifier when background noise is present; push the knob to hear voice transmissions. A good operating practice is to pull the knob out for station identification purposes and then push it back in after positive identification has been made.

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REPORT: VB-1611 9-88 6 of 6

PILOT'S OPERATING HANDBOOK AND FAA APPROVED AIRPLANE FLIGHT MANUAL

SUPPLEMENT NO. 16 FOR GARMIN GMA 340 AUDIO PANEL

This supplement must be attached to the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual when the Garmin GMA 340 is installed per the Equipment List. The information contained herein supplements or supersedes the information in the basic Pilot's Operating Handbook and FAA Approved Airplane Flight Manual only in those areas listed herein. For limitations, procedures, and performance information not contained in this supplement, consult the basic Pilot's Operating Handbook and FAA Approved Airplane Flight Manual.

FAA APPROVED

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SECTION 1 - GENERAL

This supplement supplies information necessary for the operation of the airplane when the Garmin GMA 340 audio panel is installed in accordance with FAA approved Piper data.

SECTION 2 - LIMITATIONS

No change.

SECTION 3 - EMERGENCY PROCEDURES

. No change.

SECTION 4 - NORMAL PROCEDURES

AUDIO CONTROL SYSTEM OPERATION:

- Select the desired transmitter audio selector button (COM1, COM2, OR COM3) and verify that the buttons LED is illuminated.
- INTERCOM VOL Control (ICS) Adjust to desired listening level.
- INTERCOM VOX (voice) Sensitivity Control ROTATE CONTROL knob clockwise to the middle range and then adjust as required for desired voice activation or hot mic intercom.
- If desired, select the speaker function button. Selecting this button allows radio transmissions to be received over the cabin speaker.

NOTE

Audio level is controlled by the selected NAV radio volume control.

MARKER BEACON RECEIVER OPERATION:

- TEST Button PRESS to verify all marker lights are operational.
- SENS Button SELECT HI for airway flying for LO for ILS/LOC approaches.

REPORT: VB-1611 9-90 2 of 6

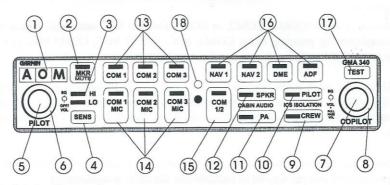
SECTION 5 - PERFORMANCE

No change.

SECTION 6 - WEIGHT AND BALANCE

Factory installed optional equipment is included in the licensed weight and balance data in section 6 of the Airplane Flight Manual.

SECTION 7 - DESCRIPTION AND OPERATION



- 1. Marker Beacon Lamps
- 2. Marker Beacon Receiver Audio Select/Mute Button
- 3. Marker Beacon Receiver Sensitivity Selection Indicator LED
- 4. Marker Beacon Receiver Sensitivity Selection Button
- 5. Unit On/Off, Pilot Intercom System (ICS) Volume
- 6. Pilot ICS Voice Activated (VOX) Intercom Squelch Level
- 7. Copilot and Passenger ICS Volume Control (Pull out for Passenger Volume)
- 8. Copilot/Passenger VOX Intercom Squelch Level
- 9. Crew Isolation Intercom Mode Button
- 10. Pilot Isolation Intercom Mode Button
- 11. Passenger Address (PA) Function Button
- 12. Speaker Function Button
- 13. Transceiver Audio Selector Buttons (COM1, COM2, COM3)
- 14. Transmitter (Audio/Mic) Selection Buttons
- 15. Split COM Button
- 16. Aircraft Radio Audio Selection Buttons (NAV1, NAV2, DME, ADF)
- 17. Annunciator Test Button
- 18. Photocell Automatic Annunciator Dimming

ON/OFF, Pilot Intercom System (ICS) Volume Control

The GMA 340 is powered OFF when the left small knob (5) is rotated fully CCW into the detent. To turn the unit ON, rotate the knob clockwise past the click. The knob then functions as the pilot ICS volume control. A fail safe circuit connects the pilot's headset and microphone directly to COM1 in case power is interrupted or the unit is turned OFF.

Transceivers

Selection of either COM1, COM2, or COM3 for both MIC and audio source is accomplished by pressing either COM1, MIC, COM2 MIC, COM3 MIC (14). The activeCOM audio is always heard on the headphones.

Additionally, each audio source can be selected independently by pressing COM1, COM2, or COM3 (13). When selected this way, they remain active as audio sources regardless of which transceiver has been selected for microphone use.

When a microphone is keyed, the active transceiver's MIC button LED blinks approximately one per second to indicate that the radio is transmitting.

NOTE

Audio level is controlled by the selected COM radio volume controls.

Split COM

Pressing the COM 1/2 button (15) activates the split COM function. When this mode is active, COM1 is dedicated solely to the pilot for MIC/Audio while COM2 is dedicated to the copilot for MIC/Audio. The pilot and copilot can simultaneously transmit in this mode over separate radios. Both pilots can still listen to COM3, NAV1, NAV2, DME, ADF, and MRK as selected. The split COM mode is cancelled by pressing the COM 1/2 button a second time.

When in the split COM mode the copilot may make PA announcements while the pilot continues using COM1 independently. When the PA button is pressed after the split com mode is activated the copilot's mic is output over the cabin speaker when keyed. A second press of the PA button returns the copilot to normal split COM operation.

REPORT: VB-1611 ISSUED: JULY 12, 1995 9-92 4 of 6 REVISED: JANUARY 2, 2001

Aircraft Radios and Navigation

Pressing NAV1, NAV2, DME, ADF (16) or MRK (2) selects each audio source. A second button press deselects the audio.

Speaker Output

Pressing the SPKR button (12) selects the aircraft radios over the cabin speaker. The speaker output is muted when a COM microphone is keyed.

PA Function

The PA mode is activated by pressing the PA button (11). Then, when either the pilot's or copilot's microphone is keyed, the corresponding mic audio is heard over the cabin speaker. If the SKR button is also active, then any selected speaker audio is muted while the microphone is keyed. The SPKR button does not have to be previously active in order to use the PA function.

Intercom System (ICS)

Intercom volume and squelch (VOX) are adjusted using the following front panel knobs:

- Left Small Knob Unit ON/OFF power control and pilot's ICS volume.
 Full CCW detent position is OFF.
- Left Large Knob Pilot ICS mic VOX squelch level. CW rotation increases the amount of mic audio (VOX level) required to break squelch. Full CCW is the "HOT MIC" position (no squelch).
- Right Small Knob IN position: Copilot ICS volume. OUT position: Passenger ICS volume.
- Right Large Knob Copilot and passenger mic VOX squelch level. CW rotation increases the amount of mic audio (VOX level) required to break squelch. Full CCW is the "HOT MIC" position.
- PILOT Mode This mode isolates the pilot from everyone else and dedicates the aircraft radios to the pilot exclusively. The copilot and passengers share communications between themselves but cannot communicate with the pilot or hear the aircraft radios.
- CREW Mode This mode places the pilot and copilot on a common ICS
 communication channel with the aircraft radios. The passengers are on
 their own intercom channel and can communicate with each other, but
 cannot communicate with the crew or hear the aircraft radios.

Marker Beacon Receiver

The GMA 340's marker beacon receiver controls are located on the left side of the front panel (1 - 4). The SENS button selects either high or low sensitivity as indicated by the HI or LO LED being lit. Low sensitivity is used on ILS approaches while high sensitivity allows operation over airway markers or to get an earlier indication of nearing the outer marker during an approach.

The marker audio is initially selected by pressing the MKR/Mute button (2). If no beacon signal is received, then a second button press will deselect the marker audio. This operation is similar to selecting any other audio source on the GMA 340. However, if the second button press occurs while a marker beacon signal is received, then the marker audio is muted but not deselected. The buttons LED will remain lit to indicate that the source is still selected. When the current marker signal is no longer received, the audio is automatically un-muted. While in the muted state, pressing the MKR/Mute button deselects the marker audio. The button's LED will extinguish to indicate that the marker audio is no longer selected.

PILOT'S OPERATING HANDBOOK AND FAA APPROVED AIRPLANE FLIGHT MANUAL

SUPPLEMENT NO. 17 FOR S-TEC DME-450

This supplement must be attached to the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual when the S-TEC DME-450 is installed per the Equipment List. The information contained herein supplements or supersedes the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual only in those areas listed herein. For limitations, procedures and performance information not contained in this supplement, consult the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual.

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VERO BEACH, FLORIDA

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SECTION 1 - GENERAL

The S-TEC DME-450 system is a full feature, solid state, remote mounted system with full 200 channel capability. For long distance operation, it provides a full 100 watts maximum pulse power transmitter output.

The IND-450 indicator (see figure 1) provides selectable read-out of distance to/from the station, ground speed, and time to/from the station. Features also include automatic display dimming and waypoint annunciation.

SECTION 2 - LIMITATIONS

No change.

SECTION 3 - EMERGENCY PROCEDURES

No change.

SECTION 4 - NORMAL PROCEDURES

DME OPERATION

- DME Mode Selector Switch Set to DME 1 or DME 2
- NAV 1 and NAV 2 VHF Navigation Receivers ON; SET FREQUENCY to VOR/DME station frequencies, as required.

NOTE

When the VOR frequency is selected, the appropriate DME Frequency is automatically channeled.

• DME audio selector button (on audio selector panel) - SET to desired mode.

SECTION 5 - PERFORMANCE

No change.

REPORT: VB-1611 9-96 2 of 4

SECTION 6 - WEIGHT AND BALANCE

Factory installed optional equipment is included in the licensed weight and balance data in Section 6 of the Pilot's Operating Handbook and Airplane Flight Manual.

SECTION 7 - DESCRIPTION AND OPERATION

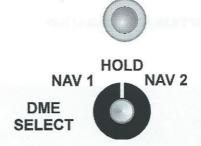


IND-450 Figure 1

- DISTANCE DISPLAY (NM) DME distance to VORTAC/WAYPOINT displayed in .1 nautical mile increments up to 99.9 NM, then in increments of one nautical mile.
- GROUND SPEED DISPLAY (KTS) Displays ground speed in knots to or from VORTAC/WAYPOINT up to 999 knots (aircraft must be flying directly to or from the VORTAC/WAYPOINT for true ground speed indication.
- TIME TO STATION DISPLAY (MIN) Displays time to station (VORTAC/WAYPOINT) in minutes up to 99 minutes (aircraft must be flying directly to or from the VORTAC/WAYPOINT for true time to the station indication.

7 - DESCRIPTION AND OPERATION (continued)

4. DME ON/OFF SWITCH - Turns DME power on or off.



Mode Selector Switch Figure 2

- 5. DME MODE SELECTOR SWITCH (NAV 1, HOLD, NAV 2) Selects DME operating mode as follows:
 - NAV 1 Selects DME operation with NO. 1 VHF navigation set; enables channel selection by NAV 1 frequency selector controls.
 - HOLD Selects DME memory circuit; DME remains channeled to station to which it was last channeled when HOLD was selected and will continue to display information relative to this channel. Allows both the NAV 1 and NAV 2 navigation receivers to be set to new operational frequencies without affecting the previously selected DME operation.

NOTE

In the HOLD mode there is no annunciation of the VOR/DME station frequency. However, an annunciator light located above the HOLD position of the selector illuminates to inform the pilot that the DME is in the HOLD mode.

NAV 2 - Selects DME operation with NO. 2 VHF navigation set; enables channel selection by NAV 2 frequency selector controls.

REPORT: VB-1611 9-98 4 of 4

PILOT'S OPERATING HANDBOOK AND FAA APPROVED AIRPLANE FLIGHT MANUAL

SUPPLEMENT NO. 18 FOR GARMIN GTX 330 TRANSPONDER

This supplement must be attached to the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual when the Garmin GTX 330 Transponder is installed per the Equipment List. The information contained herein supplements or supersedes the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual only in those areas listed herein. For limitations, procedures and performance information not contained in this supplement, consult the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual.

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THE NEW PIPER AIRCRAFT, INC.

VERO BEACH, FLORIDA

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SECTION 1 - GENERAL

This supplement supplies information necessary for the operation of the airplane when the Garmin GTX 330 Transponder is installed in accordance with FAA approved Piper data.

SECTION 2 - LIMITATIONS

- A. Display of TIS traffic information is advisory only and does not relieve the pilot responsibility to "see and avoid" other aircraft. Aircraft maneuvers shall not be predicated on the TIS displayed information.
- B. Display of TIS traffic information does <u>not</u> constitute a TCAS I or TCAS II collision avoidance system as required by 14 CFR Part 121 or Part 135.
- C. Title 14 of the Code of Federal Regulations (14 CFR) states that "When an Air Traffic Control (ATC) clearance has been obtained, no pilot-in-command (PIC) may deviate from that clearance, except in an emergency, unless he obtains an amended clearance." Traffic information provided by the TIS uplink does not relieve the PIC of this responsibility.
- D. The <u>400/500 Series Garmin Display Interfaces</u> (Pilot's Guide Addendum) P/N 190-00140-13 Rev. A or later revision must be accessible to the flight crew during flight.
- E. 400/500 Series Main Software 4.00 or later FAA approved software is required to operate the TIS interface and provide TIS functionality.

SECTION 3 - EMERGENCY PROCEDURES

To transmit an emergency signal:

- · Mode Selection Key ALT
- Code Selection SELECT 7700

To transmit a signal representing loss of all communications:

- · Mode Selection Key ALT
- · Code Selection SELECT 7600

REPORT: VB-1611 9-100, 2 of 4



BEFORE TAKEOFF:

- To transmit Mode C (Altitude Reporting) code in flight:
- · Mode Selection Key ALT
- · Code Selector Keys SELECT assigned code.

To transmit Mode A (Aircraft Identification) code in flight:

- · Mode Selector Key ON
- · Code Selector Keys SELECT assigned code.

NOTE

During normal operation with the ON mode selected, the reply indicator "R" flashes, indicating transponder replies to interrogations.

NOTE

Mode A reply codes are transmitted in ALT also; however, Mode C codes only are suppressed when the Function Selector ON key is selected.

1. DETAILED TRANSPONDER OPERATING PROCEDURES

Normal transponder operating procedures are described in the GARMIN GTX 330 Pilot's Guide, P/N 190-00207-00, Rev. A, or later appropriate revision.

2. DISPLAY OF TRAFFIC INFORMATION SERVICE (TIS) DATA

TIS surveillance data uplinked by Air Traffic Control (ATC) radar through the GTX 330 Mode S Transponder will appear on the interfaced display device (Garmin 400 or 500 series products). For detailed operating instructions and information regarding the TIS interface, refer to the 400/500 Series Garmin Display Interfaces (Pilot's Guide Addendum) P/N 190-00140-13 Rev. A or later appropriate revision.

ISSUED: JULY 12, 1995 REVISED: JANUARY 5, 2004 REPORT: VB-1611 3 of 4, 9-101

SECTION 5 - PERFORMANCE

No change.

SECTION 6 - WEIGHT AND BALANCE

Factory installed optional equipment is included in the licensed weight and balance data in section 6 of the Airplane Flight Manual.

SECTION 7 - DESCRIPTION AND OPERATION

See the $\underline{400/500}$ Series Garmin Display Interfaces (Pilot's Guide Addendum), P/N 190-00140-13, and \underline{GTX} 330 Pilot's Guide, P/N 190-00207-00, for a complete description of the GTX 330 system.

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PILOT'S OPERATING HANDBOOK AND FAA APPROVED AIRPLANE FLIGHT MANUAL

SUPPLEMENT NO. 20 FOR AVIDYNE FLIGHTMAX ENTEGRA PRIMARY FLIGHT/MULTI-FUNCTION DISPLAYS

This supplement must be attached to the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual when the optional Avidyne FlightMax Entegra Primary Flight and Multi-Function Displays are installed per the Equipment List. The information contained herein supplements or supersedes the basic Pilot's Operating Handbook and FAA Approved Airplane Flight Manual only in those areas listed herein. For limitations, procedures and performance information not contained in this supplement, consult the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual.

FAA APPROVED:

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THE NEW PIPER AIRCRAFT, INC.

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TION 1 - GENERAL

This airplane is equipped with the Avidyne FlightMax Entegra EXP5000 series 700-00006-0XX-() Primary Flight Display with software to the latest revision per Avidyne website and EX5000 series 700-00004-0XX-() Multi-Function Display with software to the latest revision per Avidyne website, herein referred to as the "PFD" and "MFD". The PFD is intended to be the primary display of primary flight and essential engine parameter information to the pilot. The PFD is capable of interfacing with a pair of Garmin GNS 430/530's, and an S-TEC System 55X autopilot.

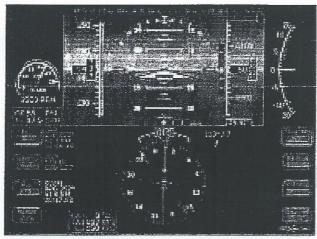


Figure 1 - Entegra 700-0006-0XX-() Primary Flight Display

The PFD provides the display of the following aircraft parameters:

- · Artificial Horizon
- · Airspeed Indication
- Altimeter
- Vertical Speed Indication
- · Rate of Turn Indicator
- Skid/Slip Indicator
- Horizontal Situation Indication

- RMT
- · Course Deviation Indication
- · Outside Air Temperature
- · Engine RPM
- · Fuel Flow
- · Oil Pressure
- Autopilot Annunciation

REPORT: VB-1611 9-112, 2 of 30 ISSUED: JULY 12, 1995 REVISED: June 15, 2009

SECTION 1 - GENERAL (continued)

The MFD is intended to be a supplemental display of situational and navigation information to the pilot. Its primary function is to provide a moving map display to the pilot for increased situational awareness. The MFD is capable of accepting data from a variety of GPS sensors, the BFG WX-500 Stormscope passive thunderstorm detection unit, Engine Sensor Unit, and either the L3 Skywatch Traffic Advisory System (TAS), Bendix/King TAS, or the Ryan Traffic and Collision Alert Device (TCAD) system. The unit is organized around logical groupings of information presented on "Pages".

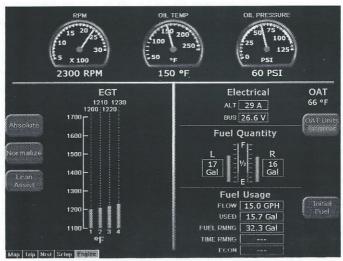


Figure 2 - EX5000 series 700-00004-0XX-() Multi-Function Display

The MFD provides the display of the following aircraft parameters:

- · Engine RPM
- · Engine Oil Temperature
- Engine Oil Pressure
- · EGT
- · Cylinder Head Temperature
- · Aircraft Electrical Status
- Outside Air Temperature
- · Fuel Quantity
- · Fuel Usage Data

ISSUED: JULY 12, 1995 REVISED: JANUARY 9, 2006 REPORT: VB-1611 3 of 30, 9-113

SECTION 2 - LIMITATIONS

A. PFD Limitations

- IFR flight is prohibited when the PFD or any standby instrument is inoperative (altimeter, airspeed indicator, artificial horizon, or whiskey compass).
- 2. IFR flight is prohibited upon aircraft total loss of essential engine parameter display (manifold pressure, tachometer, fuel flow).
- 3. The Avidyne FlightMax Entegra series Primary Flight Display Pilot's Guide, p/n 600-00104-000 revision 00 or appropriate later revision, or p/n 600-00143-000 revision 01 (EXP 5000 R6) or appropriate later revision, must be available to the pilot during all flight operations.
- 4. If a VOR or Localizer (VLOC) navigation source is displayed on the HSI and GPSS mode is engaged on the autopilot, the autopilot will track the active flight plan in the GPS corresponding to the selected VLOC source selected for display on the HSI (i.e. GPS1 for VLOC1 or GPS2 for VLOC2). This configuration is potentially confusing and must be avoided.
- GPSS mode must not be used on the final approach segment of a VLOC approach (ILS, LOC or non-GPS-overlay VOR). GPSS mode must be deselected (i.e., NAV mode selected) prior to the turn onto the final approach course.

NOTE

The PFD integrates with separately approved sensor and flight control installations. Adherence to limitations in appropriate installation AFM supplements is mandatory.

B. MFD Limitations

- The Avidyne moving map display provides visual advisory of the airplane's GPS position against a moving map. This information supplements CDI course deviation and information presented on the GPS navigator. The moving map display must not be used as the primary navigation instrument.
- 2. Use of Map page during IFR flight requires an IFR approved GPS receiver and installation, operated in accordance with its applicable limitations.
- 3. The Avidyne FlightMax EX-series Pilot's Guide, p/n 600-00105-000 revision 00 or appropriate later revision, must be available to the pilot during all flight operations.

REPORT: VB-1611 |9-114, 4 of 30

SECTION 2 - LIMITATIONS (continued)

B. MFD Limitations (continued)

- 4. Aircraft dispatch is prohibited when the MFD is inoperative.
- 5. Selecting "Lightning Display OFF" for the Lightning overlay of the Map page will prevent current heading values from being sent to the WX500 sensor from the EX5000.

When "Lightning Display OFF" is selected the EX5000 will stop sending current heading values to the WX500. When this selection is made, the WX500 will still use the last heading value that was present before this selection even though the actual aircraft heading may have changed since that selection was made.

Consequently, the Stormscope heading information provided to the Garmin 430 by the EX5000 will not be updated, resulting in an inaccurate lightning depiction on the Garmin 430. This issue does not affect the lightning display on the EX5000.

To avoid this invalid condition, **disable the WX500 on the GNS430**. For instructions on how to accomplish this, refer to the Garmin 400 Series Installation Manual, p/n 190-00140-02, latest revision (reference Section 5.1 Configuration Mode Operations, Section 5.2 Installation Configuration pages, and Section 5.2.2 Main RS232 Configuration page).

CAUTION

Traffic information shown on the Map page display is provided to the pilot as an aid to visually acquiring traffic. Pilot's should maneuver their aircraft based only on ATC guidance or positive visual acquisition of the conflicting traffic. Maneuvers should be consistent with ATC instructions. No maneuvers should be based only on a Traffic Advisory.

Terrain information shown on the Map page display is provided to the pilot as an aid to situational awareness. The Map page terrain color representations should not be used as a basis for terrain avoidance.

NOTE

The MFD integrates with separately approved sensor and flight control installations. Adherence to limitations in appropriate installation AFM supplements is mandatory.

ISSUED: JULY 12, 1995 REVISED: JANUARY 9, 2006 REPORT: VB-1611 5 of 30, 9-114a

SECTION 2 - LIMITATIONS (continued)

C. CMAX CHART PAGE Limitations

The geographic referenced aircraft symbol must not be used for navigation.

NOTE

The aircraft symbol displayed provides supplemental aircraft situational awareness information. It is not intended as a means for navigation or flight guidance. The airplane symbol is not to be used for conducting instrument approaches or departures. Position accuracy, orientation, and related guidance must be assumed by other means or required navigation.

Operators with the optional CMax Chart Page must have back-up charts available. Do not rely upon CMax charts as your sole source of navigation information.

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ISSUED: JULY 12, 1995 REVISED: JANUARY 9, 2006

REPORT: VB-1611 7 of 30, 9-115

SECTION 3 - EMERGENCY PROCEDURES

Failure of Pilot's Electronic Attitude Direction Display Screen (PFD)

Indication: PFD Display goes blank.

Standby Attitude GyroVERIFY ON and

Maintain attitude control using standby gyro and establish the aircraft in straight and level unaccelerated flight.

If time and conditions permit:

PFD Brightness Control (BRT/DIM)	Run to full bright
PFD Circuit Breaker	PULL and RESET

If PFD Screen cannot be reinstated:

On aircraft equipped with the optional second Nav Indicator (OBS):

NOTE

The Mechanical Nav Indicator (OBS) receives nav information directly from the No. 2 nav/com/GPS. Only VLOC information is available.

Maintain attitude, airspeed and heading control using standby instruments, magnetic compass and other directional indications (such as MFD, MAP/NAV page).

CAUTION

High current loads in the vicinity of the magnetic compass can influence its accuracy. Depending on the flight conditions, the pilot must reduce these loads as much as possible to insure accuracy. Tests have shown that air conditioner and pitot heat contribute to significant heading errors of the magnetic compass. These items should be turned OFF prior to comparing magnetic compass headings.

Land as soon as practical.

Loss of PFD Engine Data

Indication: Indicator needle removed from dial and digital readout replaced with white dashes.

Engine Instruments......Refer to Engine page of MFD Land as soon as practical.

Invalid Air Data

Indication: Airspeed, Altimeter, and Vertical Speed data replaced with Red X's.

Maintain aircraft airspeed and altitude by referring to the standby airspeed and altimeter.

If time and conditions permit:

PFD Circuit BreakerPULL and RESET

If air data is still invalid:

Refer to standby airspeed indicator and altimeter.

Land as soon as practical.

Invalid Heading Data

Indication: Heading Bug and Heading Data removed and replaced with Red X's.

If time and conditions permit:

PFD Circuit BreakerPULL and RESET Maintain heading control using magnetic compass and other directional indications (such as MFD, MAP/NAV page).

CAUTION

High current loads in the vicinity of the magnetic compass can influence its accuracy. Depending on the flight conditions, the pilot must reduce these loads as much as possible to insure accuracy. Tests have shown that air conditioner and pitot heat contribute to significant heading errors of the magnetic compass. These items should be turned OFF prior to comparing magnetic compass headings.

Land as soon as practical.

ISSUED: JULY 12, 1995 REVISED: JANUARY 9, 2006 REPORT: VB-1611 9 of 30, 9-117

Invalid Attitude and Heading Data

Indication: Attitude and Heading Data removed and replaced with Red X's.

Standby Attitude GyroVERIFY ON and flag is pulled on gyro.

Maintain attitude control using standby gyro.

If time and conditions permit:

PFD Circuit BreakerPULL and RESET

If attitude and heading data is still invalid:

Maintain attitude control by using standby gyro.

Maintain heading control by utilizing magnetic compass and other directional indications (such as MFD, MAP/NAV page).

CAUTION

High current loads in the vicinity of the magnetic compass can influence its accuracy. Depending on the flight conditions, the pilot must reduce these loads as much as possible to insure accuracy. Tests have shown that air conditioner and pitot heat contribute to significant heading errors of the magnetic compass. These items should be turned OFF prior to comparing magnetic compass headings.

Land as soon as practical.

Failure of Attitude, Airspeed and Heading Reference System (ADAHRS)
Indication: Airspeed, Attitude, Heading and Altitude replaced with
Red X's.

Standby Attitude GyroVERIFY ON and flag is pulled on gyro

Maintain attitude control using standby gyro.

If time and conditions permit:

PFD Circuit BreakerPULL and RESET

If ADAHRS initialization does not occur:

On aircraft equipped with the optional second Nav Indicator (OBS):

NOTE

The Mechanical Nav Indicator (OBS) receives nav information directly from the No. 2 nav/com/GPS. Only VLOC information is available.

Maintain attitude, airspeed and heading control using standby instruments, magnetic compass and other directional indications (such as MFD, MAP/NAV page).

CAUTION

High current loads in the vicinity of the magnetic compass can influence its accuracy. Depending on the flight conditions, the pilot must reduce these loads as much as possible to insure accuracy. Tests have shown that air conditioner and pitot heat contribute to significant heading errors of the magnetic compass. These items should be turned OFF prior to comparing magnetic compass headings.

Land as soon as practical.

ISSUED: JULY 12, 1995 REVISED: FEBRUARY 14, 2006 REPORT: VB-1611 11 of 30, 9-119

SECTION 3 - EMERGENCY PROCEDUR	ES (continued)
Cross Check Monitor	DED
Indication: Yellow Crosscheck Attitude An	
Establish aircraft in straight and level unaccele	
Alterna Anduce	with standby attitude gyro
Total Loss of Engine Instruments	
Indication: Indicator needle removed from replaced with white dashes.	om dial and digital readout
DAU Circuit Breaker	PULL and RESET
If engine data is still invalid:	
NOTE	
The following engine messages wil MFD if an exceedance is detected: • Check Oil Temp • Check Oil Press	l be displayed on the
 Check CHT Check RPM Check EGT	
If failure occurs during takeoff: Mixture Throttle Return to airport for landing.	
If failure occurs during climb or landing:	
Mixture	Maintain full rich
Throttle	As required
Land as soon as practical.	
If failure occurs after setting cruise power and	mixture:
Power Land as soon as practical.	Maintain power setting
If failure occurs prior to or during descent:	
Mixture	Full rich

REPORT: VB-1611 9-120, 12 of 30 ISSUED: JULY 12, 1995 REVISED: FEBRUARY 14, 2006

descent at 122 KIAS

Alternator Failure

Indication: Alternator Inop annunciator light illuminated and zero current displayed on MFD alternator indication source.

NOTE

Anytime the bus voltage is below 25 Vdc, the Low Bus Voltage annunciator will be illuminated.

Verify Failure	Check ammeter
If ammeter shows zero:	
ALTR switch	OFF
Reduce electrical load to minimum:	
ALTNR FIELD C/B	CHECK and RESET as required
ALTD Cwitch	ON

WARNING

Compass error may exceed 10 degrees with alternator inoperative.

CAUTION

Any power interruption will result in loss of attitude information from the PFD until the unit can be reinstated on the ground.

NOTE

Consider using the autopilot to reduce workload. Using the GPSS mode can assist in maintaining a flight-planned route.

NOTE

LO BUS VOLTAGE annunciator will be illuminated. Anticipate complete electrical failure. Duration of battery power available will be dependent on electrical load and battery condition prior to failure.

ISSUED: JULY 12, 1995 REVISED: JANUARY 9, 2006 REPORT: VB-1611 13 of 30, 9-121

Alternator Failure (continued)

If power is not restored:

ALTR Switch.....OFF

Reduce electrical loads by switching OFF or pulling circuit breakers for all non-essential equipment to include the following:

- Reduce PFD and MFD brightness as part of overall electrical system management
- Pitot heat (unless required)
- Airconditioner and ventilation fan (if installed)
- Landing light (use sparingly)
- · Strobe lights
- Recognition lights (if equipped)
- · Cabin/flood lights
- · No. 2 nav/com/GPS
- Autopilot
- · Electric trim
- DME (unless required for published approach)
- Stormscope (if equipped)
- Skywatch (if equipped)

Land as soon as practical.

Complete Electrical Failure

Standby Attitude Gyro......SELECT Standby (STBY) power button

CAUTION

The STBY PWR annunciator will rapidly flash for approximately one minute when aircraft power is lost. STBY PWR must be selected, otherwise the gyro will auto shutdown after approximately one minute.

Standby Attitude GyroVERIFY ON and flag is pulled on gyro

Maintain aircraft control with reference to the standby airspeed, altimeter, and attitude gyro indicators.

Battery SwitchOFI

Land as soon as possible.

WARNING

Compass error may exceed 10 degrees with alternator inoperative.

ISSUED: JULY 12, 1995 REVISED: FEBRUARY 14, 2006

Land as soon as practical.

WARNING

Compass error may exceed 10 degrees with alternator inoperative.

Aircraft Engine Power Loss

During an engine failure the pilot may elect to attempt an engine restart. During this time large voltage drops may cause the PFD to lose power and reinitialize. During this initialization process the PFD may not be able to complete a fast alignment during flight and therefore the pilot may have to obtain aircraft attitude and aircraft control using the standby instruments.

- Refer to the Emergency Section of the Pilot's Operating Handbook.
- If the PFD is able to perform fast alignment, when prompted by the PFD:
 - · Maintain straight and level flight

OR

- If engine does not restart, maintain wings level and appropriate aircraft speed.
- · Press the fast erect button.
- If the PFD was not able to perform fast alignment, maintain aircraft control with reference to the standby instruments for aircraft attitude information.

CAUTION

In case of engine failure, minimize the use of the starter and turn off all non-essential electrical equipment to preserve battery capacity.

Loss of Fuel Flow

Electric Fuel Pump	ON
Engine Driven Fuel Pur	np Failure
Throttle	RETARD
Electric Fuel Pump	ON
	RESET as required

CAUTION

If normal engine operation and fuel flow is not immediately re-established, the electric fuel pump should be turned OFF. The lack of fuel flow indication while the electric pump is on could indicate a leak in the fuel system or fuel exhaustion. If fuel system leak is verified, switch fuel selector to OFF.

ISSUED: JULY 12, 1995 REVISED: JANUARY 9, 2006 REPORT: VB-1611 17 of 30, 9-125

ISSUED: JULY 12, 1995 REVISED: JANUARY 9, 2006

SECTION 3 - EMERGENCY PROCEDURES (continued) Loss of Heading Accuracy

Indication:

- Difficulty maintaining course while using VOR or GPS.
- Excessive difference between heading and track required maintaining a VOR or GPS course.
- ATC indicates the aircraft is on a wrong heading.
- Excessive deviation between PFD heading and Whiskey Compass.
 (>10° after compass deviation applied.)

If heading systems differ by more than 10° (after compass deviation applied):

· Use Whiskey Compass for primary heading reference.

CAUTION

High current loads in the vicinity of the Whiskey Compass can influence its accuracy. Depending on the flight conditions, the pilot must reduce these loads as much as possible to insure accuracy. Tests have shown that air conditioner and pitot heat contribute to significant heading errors of the Whiskey Compass. These items should be turned OFF prior to comparing the Whiskey Compass to the PDF heading.

SECTION 4 - NORMAL PROCEDURES

Engine Start - General

CAUTION

Do not attempt flight if there is no indication of alternator output.

CAUTION

If a positive oil pressure is not indicated within 30 seconds following an engine start, stop the engine and determine the trouble. In cold weather it will take a few seconds longer to get a positive oil pressure indication.

NOTE

Starter manufacturers recommend that starter cranking periods be limited to 30 seconds with a two minute rest period between cranking periods. Longer cranking periods will shorten the life of the starter.

Before Starting Engine

Passengers	BOARD
	CLOSE and LATCH
Seats	ADJUSTED and LOCKED in position
Seat Belts and Harnesses	FASTEN/ADJUST
Brakes	SET
Circuit Breakers	Check IN
Alternate Air	OFF
Propeller	Full INCREASE rpm
	Desired tank

SECTION 4 - NORMAL PROCEDURES (continued)

Normal Start - Cold Engine	
Throttle	½ inch open
Battery Master Switch	
Primary Flight Display (PFD)	
,gp, (/	model software
Alternator Switch	ON
Electric Fuel Pump	
Magneto Switches	
Mixture	
Propeller	
Starter	
Mixture	Full RICH
Throttle	ADJUST
Oil Pressure	CHECK
Normal Start - Hot Engine	
Throttle	
Battery Master Switch	
Primary Flight Display (PFD)	Verify correct aircraft
	model software
Alternator Switch	ON
Electric Fuel Pump	
Magneto Switches	
Mixture	
Propeller	
Starter	
Mixture	
Throttle	

SECTION 4 - NORMAL PROCEDURES (continued)

Engine Start When Flooded

Throttle	Open full
Battery Master Switch	
Primary Flight Display (PFD)	
	model software
Alternator Switch	ON
Electric Fuel Pump	
Magneto Switches	ON
Mixture	Idle cut-off
Propeller	CLEAR
Starter	ENGAGE
Mixture	Full rich
Throttle	RETARD
Oil Pressure	CHECK

SECTION 4 - NORMAL PROCEDURES (continued)

Starting With External Power Source

CAUTION

It is possible to use the ship's battery in parallel by turning only the battery master switch ON. This will give longer cranking capabilities, but will not increase the amperage. Care should be exercised because if the ship's battery has been depleted, the external power supply can be reduced to the level of the ship's battery. This can be tested by turning on the battery master switch momentarily while the starter is engaged. If cranking speed increases, the ship's battery is at a higher level than the external power supply.

NOTE

For all normal operations using external power, the battery master and alternator switches should be OFF.

Battery Master Switch	OFF
Alternator Switch	OFF
Magneto Switches	ON
All Electrical Equipment	OFF
External Power Plug	Insert in fuselage
Proceed with normal start checklist	
Throttle	Lowest possible RPM
External Power Plug	
Battery Master Switch	ON
Alternator Switch	ON - check ammeter
Oil Pressure	CHECK

SECTION 5 - PERFORMANCE

No change from basic Handbook.

SECTION 6 - WEIGHT AND BALANCE

No change from basic Handbook.

REPORT: VB-1611 9-130, 22 of 30

SECTION 7 - DESCRIPTION AND OPERATION

A. PFD Systems Description

NOTE

This supplement provides a general description of the Avidyne FlightMax Entegra Series 700-0006-0XX-() PFD, its operation, and aircraft systems interfaces. For a detailed description of PFD operation, refer to the Avidyne FlightMax Entegra Series Primary Flight Display Pilot's Guide, p/n 600-00104-000 revision 00 or appropriate later revision, or 600-00143-000 revision 01 (EXP 5000 R6) or appropriate later revision.

The Entegra PFD start-up is automatic once power is applied. The display presents the Initialization Display immediately after power is applied. Power-on default is 75% brightness. Typical alignment times are 3 minutes once power is applied.

Attitude Direction Indicator (ADI)

Air Data

The airspeed tape to the left of the main ADI begins indicating at 20 Knots Indicated Airspeed (IAS) and is color coded in accordance with the model POH airspeeds for Vso, VFE, Vs, VNo, and VNE. An altitude tape is provided to the right of the main ADI and also displays a symbol for the Altitude Preselect (Altitude Bug). The Vertical Speed Indicator (VSI) is displayed to the right of the altitude tape. For vertical speed rates greater than the PFD displayed VSI scale, the indicator needle will peg just outside the scale and a digital readout of actual VSI up to 4000 FPM is then displayed. An additional data block is provided for display of Outside Air Temperature (OAT), True Airspeed (TAS), and Ground Speed (GS). Controls for selecting bug and barometric correction values are along the right side of the PFD. A wind indicator is also provided beneath the altitude tape.

Attitude Data

Attitude is depicted on the main ADI using a combination of an aircraft reference symbol ("flying-delta") against a background of labeled pitch ladders for pitch and a bank angle pointer in the form of an arced scale along the top of the main ADI for bank. A skid/slip indicator is attached to the bottom edge of the bank angle pointer.

ISSUED: JULY 12, 1995 REVISED: APRIL 11, 2006 REPORT: VB-1611 23 of 30, 9-131

A. PFD Systems Description (continued)

Horizontal Situation Indicator (HSI)

Heading Data

Magnetic heading is represented in a boxed digital form at the top of the compass rose. Heading rate (Rate of Turn Indicator) takes the form of a blue arcing arrow that begins behind the magnetic heading indicator and moves left or right accordingly. Graduations are provided on the rate of turn indicator scale to indicate ½ and full standard rate turns. A heading bug is also provided on the compass rose.

Navigation Data

Navigation data on the PFD takes several forms. A Course Deviation Indicator (CDI) is always provided on the HSI and a bearing pointer can be optionally selected for display on the HSI by the pilot. Controls for selecting the source of navigation data, selecting the display format of the navigation data, and for selecting the type of compass rose and moving map to be displayed are along the left side of the PFD. The active flight plan contained in the GPS Nav/Comm unit selected as the primary navigation source (Nav) can be optionally selected for display on the HSI as well as the desired range of the optionally selectable moving map display. If a localizer or ILS frequency is tuned and captured in the GPS Nav/Comm selected as the Nav source, a Vertical Deviation Indicator (VDI) and Horizontal Deviation Indicator (HDI) are automatically displayed on the ADI.

While executing an ILS or localizer only approach, the course deviation indicator (CDI) and glideslope needles on the PFD, as appropriate, may exhibit a slight oscillatory motion. The oscillatory motion increases from zero amplitude at approximately 2500 rpm to approximately ½ dot total amplitude at 2700 rpm. The GI-106 mechanical VOR Indicator needles exhibit this same behavior, only to a lesser degree. The pilot should fly the "average" localizer/glideslope needle position or decrease engine rpm to reduce needle oscillation.

NOTE

In the event glide slope or localizer signals are lost, the HDI and/or VDI will be displayed as red X's to indicate loss of signal. The red X'd indicator will only be removed if the signal is regained. In this case, the PFD Nav source will set to GPS, or if the GPS Nav/Comm is retuned, to another frequency. Appropriate action must be taken by the pilot if on an approach.

REPORT: VB-1611 9-132, 24 of 30

A. PFD Systems Description (continued)

Autopilot Integration

The Entegra PFD is fully integrated with the S-TEC System 55X Autopilot. Reference bugs for Heading, Altitude, and Vertical Speed are provided on the PFD to control the autopilot and aid pilot situational awareness. These bugs are displayed with solid or hollow symbology depending on the autopilot status. If the autopilot is engaged in that mode, the bug is solid to indicate the autopilot is coupled to that bug. A hollow bug indicates the autopilot is not engaged in that mode.

Autopilot mode annunciations are shown on the S-TEC System 55X computer.

When included as part of the installation, autopilot mode annunciations including autopilot ready and fail indications are provided at the top of the PFD screen.

When included as part of the installation, flight director command bars on the PFD attitude indicator can be enabled by the pilot. When the flight director is enabled and the autopilot is engaged in both lateral and vertical modes, the flight director displays the goals of the autopilot.

A lateral autopilot mode must be engaged on the S-TEC System 55X before a vertical mode can be engaged.

The flight director command bars will only be displayed on the PFD when enabled by the pilot and when both lateral and vertical autopilot modes are engaged.

A. PFD Systems Description (continued)

Autopilot Integration (continued)

The following autopilot modes are supported by the PFD:

- 1. HDG (Heading, using the heading bug)
- 2. NAV (Nav, using the course pointer and course deviation indicator)
- 3. GPSS (GPS Steering, using GPS course guidance)
- 4. APR (Approach, using the HDI and VDI, including automatic glide slope capture)
- 5. REV (Reverse sensing HDI approach)
- 6. ALT (Altitude Hold and Preselect, using the altitude bug)
- 7. VS (Vertical Speed, using the vertical speed bug)

NOTE

When HDG mode is engaged, rotation of the heading bug greater than 180° will result in a reversal of turn direction.

CAUTION

If a VLOC is selected in NAV on the PFD and GPSS mode is engaged on the autopilot, the autopilot will track the active flight plan in GPS1 if VLOC1 is selected or GPS2 if VLOC2 is selected and not track VLOC1 or VLOC2 as the selected source in NAV on the PFD. Therefore, the course deviation on the PFD CDI and the course deviation flown by the autopilot can be different. This situation may be confusing and should be avoided.

Engine Instruments

The Entegra PFD provides a display of Engine Tachometer (RPM), Oil Pressure (OP), and Fuel Flow (FF) in the upper left hand corner of the display. Tach indications are presented on analog scales with normal operating (green) and warning (red) markings, as appropriate. A digital indication presents fuel flow information in gallons per hour (GPH). A digital indication presents oil pressure information in pounds per square inch (PSI).

REPORT: VB-1611 9-134, 26 of 30

A. PFD Systems Description (continued)

Back-up Instruments

The Entegra PFD system installation includes redundant means of display of certain aircraft flight and systems parameters. Back-up Altimeter, Airspeed and Attitude instruments are provided to facilitate pilot cross-checking of PFD display flight parameters. The aircraft wet compass serves as a back-up heading source.

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B. MFD Systems Description

NOTE

This supplement provides a general description of the Avidyne EX5000 Series 700-00004-0XX-() MFD, its operation and aircraft interface. For a detailed description of the MFD, refer to the Avidyne FlightMax EX5000 Series Pilot's Guide and Reference, p/n 600-00105-000 revision 00 or later.

Navigation

Data associated with the moving map is found on four pages: Map, Nearest, Trip, and Info pages. The MFD contains a Jeppesen NavData database that is available for display on the Map page. In conjunction with GPS-supplied position information, an own-ship symbol is superimposed on the moving map and positioned relative to the NavData information. GPS can also supply the active flight plan for display on the moving map. Terrain data is provided by a USGS terrain database stored within the MFD and updated only on an as needed basis.

The Jeppesen Navigation Database provides data on airports, approaches, VOR's, NDB's, intersections, airspace definitions, and frequencies. North American and international databases are available. Database information can be updated via the USB port on the front face of the bezel.

The navigation data on the moving map display are based on databases that are updated periodically. Database updates are available on 28-day cycle subscriptions. Expired databases are clearly stated to the pilot via messages during system startup and on the System Setup page. The warning can only be removed by updating the data.

NOAA man-made obstruction database information provides data on man-made obstacles over 200 feet AGL. This data is only available for North America and can be updated via the USB port on the front face of the bezel.

The obstacle data on the moving map display are based on databases that are updated periodically. Database updates are available from Avidyne on 56-day cycle subscriptions. Expired databases are clearly stated to the pilot via messages during system startup and on the System Setup page. The warning can only be removed by updating the data.

REPORT: VB-1611 9-136, 28 of 30

B. MFD Systems Description (continued)

Navigation (continued)

Using the Jeppesen NavData data and the GPS-supplied present position, the MFD can provide the pilot with the nearest 25 airports or navaids, depending on pilot selection, within 100 nm. This information is presented on the Nearest page.

More detailed information on a particular airport is also generated from the Jeppesen NavData data and is available for pilot viewing on the Info page.

Flight plan data supplied by the GPS system provide the pilot with a tabular form of the remaining legs in the active GPS flight plan. This information is viewed on the Trip page and includes a CDI for added enroute navigation aiding.

Flight plan data is transmitted to the MFD from an external GPS navigator. Some installations do not support depictions of curved flight paths. In these cases, curved flight path segments will be depicted as straight lines. The GPS navigator and HSI are to be used during approach procedures. Reference the Avidyne FlightMax EX5000 Series Pilot's Guide, p/n 600-00105-000, for more information.

Datalink

Datalink information is received by the MFD based upon installation provisions and a subscription service available through Avidyne (www.myavidyne.com). Data is presented on the Map, Trip, and Nearest pages. Datalink information is provided for strategic planning purposes only. Data aging and transport considerations make it unsuitable for tactical use. Reference the Avidyne FlightMax EX5000 Series Pilot's Guide, p/n 600-00105-000, for more information.

Setup

The various System Setup pages allow the pilot to set user preferences for system operation. In addition to listing the software version identification information and database validity dates, the System Setup page allows access to several pages for preference selection and provides a means to initiate self-tests of the traffic and lightning sensors.

ISSUED: JULY 12, 1995 REVISED: JANUARY 9, 2006 REPORT: VB-1611 29 of 30, 9-137

ISSUED: JULY 12, 1995 REVISED: JANUARY 9, 2006

SECTION 7 - DESCRIPTION AND OPERATION (continued)

B. MFD Systems Description (continued) Setup (continued)

Airport Settings page provides selections for displaying airport type, runway surface type and minimum runway lengths on the moving map. Declutter Settings page allows the pilot to select settings for defining the base map detail when changing display range. System Time page provides an opportunity to select system time zone and Map page menu timeout options. DataBlock Edit page allows the pilot to select the data to be displayed in the datablock windows on the Map page. Datalink Setup page allows the pilot to select parameters for the datalink system, including update rate and range of weather data request.

Engine Instruments

The Engine page provides the pilot with engine parameters depicted on simulated gauges and electrical system parameters located in dedicated regions within the MFD display. An Engine Sensor Unit interfaces with engine-mounted sensors and provides data to the MFD for display.

A leaning function assists the pilot in leaning the engine for best power or best fuel economy. To initiate the leaning function, press the Lean Assist bezel key and proceed to lean the engine fuel mixture. Best economy is achieved when the engine is operating at peak EGT of the leanest cylinder (first cylinder to peak), as recommended by the engine manufacturer. Best power is achieved when the engine is leaned to the first cylinder to reach its EGT peak. When leaning is complete, select Absolute or Normalize to complete the leaning process. A digital readout of EGT change from the peak value is provided for reference. Reference the Avidyne FlightMax EX5000 series Pilot's Guide, p/n 600-00105-000, for more information.

PILOT'S OPERATING HANDBOOK AND FAA APPROVED AIRPLANE FLIGHT MANUAL

SUPPLEMENT NO. 21 FOR MID-CONTINENT 4300-4XX SERIES ELECTRIC ATTITUDE INDICATOR

This supplement must be attached to the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual when the optional Mid-Continent 4300-4XX Series Electric Attitude Indicator is installed per the Equipment List. The information contained herein supplements or supersedes the basic Pilot's Operating Handbook and FAA Approved Airplane Flight Manual only in those areas listed herein. For limitations, procedures and performance information not contained in this supplement, consult the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual.

FAA APPROVED:

LINDA J. DICKEN DOA-510620-CE

THE NEW PIPER AIRCRAFT, INC.

VERO BEACH, FLORIDA

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REPORT: VB-1611 1 of 4, 9-139

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SECTION 1 - GENERAL

This supplement supplies information necessary for the operation of the airplane when the optional Mid-Continent model 4300-XXX Electric Attitude Indicator is installed in accordance with FAA Approved Piper data. For additional information refer to the Mid-Continent Instruments Pilot's Guide, manual number 9015834, revision NR, or later revision.

SECTION 2 - LIMITATIONS

- The emergency battery must be checked for proper operation prior to flight.
- Should the RED TEST annunciator illuminate any time during the self test, this is an indication that the battery pack is in need of charging, or possible replacement. Flight in Instrument Meteorological Conditions (IMC) is prohibited.
- 3. Internal battery should be used for emergency use only.

SECTION 3 - EMERGENCY PROCEDURES

Loss of Aircraft Electrical System

CAUTION

The STBY PWR annunciator will rapidly flash for approximately one minute when aircraft power is lost. STBY PWR must be selected, otherwise the gyro will auto shutdown after approximately one minute.

Maintain attitude control using standby gyro.

SECTION 4 - NORMAL PROCEDURES

Preflight Check

- Apply aircraft power and allow the gyro to spin up for approximately 2 minutes.
- 2. Press and hold the STBY PWR button.
- Verify that after several seconds the amber LED has started to flash. This indicates that the unit has latched into the Battery Test Mode. At this time the STBY PWR button can be released.
- 4. Verify that a green annunciator is illuminated under the word TEST.
- 5. Visually monitor the test lights until the amber LED stops flashing, signaling the end of the test.

NOTE

A green annunciator throughout the test indicates the standby battery is sufficiently charged and should be able to function under normal operation. The presence of a red annunciator at any time during the test is an indication the standby battery is in need of charging, or possibly replacement.

NOTE

The Standby Attitude Indicator will operate for approximately one hour with the internal battery, depending on battery condition at the time of power failure.

SECTION 5 - PERFORMANCE

No change.

SECTION 6 - WEIGHT AND BALANCE

Factory installed optional equipment is included in the licensed weight and balance data in Section 6 of the Airplane Flight Manual.

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REPORT: VB-1611 3 of 4, 9-141

SECTION 7 - DESCRIPTION AND OPERATION

The Model 4300-4XX Electric Attitude Indicator incorporates a moving display that simulates the earth's horizon and provides the pilot with a real time visual indication of the aircraft pitch and roll attitude relative to the indicator symbolic airplane.

The 4300-4XX Electric Attitude Indicator offers the feature of a self-contained standby power source.

Anytime aircraft power is absent, selecting the STBY PWR button will put the unit into the standby power mode.

A warning circuit monitors the electrical voltage used to power the gyro. When the indicator is turned "OFF", or after the internal battery is discharged, the gyro warning flag comes into view.

PILOT'S OPERATING HANDBOOK AND FAA APPROVED AIRPLANE FLIGHT MANUAL

SUPPLEMENT NO. 22 FOR S-TEC ADF-650D SYSTEM

This supplement must be attached to the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual when the S-TEC ADF-650D System is installed per the equipment list. The information contained herein supplements or supersedes the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual only in those areas listed herein. For limitations, procedures, performance and loading information not contained in this supplement, consult the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual.

FAA APPROVED:

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VERO BEACH, FLORIDA

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REPORT: VB-1611 1 of 10, 9-143

SECTION 1 - GENERAL

This supplement supplies information necessary for the operation of the airplane when the S-TEC ADF-650D System is installed in accordance with FAA approved Piper data.

SECTION 2 - LIMITATIONS

No change.

SECTION 3 - EMERGENCY PROCEDURES

No change.

SECTION 4 - NORMAL PROCEDURES

To turn on the ADF-650D System:

Depress the PWR button momentarily and release.

NOTE

If the PWR button is pressed for longer than 3 seconds, the receiver will immediately shut off.

- After successful self test, input desired station frequency and select ANT mode.
- Positively identify selected station or beacon.
- Adjust volume control as required.
- If ADF-650D System is used for navigation, select ADF or BFO mode immediately after the station has been positively identified.

To turn off the ADF-650D System:

Depress the PWR button for at least 3 seconds.

NOTE

If the PWR button is released within 3 seconds, normal operations will resume.

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SECTION 4 - NORMAL PROCEDURES (continued)

To perform the preflight checklist and self test:

- After successful self test, press the mode control until ANT is displayed and input a predetermined frequency to select a station in the immediate area. Adjust the volume control as necessary to provide a comfortable listening level.
- Press the ID button and observe that the station identification code becomes louder (if the station is voice-identified, it is not necessary to press the ID button).
- Press the ID button again to cancel the IDENT function and press the mode control until ADF is displayed.
- Observe the IND-650A Indicator and note that the bearing pointer indicates the relative bearing to the station.
- Push the TEST button while observing the indicator bearing pointer. The bearing pointer will rotate 90° and stop.
- Push the TEST button again (to turn off test function). The bearing pointer returns to the original relative bearing position.
- Switch to BFO mode, if appropriate, and verify a tone is present. Select the appropriate operating mode when all checks have been completed.

SECTION 5 - PERFORMANCE

No change.

SECTION 6 - WEIGHT AND BALANCE

Factory installed optional equipment is included in the licensed weight and balance data in Section 6 of the Pilot's Operating Handbook and Airplane Flight Manual.

SECTION 7 - DESCRIPTION AND OPERATION

The S-TEC ADF-650D System operates over a frequency range of 200 through 1799 kHz in 1-kHz increments. Three operating modes are included as part of the ADF-650D System.

- BFO
- ADF
- ANT



RCR-650D Receiver Controls

Beat Frequency Oscillator (BFO) Mode

The BFO (beat frequency oscillator) mode is used to aurally identify stations that employ keyed CW (Carrier Wave) rather than amplitude modulation techniques. This mode activates the bearing pointer. The bearing pointer will point in the direction of the station relative to the aircraft heading.

NOTE

CW signals (Morse Code) are unmodulated and no audio will be heard without use of BFO. This type of signal is not used in the United States air navigation. It is used in some foreign countries and marine beacons.

ISSUED: JULY 12, 1995

REVISED: SEPTEMBER 12, 2005

REPORT: VB-1611 5 of 10, 9-147

SECTION 7 - DESCRIPTION AND OPERATION (continued)

Automatic Direction Finder (ADF) Mode

The Automatic Direction Finder (ADF) mode uses conventional nondirectional beacons and AM broadcast stations for navigation. This mode activates the bearing pointer. The bearing pointer will point in the direction of the station relative to the aircraft heading.

Antenna (ANT) Mode

The ANT (antenna) mode cannot be used for navigation; this mode enhances audio reception clarity and is normally used for station identification.

Frequency Selection Keypad

The Frequency Selection Keypad is used to select the system operating frequency. The keypad consists of a row of numbered buttons from 0 to 9, located along the bottom of the RCR-650D Receiver. Frequencies in the megahertz and kilohertz range may be selected.

Power (PWR) Control

The power control is used to turn the receiver on and off. Momentarily depressing the PWR button will turn the receiver on and also initiate a self test.

NOTE

If the PWR button is pressed for longer than 3 seconds the receiver will immediately shut off.

SECTION 7 - DESCRIPTION AND OPERATION (continued)

Clear (CLR)

The clear function offers several options for the operator.

- If the entire frequency is entered and the CLR button is pushed, all the numbers will become dashes. An additional push on the CLR button will restore and display the prior frequency entry.
- If an entry is in progress and a number is entered in error, pressing the CLR button will erase the last number entry.
- Pressing the CLR button while in the contrast function reverses the display image and also places the receiver in manual mode.

NOTE

It is not necessary to push CLR to enter a new frequency number. Simply complete the entry and then enter the new numbers and they will replace the old frequency.

Volume (VOL) Control

The audio volume control is used to adjust the settings and levels for all function selector and setup modes and is controlled by pressing the $^{\Lambda}$ and V buttons on the VOL control.

ISSUED: JULY 12, 1995 REVISED: SEPTEMBER 12, 2005

SECTION 7 - DESCRIPTION AND OPERATION (continued) Function (FUNC) Selector

The function selector enables the user to select between contrast and volume display functions (on power-up, the RCR-650D will be in the volume display function). The first time the function selector is pressed, the receiver enters the contrast function. Subsequent presses of the function selector button toggles the unit between contrast and volume. Additionally, pressing the clear button while in the contrast function places the receiver in manual mode. In manual mode, subsequent pushes of the function selector will cycle the receiver through four functions: volume, contrast, display and keypad.

Volume



The volume control function is available on power-up and is accessed immediately by pressing the A and V buttons on the VOL control. Upon activation, the kHz and mode annunciations are temporarily replaced by the text "VOLUME" with a horizontal fill bar. The filled portion of the bar indicates the current volume setting.

Contrast



The contrast function is activated by pressing the FUNC selector. Upon activation, the kHz and mode annunciation are temporarily replaced by the text "CONTRAST" with a horizontal fill bar on the right side of the annunciator panel. The filled portion of the bar indicates the current contrast setting. The contrast is adjusted by pressing the appropriate $^{\Lambda}$ and $^{\vee}$ indicators on the volume control.

Display



When the display is setup in the manual mode, press the FUNC selector until the display function is selected. The display function is then activated and the kHz and mode annunciations are temporarily replaced by the text "DISPLAY" with a horizontal fill bar on the right side of the annunciator panel. The filled portion of the bar indicates the current display setting. The display is adjusted by pressing the appropriate $^{\Lambda}$ and $^{\vee}$ indicators on the volume control.

SECTION 7 - DESCRIPTION AND OPERATION (continued)

Function (FUNC) Selector - continued

Keypad Light Brightness



The keypad light brightness setting is used to adjust the brightness of all legends on the display face. When the display is setup in the manual mode, press the FUNC selector until the keypad function is selected. The keypad function is then displayed with the text "KEYPAD" and a horizontal fill bar on the right side of the annunciator panel. The filled portion of the bar indicates the current keypad brightness setting. The brightness is adjusted by pressing the appropriate Λ and V indicators on the volume control.

Mode Selector



The mode selector is used to select one of the three operating states: BFO, ADF, or ANT. Pressing the MODE selector button will step the receiver through the three modes. The current mode will be displayed in the upper right corner of the display. On system power-up, the mode selector will be in the ADF mode.

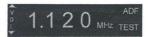
Ident (ID)



The receiver utilizes an Ident Filter for audio output which aids in receiving weak signals. Pressing the ID button toggles the Ident Filter on and off. When the Ident Filter is active, the text "IDENT" is displayed in the bottom right corner of the display.

SECTION 7 - DESCRIPTION AND OPERATION (continued)

Test Mode



Press the TEST button to start the test mode. The text "TEST" will be displayed in the bottom right corner of the display for approximately 15 seconds. During this time, the IND-650A Indicator pointer will incrementally rotate 90°. Press the TEST button again to cancel the test while in this mode. The pointer will immediately return to its starting point.

PILOT'S OPERATING HANDBOOK AND FAA APPROVED AIRPLANE FLIGHT MANUAL

SUPPLEMENT NO. 23 FOR AVIDYNE FLIGHTMAX ENTEGRA PRIMARY FLIGHT/MULTI-FUNCTION DISPLAYS WITH THE B&C SPECIALTIES BC410 STANDBY ALTERNATOR

This supplement must be attached to the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual when the optional Avidyne FlightMax Entegra Primary Flight and Multi-Function Displays with the B&C Specialties BC410 Standby Alternator is installed per the Equipment List. The information contained herein supplements or supersedes the basic Pilot's Operating Handbook and FAA Approved Airplane Flight Manual only in those areas listed herein. For limitations, procedures and performance information not contained in this supplement, consult the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual.

FAA APPROVED:

LINDA J. DICKEN DOA-510620-CE

THE NEW PIPER AIRCRAFT, INC.

VERO BEACH, FLORIDA

DATE OF APPROVAL: FEBRUARY 14, 2006

ISSUED: JULY 12, 1995

REVISED: FEBRUARY 14, 2006

REPORT: VB-1611 1 of 36, 9-153

SECTION 1 - GENERAL

This airplane is equipped with the Avidyne FlightMax Entegra EXP5000 series 700-00006-0XX-() Primary Flight Display with 530-00138-000 software and EX5000 series 700-00004-0XX-() Multi-Function Display with 530-00137-000 software, herein referred to as the "PFD" and "MFD". The PFD is intended to be the primary display of primary flight and essential engine parameter information to the pilot. The PFD is capable of interfacing with a pair of Garmin GNS 430/530's, and an S-TEC System 55X autopilot.



Figure 1 - Entegra 700-00006-0XX-() Primary Flight Display

The PFD provides the display of the following aircraft parameters:

- · Artificial Horizon
- · Airspeed Indication
- Altimeter
- Vertical Speed Indication
- · Rate of Turn Indicator
- · Skid/Slip Indicator
- Horizontal Situation Indication

- · RMI
- Course Deviation Indication
- Outside Air Temperature
- Engine RPM
- Fuel Flow
- · Oil Pressure
- Autopilot Annunciation

SECTION 1 - GENERAL (continued)

The MFD is intended to be a supplemental display of situational and navigation formation to the pilot. Its primary function is to provide a moving map display the pilot for increased situational awareness. The MFD is capable of accepting data from a variety of GPS sensors, the BFG WX-500 Stormscope passive thunderstorm detection unit, Engine Sensor Unit, and either the L3 Skywatch Traffic Advisory System (TAS), Bendix/King TAS, or the Ryan Traffic and Collision Alert Device (TCAD) system. The unit is organized around logical groupings of information presented on "Pages".

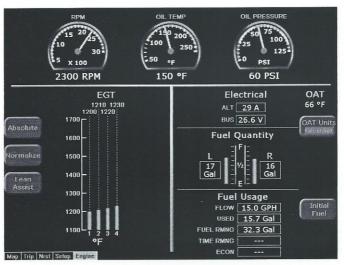


Figure 2 - EX5000 series 700-00004-0XX-() Multi-Function Display

The MFD provides the display of the following aircraft parameters:

- Engine RPM
- Engine Oil Temperature
- Engine Oil Pressure
- EGT

- · Aircraft Electrical Status
- Outside Air Temperature
- Fuel Quantity
- Fuel Usage Data

SECTION 1 - GENERAL (continued)

A B&C Specialties, BC410 standby alternator, when ON, will automatical activate in the event of a failure in the primary alternator, therefore replacing t primary alternator function, but not supplementing its output. The alternator is gear driven through the engine vacuum pump drive pad.

The standby alternator is rated for 20 amperes of maximum load. The actual load available for use is dependent on engine rpm and current operating conditions.

SECTION 2 - LIMITATIONS

A. PFD Limitations

- IFR flight is prohibited when the PFD or any standby instrument is inoperative (altimeter, airspeed indicator, artificial horizon, or whiskey compass).
- 2. IFR flight is prohibited upon aircraft total loss of essential engine parameter display (manifold pressure, tachometer, fuel flow).
- 3. The Avidyne FlightMax Entegra series Primary Flight Display Pilot's Guide, p/n 600-00104-000 revision 00 or appropriate later revision, or p/n 600-00143-000 revision 01 (EXP 5000 R6) or appropriate later revision, must be available to the pilot during all flight operations.
- 4. If a VOR or Localizer (VLOC) navigation source is displayed on the HSI and GPSS mode is engaged on the autopilot, the autopilot will track the active flight plan in the GPS corresponding to the selected VLOC source selected for display on the HSI (i.e. GPS1 for VLOC1 or GPS2 for VLOC2). This configuration is potentially confusing and must be avoided.
- GPSS mode must not be used on the final approach segment of a VLOC approach (ILS, LOC or non-GPS-overlay VOR). GPSS mode must be deselected (i.e., NAV mode selected) prior to the turn onto the final approach course.

NOTE

The PFD integrates with separately approved sensor and flight control installations. Adherence to limitations in appropriate installation AFM supplements is mandatory.

B. MFD Limitations

- The Avidyne moving map display provides visual advisory of the airplane's GPS position against a moving map. This information supplements CDI course deviation and information presented on the GPS navigator. The moving map display must not be used as the primary navigation instrument.
- 2. Use of Map page during IFR flight requires an IFR approved GPS receiver and installation, operated in accordance with its applicable limitations.
- 3. The Avidyne FlightMax EX-series Pilot's Guide, p/n 600-00105-000 revision 00 or appropriate later revision, must be available to the pilot during all flight operations.

ISSUED: JULY 12, 1995 REVISED: FEBRUARY 14, 2006 REPORT: VB-1611 5 of 36, 9-157

SECTION 2 - LIMITATIONS (continued)

B. MFD Limitations (continued)

- 4. Aircraft dispatch is prohibited when the MFD is inoperative.
- Selecting "Lightning Display OFF" for the Lightning overlay of the Map page will prevent current heading values from being sent to the WX300 sensor from the EX5000.

When "Lightning Display OFF" is selected the EX5000 will stop sending current heading values to the WX500. When this selection is made, the WX500 will still use the last heading value that was present before this selection even though the actual aircraft heading may have changed since that selection was made.

Consequently, the Stormscope heading information provided to the Garmin 430 by the EX5000 will not be updated, resulting in an inaccurate lightning depiction on the Garmin 430. This issue does not affect the lightning display on the EX5000.

To avoid this invalid condition, **disable the WX500 on the GNS430**. For instructions on how to accomplish this, refer to the Garmin 400 Series Installation Manual, p/n 190-00140-02, latest revision (reference Section 5.1 Configuration Mode Operations, Section 5.2 Installation Configuration pages, and Section 5.2.2 Main RS232 Configuration page).

CAUTION

Traffic information shown on the Map page display is provided to the pilot as an aid to visually acquiring traffic. Pilot's should maneuver their aircraft based only on ATC guidance or positive visual acquisition of the conflicting traffic. Maneuvers should be consistent with ATC instructions. No maneuvers should be based only on a Traffic Advisory.

Terrain information shown on the Map page display is provided to the pilot as an aid to situational awareness. The Map page terrain color representations should not be used as a basis for terrain avoidance.

NOTE

The MFD integrates with separately approved sensor and flight control installations. Adherence to limitations in appropriate installation AFM supplements is mandatory.

SECTION 2 - LIMITATIONS (continued)

C. CMAX CHART PAGE Limitations

The geographic referenced aircraft symbol must not be used for navigation.

NOTE

The aircraft symbol displayed provides supplemental aircraft situational awareness information. It is not intended as a means for navigation or flight guidance. The airplane symbol is not to be used for conducting instrument approaches or departures. Position accuracy, orientation, and related guidance must be assumed by other means or required navigation.

Operators with the optional CMax Chart Page must have back-up charts available. Do not rely upon CMax charts as your sole source of navigation information.

D. STANDBY ALTERNATOR Limitations

The standby alternator system is used in the event of primary alternator failure and not for normal operations.

The standby alternator is limited to 20 amperes continuous output. Transient operations of greater than 20 amperes for no more than 5 consecutive minutes may be conducted.

NOTE

Certain flight maneuvers such as climbs and lower power settings will result in an engine RPM less than 2500. Flight conditions resulting in less than 2500 engine RPM will reduce the standby alternator system capability and possibly require load shedding to maintain a system voltage above 25 volts.

ISSUED: JULY 12, 1995 REVISED: FEBRUARY 14, 2006

SECTION 3 - EMERGENCY PROCEDURES

Failure of Pilot's Electronic Attitude Direction Display Screen (PFD)

Indication: PFD Display goes blank.

Standby Attitude GyroVERIFY ON and

Maintain attitude control using standby gyro and establish the aircraft in straight and level unaccelerated flight.

If time and conditions permit:

PFD Brightness Control (BRT/DIM)Run to full bright PFD Circuit BreakerPULL and RESET

If PFD Screen cannot be reinstated:

On aircraft equipped with the optional second Nav Indicator (OBS):

NOTE

The Mechanical Nav Indicator (OBS) receives nav information directly from the No. 2 nav/com/GPS. Only VLOC information is available.

Maintain attitude, airspeed and heading control using standby instruments, magnetic compass and other directional indications (such as MFD, MAP/NAV page).

CAUTION

High current loads in the vicinity of the magnetic compass can influence its accuracy. Depending on the flight conditions, the pilot must reduce these loads as much as possible to insure accuracy. Tests have shown that air conditioner and pitot heat contribute to significant heading errors of the magnetic compass. These items should be turned OFF prior to comparing magnetic compass headings.

Land as soon as practical.

Loss of PFD Engine Data

Indication: Indicator needle removed from dial and digital readout replaced with white dashes.

Land as soon as practical.

Invalid Air Data

Indication: Airspeed, Altimeter, and Vertical Speed data replaced with Red X's.

Maintain aircraft airspeed and altitude by referring to the standby airspeed and altimeter.

If time and conditions permit:

PFD Circuit BreakerPULL and RESET

If air data is still invalid:

Refer to standby airspeed indicator and altimeter.

Land as soon as practical.

Invalid Heading Data

Indication: Heading Bug and Heading Data removed and replaced with Red X's.

If time and conditions permit:

PFD Circuit BreakerPULL and RESET Maintain heading control using magnetic compass and other directional indications (such as MFD, MAP/NAV page).

CAUTION

High current loads in the vicinity of the magnetic compass can influence its accuracy. Depending on the flight conditions, the pilot must reduce these loads as much as possible to insure accuracy. Tests have shown that air conditioner and pitot heat contribute to significant heading errors of the magnetic compass. These items should be turned OFF prior to comparing magnetic compass headings.

Land as soon as practical.

ISSUED: JULY 12, 1995 REVISED: FEBRUARY 14, 2006 REPORT: VB-1611 9 of 36, 9-161

Invalid Attitude and Heading Data

Indication: Attitude and Heading Data removed and replaced with Red X's. Standby Attitude GyroVERIFY ON and

flag is pulled on syra.

Maintain attitude control using standby gyro.

If time and conditions permit:

PFD Circuit BreakerPULL and RESET

If attitude and heading data is still invalid:

Maintain attitude control by using standby gyro.

Maintain heading control by utilizing magnetic compass and other directional indications (such as MFD, MAP/NAV page).

CAUTION

High current loads in the vicinity of the magnetic compass can influence its accuracy. Depending on the flight conditions, the pilot must reduce these loads as much as possible to insure accuracy. Tests have shown that air conditioner and pitot heat contribute to significant heading errors of the magnetic compass. These items should be turned OFF prior to comparing magnetic compass headings.

Land as soon as practical.

Failure of Attitude, Airspeed and Heading Reference System (ADAHRS)

ndication: Airspeed, Attitude, Heading and Altitude replaced with

Red X's.

Standby Attitude GyroVERIFY ON and flag is pulled on gyro

Maintain attitude control using standby gyro.

If time and conditions permit:

PFD Circuit BreakerPULL and RESET

If ADAHRS initialization does not occur:

On aircraft equipped with the optional second Nav Indicator (OBS):

NOTE

The Mechanical Nav Indicator (OBS) receives nav information directly from the No. 2 nav/com/GPS. Only VLOC information is available.

Maintain attitude, airspeed and heading control using standby instruments, magnetic compass and other directional indications (such as MFD, MAP/NAV page).

CAUTION

High current loads in the vicinity of the magnetic compass can influence its accuracy. Depending on the flight conditions, the pilot must reduce these loads as much as possible to insure accuracy. Tests have shown that air conditioner and pitot heat contribute to significant heading errors of the magnetic compass. These items should be turned OFF prior to comparing magnetic compass headings.

Land as soon as practical.

ISSUED: JULY 12, 1995 REVISED: FEBRUARY 14, 2006 REPORT: VB-1611 11 of 36, 9-163

Cross Check Monitor

Indication: Yellow Crosscheck Attitude Annunciator on PFD.

Establish aircraft in straight and level unaccelerated flight.

Total Loss of Engine Instruments

Indication: Indicator needle removed from dial and digital readout replaced with white dashes.

DAU Circuit BreakerPULL and RESET

If engine data is still invalid:

NOTE

The following engine messages will be displayed on the MFD if an exceedance is detected:

- Check Oil Temp
- Check Oil Press
- Check RPM
- Check EGT

If failure occurs during takeoff:	
Mixture	
Throttle	Full power
Return to airport for landing.	
If failure occurs during climb or landing:	
Mixture	Maintain full rich
Throttle	As required
Land as soon as practical.	
If failure occurs after setting cruise power and mixtu	ure:
Power	Maintain power setting
Land as soon as practical.	hand only on story the beau.
If failure occurs prior to or during descent:	
Mixture	Full ric
Throttle	
	descent at 122 KIAS

REPORT: VB-1611 9-164, 12 of 36 ISSUED: JULY 12, 1995 REVISED: April 11, 2008

ALTERNATOR FAILURE

Failure of Primary Alternator

Indication: Alternator Inop annunciator light illuminated and Standby Alternator ON annunciator light illuminated or zero current displayed on MFD alternator indication source.

NOTE

Anytime the bus voltage is below 25 Vdc, the Low Bus Voltage annunciator will be illuminated.

STBY ALTR	Verify ON/check ammeter indication
Engine RPM	Increase to a minimum of 2500
Electrical Load	Reduce until total load is below 20 amps
	and/or low bus annunciator is extinguished

NOTE

If the STBY ALTR ON annunciator is flashing then reduce electrical loads until the annunciator no longer flashes.

NOTE

Certain flight maneuvers such as climbs and lower power settings will result in an engine RPM less than 2500. Flight conditions resulting in less than 2500 engine RPM will reduce the standby alternator system capability and possibly require load shedding to maintain a system voltage above 25 volts.

ALTR	OFF
ALTR FIELD circuit breaker	check and reset as required
ALTR	
If primary alternator power not restored	a of solid horispace Alexan
ALTR	OFF
If primary alternator output cannot be restore	ed, maintain an electrical load of less
than 20 amps with which the STBY ALTR C	N annunciator no longer flashes and
land as soon as practical.	

ISSUED: JULY 12, 1995 REVISED: FEBRUARY 14, 2006 REPORT: VB-1611 13 of 36, 9-165

SECTION 3 - EMERGENCY PROCEDURES (continued) ALTERNATOR FAILURE (continued)

Failure of Standby Alternator

If STBY ALTR ON is not illuminated:

HO1DI AEIN ON IS HOT MUMMARED.	
STRV ALTR	OFF
STBY ALTR FIELD circuit breaker	check and reset as required
STBY ALTR SENSE circuit breaker	check and reset as required
STBY ALTR	ON

If standby alternator power not restored:

STBY ALTROFF

If the standby alternator has failed or cannot provide adequate power, then electrical power is dependent on available battery storage. Duration of battery power available will be dependent on electrical load and battery condition prior to failure. Execute **Complete Electrical Failure** checklist when battery is depleted. **Land as soon as possible.**

WARNING

Compass error may exceed 10 degrees with alternator inoperative.

CAUTION

Any power interruption will result in loss of attitude information from the PFD until the unit can be reinstated on the ground.

NOTE

LO BUS VOLTAGE annunciator will be illuminated. Anticipate complete electrical failure. Duration of battery power available will be dependent on electrical load and battery condition prior to failure.

SECTION 3 - EMERGENCY PROCEDURES (continued) ALTERNATOR FAILURE (continued)

Reduce electrical loads by switching OFF or pulling circuit breakers for all non-essential equipment to include the following:

- Reduce PFD and MFD brightness as part of overall electrical system management
- Pitot heat (unless required)
- Airconditioner and ventilation fan (if installed)
- Landing light (use sparingly)
- Strobe lights
- · Nav lights
- Recognition lights (if equipped)
- · Cabin/flood lights
- · No. 2 nav/com/GPS
- Autopilot (if equipped)
- Electric trim (if equipped)
- DME (unless required for published approach)
- Stormscope (if equipped)
- Skywatch (if equipped)

Land as soon as possible.

ISSUED: JULY 12, 1995 REVISED: FEBRUARY 14, 2006

SECTION 3 - EMERGENCY PROCEDU	RES (continued)
Electrical Overload (Alternator over 20 am	ps above known electrical load)
ALTR	ON
BATT MASTR	OFF
If affernator loads are reduced;	
Electrical load	reduce to minimum
NOTE	

NOTE

Due to increased system voltage and radio frequency noise, operation with ALTR switch ON and BATT MASTR switch OFF should be made only when required by an electrical system failure.

If alternator loads are not reduced:

BATT	ON
ALT	OFF
STBY ALTR	verify ON/check ammeter indication

NOTE

If the STBY ALTR ON annunciator is flashing then reduce electrical loads until the annunciator no longer flashes.

If the standby alternator has failed or cannot provide adequate power, then electrical power is dependent on available battery storage. Duration of battery power available will be dependent on electrical load and battery condition prior to failure. Execute **Complete Electrical Failure** checklist when battery is depleted.

WARNING

Compass error may exceed 10 degrees with alternator inoperative.

CAUTION

Any power interruption will result in loss of attitude information from the PFD until the unit can be reinstated on the ground.

NOTE

LO BUS VOLTAGE annunciator will be illuminated. Anticipate complete electrical failure. Duration of battery power available will be dependent on electrical load and battery condition prior to failure.

Reduce electrical loads by switching OFF or pulling circuit breakers for all non-essential equipment to include the following:

- Reduce PFD and MFD brightness as part of overall electrical system management
- Pitot heat (unless required)
- · Airconditioner and ventilation fan (if installed)
- Landing light (use sparingly)
- · Strobe lights
- · Nav lights
- Recognition lights (if equipped)
- · Cabin/flood lights
- No. 2 nav/com/GPS
- Autopilot (if equipped)
- Electric trim (if equipped)
- DME (unless required for published approach)
- Stormscope (if equipped)
- · Skywatch (if equipped)

Land as soon as practical.

Complete Electrical Failure

Standby Attitude Gyro.....SELECT Standby (STBY) power button

CAUTION

The STBY PWR annunciator will rapidly flash for approximately one minute when aircraft power is lost. STBY PWR must be selected, otherwise the gyro will auto shutdown after approximately one minute.

Standby Attitude GyroVERIFY ON and flag is pulled on gyro

Maintain aircraft control with reference to the standby airspeed, altimeter, and attitude gyro indicators.

Battery SwitchOFF

Prior to descent:

Land as soon as possible.

WARNING

Compass error may exceed 10 degrees with alternator inoperative.

Fire in Flight

Electrical Fire

Fire	Extinguish
Battery Master Switch	OFF
ALTR Switch	OFF
STBY ALTR Switch	OFF
Standby Attitude GyroSELECT	Standby (STBY) power button

CAUTION

The STBY PWR annunciator will rapidly flash for approximately one minute when aircraft power is lost. STBY PWR must be selected, otherwise the gyro will auto shutdown after approximately one minute.

Standby Attitude GyroVERIFY ON and flag is pulled on gyro

Maintain aircraft control with reference to the standby airspeed, altimeter, and attitude gyro indicators.

Vents OPEN
Cabin Heat OFF

Prior to descent:

Mixture _______FULL RICH
Throttle ______Set for approx. 500 feet per minute descent at 122 KIAS

Land as soon as practical.

WARNING

Compass error may exceed 10 degrees with alternator inoperative.

ISSUED: JULY 12, 1995 REVISED: FEBRUARY 14, 2006 REPORT: VB-1611 19 of 36, 9-171

Aircraft Engine Power Loss

During an engine failure the pilot may elect to attempt an engine restart. During this time large voltage drops may cause the PFD to lose power and reinitialize. During this initialization process the PFD may not be able to complete a fast alignment during flight and therefore the pilot may have to obtain aircraft attitude and aircraft control using the standby instruments.

- Refer to the Emergency Section of the Pilot's Operating Handbook.
- If the PFD is able to perform fast alignment, when prompted by the PFD:
 - Maintain straight and level flight

OR

- If engine does not restart, maintain wings level and appropriate aircraft speed.
- · Press the fast erect button.
- If the PFD was not able to perform fast alignment, maintain aircraft control with reference to the standby instruments for aircraft attitude information.

CAUTION

In case of engine failure, minimize the use of the starter and turn off all non-essential electrical equipment to preserve battery capacity.

NOTE

If standby alternator is installed, select OFF when primary alternator is OFF.

Loss of Fuel Flow

Fuel Selector	Check on tank containing usable fuel
Engine Driven Fuel Pump Failure	e in the same water than the
Throttle	RETARD
Electric Fuel Pump	ON

Electric Fuel Pump ON

If normal engine operation and fuel flow is not immediately re-established, the electric fuel pump should be turned OFF. The lack of fuel flow indication while the electric pump is on could indicate a leak in the fuel system or fuel exhaustion. If fuel system leak is verified, switch fuel selector to OFF.

REPORT: VB-1611 9-172, 20 of 36 ISSUED: JULY 12, 1995 REVISED: FEBRUARY 14, 2006

Loss of Heading Accuracy

Indication:

- · Difficulty maintaining course while using VOR or GPS.
- Excessive difference between heading and track required maintaining a VOR or GPS course.
- ATC indicates the aircraft is on a wrong heading.
- Excessive deviation between PFD heading and magnetic compass. (>10° after compass deviation applied.)

If heading systems differ by more than 10° (after compass deviation applied):

Use magnetic compass for primary heading reference.

CAUTION

High current loads in the vicinity of the magnetic compass can influence its accuracy. Depending on the flight conditions, the pilot must reduce these loads as much as possible to insure accuracy. Tests have shown that air conditioner and pitot heat contribute to significant heading errors of the magnetic compass. These items should be turned OFF prior to comparing the magnetic compass to the PDF heading.

ISSUED: JULY 12, 1995 REVISED: FEBRUARY 14, 2006

SECTION 4 - NORMAL PROCEDURES

Engine Start - General

CAUTION

Do not attempt flight if there is no indication of primary alternator output.

CAUTION

If a positive oil pressure is not indicated within 30 seconds following an engine start, stop the engine and determine the trouble. In cold weather it will take a few seconds longer to get a positive oil pressure indication.

NOTE

Starter manufacturers recommend that starter cranking periods be limited to 30 seconds with a two minute rest period between cranking periods. Longer cranking periods will shorten the life of the starter.

Before Starting Engine

Passengers	BOARD
Door	
Seats	ADJUSTED and LOCKED in position
Seat Belts and Harnesses	FASTEN/ADJUST
Brakes	SET
Circuit Breakers	Check IN
Carburetor Heat	OFF
Avionics	OFF
Fuel Selector	Desired tank

SECTION 4 - NORMAL PROCEDURES (continued) Normal Start - Cold Engine Battery Master Switch.....ON Primary Flight Display (PFD)Verify correct aircraft model software Alternator SwitchON Standby Alternator SwitchON Electric Fuel PumpON Left Magneto Switch.....ON Mixture.....Full RICH StarterENGAGE Throttle......ADJUST Right Magneto SwitchON **Normal Start - Hot Engine** Battery Master Switch.....ON Primary Flight Display (PFD)Verify correct aircraft model software Alternator SwitchON Standby Alternator SwitchON Electric Fuel PumpON Left Magneto Switch.....ON Starter ENGAGE Mixture......ADVANCE

Engine Start When Flooded ThrottleOpen full Battery Master Switch.....ON model software Alternator SwitchON Standby Alternator SwitchON Electric Fuel PumpOFF Left Magneto Switch......ON StarterENGAGE Mixture Full rich Throttle RETARD Right Magneto SwitchON Oil Pressure CHECK

Starting With External Power Source

CAUTION

It is possible to use the ship's battery in parallel by turning only the battery master switch ON. This will give longer cranking capabilities, but will not increase the amperage. Care should be exercised because if the ship's battery has been depleted, the external power supply can be reduced to the level of the ship's battery. This can be tested by turning on the battery master switch momentarily while the starter is engaged. If cranking speed increases, the ship's battery is at a higher level than the external power supply.

NOTE

For all normal operations using external power, the battery master and alternator switches should be OFF.

Battery Master Switch	OFF
Alternator Switch	
tandby Alternator Switch	
Left Magneto Switch	
All Electrical Equipment	
External Power Plug	Insert in fuselage
Proceed with normal start checklist	
Throttle	Lowest possible RPM
Right Magneto Switch	ON
External Power Plug	
Battery Master Switch	ON
Alternator Switch	ON - check ammeter
Standby Alternator Switch	ON
Oil Pressure	

Ground Check

Ground Chron	
Throttle	maximum power/RP
ALTR switch	OF1
STBY ALTR ON annunciator	verify ON
Increase electrical load to over 20 amps.	
Increase electrical load to over 20 amps. STBY ALTR ON annunciator	verify flashing
Decrease electrical load to less than 20 amps.	
STBY ALTR ON annunciator	verify ON (steady)
Throttle	retard
ALTR switch	ON
Verify normal amperage indication.	
STBY ALTR ON annunciator	verify extinguished

Taxiing

NOTE

During operations with low engine RPM, electrical system voltage may decrease below 26 volts, causing the STBY ALTR ON annunciator light to illuminate.

Before Takeoff

NOTE

Operation of the standby alternator with low engine RPM may cause an error in excess of 10° on the magnetic compass.

STBY ALTR switch	verify ON
Throttle	minimum 1000 RPM
Magnetic Compass	check with runway heading prior to takeoff
Stopping Engine	
CTDV ALTD quitch	OFF

SECTION 5 - PERFORMANCE

No change from basic Handbook.

SECTION 6 - WEIGHT AND BALANCE

No change from basic Handbook.

REPORT: VB-1611 9-178, 26 of 36 ISSUED: JULY 12, 1995 REVISED: APRIL 11, 2008

SECTION 7 - DESCRIPTION AND OPERATION

A. PFD Systems Description

NOTE

This supplement provides a general description of the Avidyne FlightMax Entegra Series 700-0006-0XX-() PFD, its operation, and aircraft systems interfaces. For a detailed description of PFD operation, refer to the Avidyne FlightMax Entegra Series Primary Flight Display Pilot's Guide, p/n 600-00104-000 revision 00 or appropriate later revision, or 600-00143-000 revision 01 (EXP 5000 R6) or appropriate later revision.

The Entegra PFD start-up is automatic once power is applied. The display presents the Initialization Display immediately after power is applied. Power-on default is 75% brightness. Typical alignment times are 3 minutes once power is applied.

Attitude Direction Indicator (ADI)

Air Data

The airspeed tape to the left of the main ADI begins indicating at 20 Knots Indicated Airspeed (IAS) and is color coded in accordance with the model POH airspeeds for Vso, VFE, Vs, VNO, and VNE. An altitude tape is provided to the right of the main ADI and also displays a symbol for the Altitude Preselect (Altitude Bug). The Vertical Speed Indicator (VSI) is displayed to the right of the altitude tape. For vertical speed rates greater than the PFD displayed VSI scale, the indicator needle will peg just outside the scale and a digital readout of actual VSI up to 4000 FPM is then displayed. An additional data block is provided for display of Outside Air Temperature (OAT), True Airspeed (TAS), and Ground Speed (GS). Controls for selecting bug and barometric correction values are along the right side of the PFD. A wind indicator is also provided beneath the altitude tape.

Attitude Data

Attitude is depicted on the main ADI using a combination of an aircraft reference symbol ("flying-delta") against a background of labeled pitch ladders for pitch and a bank angle pointer in the form of an arced scale along the top of the main ADI for bank. A skid/slip indicator is attached to the bottom edge of the bank angle pointer.

ISSUED: JULY 12, 1995 REVISED: APRIL 11, 2006 REPORT: VB-1611 27 of 36, 9-179

A. PFD Systems Description (continued)

Horizontal Situation Indicator (HSI)

Heading Data

Magnetic heading is represented in a boxed digital form at the top of the compass rose. Heading rate (Rate of Turn Indicator) takes the form of a blue arcing arrow that begins behind the magnetic heading indicator and moves left or right accordingly. Graduations are provided on the rate of turn indicator scale to indicate ½ and full standard rate turns. A heading bug is also provided on the compass rose.

Navigation Data

Navigation data on the PFD takes several forms. A Course Deviation Indicator (CDI) is always provided on the HSI and a bearing pointer can be optionally selected for display on the HSI by the pilot. Controls for selecting the source of navigation data, selecting the display format of the navigation data, and for selecting the type of compass rose and moving map to be displayed are along the left side of the PFD. The active flight plan contained in the GPS Nav/Comm unit selected as the primary navigation source (Nav) can be optionally selected for display on the HSI as well as the desired range of the optionally selectable moving map display. If a localizer or ILS frequency is tuned and captured in the GPS Nav/Comm selected as the Nav source, a Vertical Deviation Indicator (VDI) and Horizontal Deviation Indicator (HDI) are automatically displayed on the ADI.

While executing an ILS or localizer only approach, the course deviation indicator (CDI) and glideslope needles on the PFD, as appropriate, may exhibit a slight oscillatory motion. The oscillatory motion increases from zero amplitude at approximately 2500 rpm to approximately ½ dot total amplitude at 2700 rpm. The GI-106 mechanical VOR Indicator needles exhibit this same behavior, only to a lesser degree. The pilot should fly the "average" localizer/glideslope needle position or decrease engine rpm to reduce needle oscillation.

NOTE

In the event glide slope or localizer signals are lost, the HDI and/or VDI will be displayed as red X's to indicate loss of signal. The red X'd indicator will only be removed if the signal is regained. In this case, the PFD Nav source will set to GPS, or if the GPS Nav/Comm is retuned, to another frequency. Appropriate action must be taken by the pilot if on an approach.

REPORT: VB-1611 9-180, 28 of 36

A. PFD Systems Description (continued)

Autopilot Integration

The Entegra PFD is fully integrated with the S-TEC System 55X Autopilot. Reference bugs for Heading, Altitude, and Vertical Speed are provided on the PFD to control the autopilot and aid pilot situational awareness. These bugs are displayed with solid or hollow symbology depending on the autopilot status. If the autopilot is engaged in that mode, the bug is solid to indicate the autopilot is coupled to that bug. A hollow bug indicates the autopilot is not engaged in that mode.

Autopilot mode annunciations are shown on the S-TEC System 55X computer.

When included as part of the installation, autopilot mode annunciations including autopilot ready and fail indications are provided at the top of the PFD screen.

When included as part of the installation, flight director command bars on the PFD attitude indicator can be enabled by the pilot. When the flight director is enabled and the autopilot is engaged in both lateral and vertical modes, the flight director displays the goals of the autopilot.

A lateral autopilot mode must be engaged on the S-TEC System 55X before a vertical mode can be engaged.

The flight director command bars will only be displayed on the PFD when enabled by the pilot and when both lateral and vertical autopilot modes are engaged.

ISSUED: JULY 12, 1995

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SECTION 7 - DESCRIPTION AND OPERATION (continued)

A. PFD Systems Description (continued)

Autopilot Integration (continued)

The following autopilot modes are supported by the PFD:

- 1. HBG (Heading, using the heading bug)
 - 2. NAV (Nav, using the course pointer and course deviation indicator)
 - 3. GPSS (GPS Steering, using GPS course guidance)
 - 4. APR (Approach, using the HDI and VDI, including automatic glide slope capture)
 - 5. REV (Reverse sensing HDI approach)
 - 6. ALT (Altitude Hold and Preselect, using the altitude bug)
 - 7. VS (Vertical Speed, using the vertical speed bug)

NOTE

When HDG mode is engaged, rotation of the heading bug greater than 180° will result in a reversal of turn direction.

CAUTION

If a VLOC is selected in NAV on the PFD and GPSS mode is engaged on the autopilot, the autopilot will track the active flight plan in GPS1 if VLOC1 is selected or GPS2 if VLOC2 is selected and not track VLOC1 or VLOC2 as the selected source in NAV on the PFD. Therefore, the course deviation on the PFD CDI and the course deviation flown by the autopilot can be different. This situation may be confusing and should be avoided.

Engine Instruments

The Entegra PFD provides a display of Engine Tachometer (RPM), Oil Pressure (OP), and Fuel Flow (FF) in the upper left hand corner of the display. Tach indications are presented on analog scales with normal operating (green) and warning (red) markings, as appropriate. A digital indication presents fuel flow information in gallons per hour (GPH). A digital indication presents oil pressure information in pounds per square inch (PSI).

A. PFD Systems Description (continued)

Back-up Instruments

The Entegra PFD system installation includes redundant means of display of certain aircraft flight and systems parameters. Back-up Altimeter, Airspeed and Attitude instruments are provided to facilitate pilot cross-checking of PFD display flight parameters. The aircraft magnetic compass serves as a back-up heading source.

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B. MFD Systems Description

NOTE

This supplement provides a general description of the Avidyne Ex3000 Series 7000004-0xx-() MFD its operation and aircraft interface. For a detailed description of the MFD, refer to the Avidyne FlightMax EX5000 Series Pilot's Guide and Reference, p/n 600-00105-000 revision 00 or later.

Navigation

Data associated with the moving map is found on four pages: Map, Nearest, Trip, and Info pages. The MFD contains a Jeppesen NavData database that is available for display on the Map page. In conjunction with GPS-supplied position information, an own-ship symbol is superimposed on the moving map and positioned relative to the NavData information. GPS can also supply the active flight plan for display on the moving map. Terrain data is provided by a USGS terrain database stored within the MFD and updated only on an as needed basis.

The Jeppesen Navigation Database provides data on airports, approaches, VOR's, NDB's, intersections, airspace definitions, and frequencies. North American and international databases are available. Database information can be updated via the USB port on the front face of the bezel.

The navigation data on the moving map display are based on databases that are updated periodically. Database updates are available on 28-day cycle subscriptions. Expired databases are clearly stated to the pilot via messages during system startup and on the System Setup page. The warning can only be removed by updating the data.

NOAA man-made obstruction database information provides data on man-made obstacles over 200 feet AGL. This data is only available for North America and can be updated via the USB port on the front face of the bezel.

The obstacle data on the moving map display are based on databases that are updated periodically. Database updates are available from Avidyne on 56-day cycle subscriptions. Expired databases are clearly stated to the pilot via messages during system startup and on the System Setup page. The warning can only be removed by updating the data.

REPORT: VB-1611 9-184, 32 of 36

B. MFD Systems Description (continued)

avigation (continued)

Using the Jeppesen NavData data and the GPS-supplied present position, the MFD can provide the pilot with the nearest 25 airports or navaids, depending on pilot selection, within 100 nm. This information is presented on the Nearest page.

More detailed information on a particular airport is also generated from the Jeppesen NavData data and is available for pilot viewing on the Info page.

Flight plan data supplied by the GPS system provide the pilot with a tabular form of the remaining legs in the active GPS flight plan. This information is viewed on the Trip page and includes a CDI for added enroute navigation aiding.

Flight plan data is transmitted to the MFD from an external GPS navigator. Some installations do not support depictions of curved flight paths. In these cases, curved flight path segments will be depicted as straight lines. The GPS navigator and HSI are to be used during approach procedures. Reference the Avidyne FlightMax EX5000 Series Pilot's Guide, p/n 600-00105-000, for more iformation.

Datalink

Datalink information is received by the MFD based upon installation provisions and a subscription service available through Avidyne (www.myavidyne.com). Data is presented on the Map, Trip, and Nearest pages. Datalink information is provided for strategic planning purposes only. Data aging and transport considerations make it unsuitable for tactical use. Reference the Avidyne FlightMax EX5000 Series Pilot's Guide, p/n 600-00105-000, for more information.

Setup

The various System Setup pages allow the pilot to set user preferences for system operation. In addition to listing the software version identification information and database validity dates, the System Setup page allows access to several pages for preference selection and provides a means to initiate elf-tests of the traffic and lightning sensors.

ISSUED: JULY 12, 1995 REVISED: APRIL 11, 2008

SECTION 7 - DESCRIPTION AND OPERATION (continued)

B. MFD Systems Description (continued)

Setup (continued)

Airport Settings page provides selections for displaying airport type, runway surface type and minimum runway lengths on the moving map. Declutter Settings page allows the pilot to select settings for defining the base map detail when changing display range. System Time page provides an opportunity to select system time zone and Map page menu timeout options. DataBlock Edit page allows the pilot to select the data to be displayed in the datablock windows on the Map page. Datalink Setup page allows the pilot to select parameters for the datalink system, including update rate and range of weather data request.

Engine Instruments

The Engine page provides the pilot with engine parameters depicted on simulated gauges and electrical system parameters located in dedicated regions within the MFD display. An Engine Sensor Unit interfaces with engine-mounted sensors and provides data to the MFD for display.

A leaning function assists the pilot in leaning the engine for best power (best fuel economy. To initiate the leaning function, press the Lean Assis, bezel key and proceed to lean the engine fuel mixture. Best economy is achieved when the engine is operating at peak EGT of the leanest cylinder (first cylinder to peak), as recommended by the engine manufacturer. Best power is achieved when the engine is leaned to 100°F rich of its EGT peak. When leaning is complete, select Absolute or Normalize to complete the leaning process. A digital readout of EGT change from the peak value is provided for reference. Reference the Avidyne FlightMax EX5000 series Pilot's Guide, p/n 600-00105-000, for more information.

REPORT: VB-1611 9-186, 34 of 36

C. STANDBY ALTERNATOR System Description

The B&C Specialty Products Standby Alternator system automatically delivers electrical power to the aircraft electrical power bus in the event of failure of the primary alternator, provided the STBY ALTR switch is in the ON position. Powering the bus allows the pilot flexibility to choose equipment suitable to the current flight conditions. Equipment that would otherwise deplete the battery reserve may be used within the standby alternator's current limit.

The standby alternator controller monitors the aircraft electrical power bus voltage and activates the standby alternator if the bus voltage falls to less than 26.0 volts. As long as the electrical load is maintained below standby alternator capacity, the bus voltage will not fall below 25.0 volts and the battery will remain charged. Certain flight maneuvers such as climbs and lower power settings will result in an engine RPM less than 2500. Flight conditions resulting in less than 2500 engine RPM will reduce the standby alternator system capability and possibly require load shedding to maintain a system voltage above 25 volts. As long as a minimum bus voltage of 25 volts is maintained, battery energy will then be available for landing lights and other approach loads.

The standard aircraft amperage indication represents the standby alternator output when the STBY ALTR ON annunciator is lit.

The standby alternator is capable of outputs greater than maximum continuous load for less than 5 minutes without damage. Extended operation over rated load may cause immediate or premature alternator failure and battery depletion.

NOTE

During operations with low engine RPM, electrical system voltage may decrease below 26 volts, causing the STBY ALTR ON annunciator light to illuminate.

ISSUED: JULY 12, 1995 REVISED: FEBRUARY 14, 2006 REPORT: VB-1612 35 of 36, 9-18

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PILOT'S OPERATING HANDBOOK AND FAA APPROVED AIRPLANE FLIGHT MANUAL

SUPPLEMENT NO. 24 FOR BENDIX/KING KR-87 DIGITAL ADF WITH KI-227 INDICATOR

This supplement must be attached to the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual when the Bendix/King KR-87 Digital ADF with the KI-227 Indicator is installed per the Equipment List. The information contained herein supplements or supersedes the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual only in those areas listed herein. For limitations, procedures and performance information not contained in this supplement, consult the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual.

FAA APPROVED:

Albert J. Mill DOA-510620-CE Piper Aircraft, Inc. Vero Beach, Florida

DATE OF APPROVAL: October 15, 2008

SECTION 1 - GENERAL

The Bendix/King Digital ADF is a panel mounted, digitally tuned, automatic direction finder. It is designed to provide continuous 1 kHz digital tuning in the frequency range of 200 kHz to 1799 kHz and eliminates the need for mechanical band switching. The system is comprised of a receiver, a built-in electronic timer, a bearing indicator and a KA-44B combined loop and sense antenna.

The Bendix/King Digital ADF can be used for position plotting and homing procedures, and for aural reception of amplitude modulated (AM) signals.

The "flip-flop" frequency display allows switching between pre-selected "STANDBY" and "ACTIVE" frequencies by pressing the frequency transfer button. Both preselected frequencies are stored in a non-volatile memory circuit (no battery power required) and displayed in self-dimming gas discharge numerics. The active frequency is continuously displayed in the left window, while the right window will display either the standby frequency or the selected readout from the built-in timer.

The built-in electronic timer has two separate and independent timing functions: (1) An automatic flight timer that starts whenever the unit is turned on. This timer functions up to 59 hours and 59 minutes. (2) An elapsed timer which will count up or down for up to 59 minutes and 59 seconds. When a preset time interval has been programmed and the countdown reaches :00, the display will flash for 15 seconds. Since both the flight timer and elapsed timer operate independently, it is possible to monitor either one without disrupting the other. The pushbutton controls and the bearing indicator are internally lighted.

SECTION 2 - LIMITATIONS

No change.

SECTION 3 - EMERGENCY PROCEDURES

No change.

REPORT: VB-1611 9-190 • Page 2 of 10 ISSUED: JULY 12, 1995 REVISED: OCTOBER 15, 2008

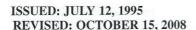
SECTION 4 - NORMAL PROCEDURES

To Operate as an Automatic Direction Finder:

- 1. OFF/VOL Control ON.
- 2. Frequency Selector Knobs SELECT desired frequency in the standby frequency display.
- FRQ Button PRESS to move the desired frequency from the standby to the active position.
- ADF SPEAKER/PHONE Selector Switch (on audio control panel) -SELECT as desired.
- 5. OFF/VOL Control SET to desired volume level.
- 6. ADF Button SELECT ADF mode and note relative bearing on indicator.

ADF Test (Pre-flight or In-flight):

- ADF Button SELECT ANT mode and note pointer moves to 90° position.
- ADF Button SELECT ADF mode and note the pointer moves without hesitation to the station bearing. Excessive pointer sluggishness, wavering or reversals indicate a signal that is too weak or a system malfuction.



ISSUED: JULY 12, 1995

REVISED: OCTOBER 15, 2008

SECTION 4 - NORMAL PROCEDURES (continued)

NOTE

The Standby Frequency which is in memory while Flight Time or Elapsed Time modes are being displayed may be called back by pressing the FRQ button, then transferred to active use by pressing the FRQ button again.

To Operate Elapsed Time Timer-Count Down Mode:

- 1. OFF/VOL Control ON.
- 2. FLT/ELT Mode Button PRESS (once or twice) until ET is annunciated.
- 3. SET/RST Button PRESS until the ET annunciation begins to flash.
- 4. FREQUENCY SELECTOR KNOBS SET desired time in the elapsed time display. The small knob is pulled out to tune the 1's. The small knob is pushed in to tune the 10's. The outer knob tunes minutes up to 59 minutes.

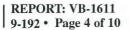
NOTE

Selector knobs remain in the time set mode for 15 seconds after the last entry or until the SET/RST, FLT/ET, or FRQ button is pressed.

5. SET/RST Button - PRESS to start countdown. When the timer reaches 0, it will start to count up as display flashes for 15 seconds.

NOTE

While FLT or ET are displayed, the active frequency on the left side of the window may be changed, by using the frequency selector knobs, without any effect on the stored standby frequency or the other modes.



ADF Operation NOTES:

Erroneous ADF Bearing Due to Radio Frequency Phenomena:

In the U.S., the FCC, which assigns AM radio frequencies, occasionally will assign the same frequency to more than one station in an area. Certain conditions, such as Night Effect, may cause signals from such stations to overlap. This should be taken into consideration when using AM broadcast station for navigation.

Sunspots and atmospheric phenomena may occasionally distort reception so that signals from two stations on the same frequency will overlap. For this reason, it is always wise to make positive identification of the station being tuned, by switching the function selector to ANT and listening for station call letters.

Electrical Storms:

In the vicinity of electrical storms, an ADF indicator pointer tends to swing from the station tuned toward the center of the storm.

Night Effect:

This is a disturbance particularly strong just after sunset and just after dawn. An ADF indicator pointer may swing erratically at these times. If possible, tune to the most powerful station at the lowest frequency. If this is not possible, take the average of pointer oscillations to determine relative station bearing.

Mountain Effect:

Radio waves reflecting from the surface of mountains may cause the pointer to fluctuate or show an erroneous bearing. This should be taken into account when taking bearings over mountainous terrain.

Coastal Refraction:

Radio waves may be refracted when passing from land to sea or when moving parallel to the coastline. This also should be taken into account.

SECTION 9 SUPPLEMENT 24

PA-28-181, ARCHER III

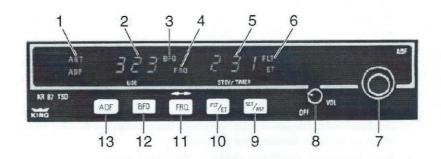
SECTION 5 - PERFORMANCE

No change.

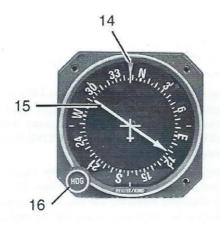
SECTION 6 - WEIGHT AND BALANCE

Factory installed optional equipment is included in the licensed weight and balance data in Section 6 of the Pilot's Operating Handbook and Airplane Flight Manual.

SECTION 7 - DESCRIPTION AND OPERATION



KR-87 Digital ADF



KI-227 Indicator

King Digital ADF Operating Controls and Indicators Figure 1

ISSUED: JULY 12, 1995 REVISED: OCTOBER 15, 2008 REPORT: VB-1611 | Page 7 of 10 • 9-195 |

ISSUED: JULY 12, 1995

REVISED: OCTOBER 15, 2008

SECTION 7 - DESCRIPTION AND OPERATION (continued)

Legend - Figure 1

- Mode Annunciation Antenna (ANT) is selected by the "out" position of the ADF button. This mode improves the aural reception and is usually used for station identification. The bearing pointer is deactivated and will park in the 90° relative position. Automatic Direction Finder (ADF) mode is selected by the depressed position of the ADF button. This mode activates the bearing pointer. The bearing pointer will point in the direction of the station relative to the aircraft heading.
- Active Frequency Display The frequency to which the ADF is tuned is displayed here. The active ADF frequency can be changed directly when either of the timer functions are selected.
- Beat Frequency Oscillator (BFO) The BFO mode, activated and annunciated when the "BFO" button is depressed, permits the carrier wave and associated morse code identifier broadcast on the carrier wave to be heard.

NOTE

CW signals (Morse Code) are unmodulated and no audio will be heard without use of BFO. This type of signal is not used in the United States air navigation. It is used in some foreign countries and marine beacons.

- 4. Standby Frequency Annunciation (FRQ) When FRQ is displayed, the STANDBY frequency is displayed in the right hand display. The STANDBY frequency is selected using the frequency select knobs. The selected STANDBY frequency is put into the ACTIVE frequency window by pressing the frequency transfer button.
- 5. Standby Frequency Display Either the standby frequency, the flight timer, or the elapsed time is displayed in this position. The flight timer and elapsed timer are displayed replacing the standby frequency which goes into "blind" memory to be called back at any time by depressing the FRQ button. Flight time or elapsed time are displayed and annunciated alternatively by depressing the FLT/ET button.

Legend - Figure 1 (continued)

- Timer Mode Annunciation Either the elapsed time (ET) or flight time (FLT) mode is annunciated here.
- 7. Frequency Selector Knobs Selects the standby frequency when FRO is displayed and directly selects the active frequency whenever either of the timer functions is selected. The frequency selector knobs may be rotated either clockwise or counterclockwise. The small knob is pulled out to tune the 1's. The small knob is pushed in to tune the 10's. The outer knob tunes the 100's with rollover into the 1000's. These knobs are also used to set the desired time when the elapsed timer is used in the countdown mode.
- Off/Volume Control (OFF/VOL) Controls primary power and audio output level. Clockwise rotation from OFF position applies primary power to receiver; further clockwise rotation increases audio level. Audio muting causes the audio output to be muted unless the receiver is locked on a valid station.
- 9. Set/Reset Button (SET/RST) The set/reset button, when pressed, resets the elapsed timer whether it is being displayed or not.
- 10. Flight Time/Elapsed Time Mode Selector Button (FLT/ET) The Flight Timer/Elapsed Time mode selector button, when pressed, alternatively selects either Flight Timer mode or Elapsed Timer mode.
- 11. Frequency Transfer Button (FRQ) The FRQ transfer button, when pressed, exchanges the active and standby frequencies. The new frequency becomes active and the former active frequency goes into standby.
- 12. BFO Button The BFO button selects the BFO mode when in the depressed position (see Note under item 3).
- 13. ADF Button The ADF button selects either the ANT mode or the ADF mode. The ANT mode is selected with the ADF button in the out position. The ADF mode is selected with the ADF button in the depressed position.
- Index (Rotatable Card) Indicates relative, magnetic, or true heading of aircraft, as selected by the HDG control.

Legend - Figure 1 (continued)

- 15. Pointer Indicates station bearing in degrees of azimuth, relative to the nose of the aircraft. When heading control is adjusted, indicates relative, magnetic, or true bearing of radio signal.
- 16. Heading Card Control (HDG) Rotates card to set in relative, magnetic, or true bearing information.

PILOT'S OPERATING HANDBOOK AND FAA APPROVED AIRPLANE FLIGHT MANUAL

SUPPLEMENT NO. 25 FOR BENDIX/KING KN-63 DME

This supplement must be attached to the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual when the Bendix/King KN-63 DME is installed per the Equipment List. The information contained herein supplements or supersedes the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual only in those areas listed herein. For limitations, procedures and performance information not contained in this supplement, consult the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual.

FAA APPROVED:

Albert J. Mill DOA-510620-CE Piper Aircraft, Inc. Vero Beach, Florida

DATE OF APPROVAL: October 15, 2008

ISSUED: JULY 12, 1995 REVISED: OCTOBER 15, 2008 REPORT: VB-1611 Page 1 of 4 • 9-199

SECTION 1 - GENERAL

The Bendix/King KN-63 DME supplies continuous slant range distance information from a fixed ground station to an aircraft in flight.

The equipment consists of a KDI-572 Panel Display which contains all the operating controls and displays, and a remotely mounted KN-63 Receiver-Transmitter. The KDI-572 Panel Display digitally displays distances in nautical miles, ground speed in knots, and time to station in minutes. All displays are in self-dimming gas discharge numerics.

SECTION 2 - LIMITATIONS

No change.

SECTION 3 - EMERGENCY PROCEDURES

No change.

SECTION 4 - NORMAL PROCEDURES DME Operation

- 1. DME Mode Selector Switch SET to N1 or N2.
- NAV 1 and NAV 2 VHF Navigation Receivers ON; SET FREQUENCY selector switches to VOR/DME station frequencies, as required.

NOTE

When the VOR frequency is selected, the appropriate DME frequency is automatically channeled.

 DME SPEAKER/PHONE selector buttons (on audio control panel) - SET to desired mode.

SECTION 5 - PERFORMANCE

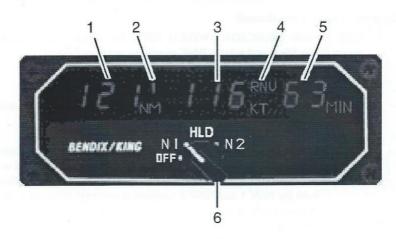
No change.

SECTION 6 - WEIGHT AND BALANCE

Factory installed optional equipment is included in the licensed weight and balance data in Section 6 of the Pilot's Operating Handbook and Airplane Flight Manual.

REPORT: VB-1611 9-200 • Page 2 of 4 ISSUED: JULY 12, 1995 REVISED: OCTOBER 15, 2008

SECTION 7 - DESCRIPTION AND OPERATION



Bendix/King KN-63 DME Figure 1

Legend - Figure 1

- 1. DISTANCE DISPLAY (NM) DME distance to VORTAC/WAYPOINT displayed in .1 nautical mile increments up to 99.9 NM, then in increments of one nautical mile to 389 NM.
- 2. DME MODE ANNUNCIATOR Displays the DME operating mode; NAV 1 (1); NAV 2 (2); NAV 1 HOLD (H1); NAV 2 HOLD (H2); of the mode selector switch (6).
- GROUND SPEED DISPLAY (KT) Displays ground speed in knots to or from VORTAC/WAYPOINT up to 999 knots (aircraft must be flying directly to or from the VORTAC/WAYPOINT for true ground speed indication).
- RNAV ANNUNCIATOR (RNV) Indicates RNV when displayed data is in relation to the RNAV waypoint. If the wrong DME mode is selected during RNAV operation, the RNAV annunciator will flash.
- 5. TIME-TO-STATION DISPLAY (MIN) Displays time-to-station (VORTAC/WAYPOINT) in minutes up to 99 minutes (aircraft must be flying directly to or from the Vortac/Waypoint for true time-to-station indication).

ISSUED: JULY 12, 1995 REVISED: OCTOBER 15, 2008 REPORT: VB-1611 Page 3 of 4 • 9-201

Legend - Figure 1 (continued)

6. DME MODE SELECTOR SWITCH (OFF, N1, HLD, N2) - Applies power to the DME and selects DME operating mode as follows:

OFF: Turns DME power off.

NAV 1

(N1): Selects DME operation with No. 1 VHF navigation set; enables channel selection by NAV 1 frequency selector controls.

HOLD

(HLD): Selects DME memory circuit; DME remains channeled to station to which it was last channeled when HOLD was selected and will continue to display information relative to this channel. Allows both the NAV 1 and NAV 2 navigation receivers to be set to new operational frequencies without affecting the previously selected DME operation.

NOTE

In the HOLD mode there is no annunciation of the VOR/DME station frequency. However, an annunciator labeled "H1" or "H2" illuminates on the DME display to flag the pilot that the DME is in the HOLD mode.

NAV 2

(N2): Selects DME operation with No. 2 VHF navigation set; enables channel selection by NAV 2 frequency selector switches. Brightness of the labels for this switch is controlled by the RADIO light dimming rheostat.

PILOT'S OPERATING HANDBOOK AND FAA APPROVED AIRPLANE FLIGHT MANUAL

SUPPLEMENT NO. 26 FOR GARMIN G500 PRIMARY FLIGHT AND MULTIFUNCTION DISPLAY SYSTEM

The FAA approved operational supplement for the Garmin G500 PFD/MFD System, installed in accordance with STC SA02015SE-D, is required for operation of this system. Garmin will be responsible to supply and revise the operational supplement. It is permitted to include the Garmin G500 PFD/MFD supplement in this location of the Pilot's Operating Handbook unless otherwise stated by Garmin. The information contained in the Garmin G500 PFD/MFD supplement may supersede or supplement the information in the basic Pilot's Operating Handbook and FAA Approved Airplane Flight Manual with respect to the operation of the Garmin G500 PFD/MFD System. For limitations, procedures and performance information not contained in the Garmin supplement, consult the basic Pilot's Operating Handbook and FAA Approved Airplane Flight Manual.

ISSUED: JULY 12, 1995 REVISED: FEBRUARY 5, 2010 REPORT: VB-1611 9-203 THIS PAGE INTENTIONALLY LEFT BLANK

REPORT: VB-1611 9-204

PILOT'S OPERATING HANDBOOK AND FAA APPROVED AIRPLANE FLIGHT MANUAL

SUPPLEMENT NO. 27 FOR GARMIN GNS 430W VHF COMMUNICATION TRANSCEIVER/VOR/ILS RECEIVER/GPS RECEIVER

This supplement must be attached to the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual when the Garmin GNS 430W VHF Communication Transceiver/VOR/ILS Receiver/Global Positioning System is installed per the Equipment List. The information contained herein supplements or supersedes the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual only in those areas listed herein. For limitations, procedures and performance information not contained in this supplement, consult the Pilot's Operating Handbook and FAA Approved Airplane Flight Manual.

FAA APPROVED:

Albert J. Mill ODA-510620-CE Piper Aircraft, Inc. Vero Beach, Florida

DATE OF APPROVAL: July 29, 2010

ISSUED: JULY 12, 1995 REVISED: JULY 29, 2010 REPORT: VB-1611 Page 1 of 12 • 9-205

ISSUED: JULY 12, 1995

REVISED: JULY 29, 2010

S'TION 1 - GENERAL

The GNS430W System is a fully integrated, panel mounted instrument, which contains a VHF Communications Transceiver, a VOR/ILS receiver, and a WAAS—enabled Global Positioning System (GPS) Navigation computer. The system consists of a GPS antenna, GPS/WAAS receiver, VHF VOR/LOC/GS antenna, VOR/ILS receiver, VHF COMM antenna and a VHF Communications transceiver. The primary function of the VHF Communication portion of the equipment is to facilitate communication with Air Traffic Control. The primary function of the VOR/ILS Receiver portion of the equipment is to receive and demodulate VOR, Localizer, and Glide Slope signals. The primary function of the GPS/WAAS portion of the system is to acquire signals from the GPS system satellites, recover orbital data, make range and Doppler measurements, and process this information in real-time to obtain the user's position, velocity, and time.

Provided the GARMIN GNS 430W's GPS/WAAS receiver is receiving adequate usable signals, it has been demonstrated capable of and has been shown to meet the accuracy specifications for:

GPS navigation is accomplished using the WGS-84 (NAD-83) coordinate reference datum. GPS navigation data is based upon use of only the Global Positioning System (GPS) operated by the United States of America.

SECTION 1 - GENERAL (continued)

Class II Oceanic, Remote, and other operations

The Garmin 430W has been found to comply with the requirements for GPS primary means of Class II navigation in oceanic and remote airspace when used in conjunction with Garmin Prediction Program part number 006-A0154-03. Oceanic operations are supported when the GNS430W unit annunciates OCN. This provides an alarm limit of four nautical miles and a mask angle of five degrees. The GNS430W unit also has the ability to predict RAIM availability at any waypoint in the database if WAAS corrections are expected to be absent or disabled. This does not constitute an operational approval for Oceanic or Remote area operations. Additional equipment installations or operational approvals may be required.

- Oceanic navigation requires an additional approved long range oceanic and/or remote area navigation system with independent display, sensors, antenna, and power source.
- Redundant VHF Com and VHF Nav systems may be required for other than US 14 CFR Part 91 operations. Check foreign regulation requirements as applicable.
- Operations approval may be granted for the use of the GNS430W unit RAIM prediction function in lieu of the Prediction Program for operators requiring this capability. Refer to your appropriate civil aviation authorities for these authorizations.

ISSUED: JULY 12, 1995 REVISED: JULY 29, 2010

CTION 2 - LIMITATIONS

Pilot's Guide

The Garmin 400W Series Pilot's Guide, part number and revision listed below (or later revisions), must be immediately available for the flight crew whenever navigation is predicated on the use of the GNS430W unit.

 400W Series Pilot's Guide & Reference P/N 190-00356-00 Rev. B, or later revision.

This AFM supplement does not grant approval for IFR operations to aircraft limited to VFR operations. Additional aircraft systems may be required for IFR operational approval.

System Software

The system must utilize the Main and GPS software versions listed below (or later FAA approved versions for this installation). The software versions are displayed on the self-test page immediately after turn-on, for approximately 5 seconds, or they can be accessed on the AUX-UTILITY page.

sequent software versions may support different functions. Check the Solve Series Pilot's Guide for further information.

Approved Software Versions		
Software Item	Approved Software Version (or later FAA-approved versions)	
	Software Version	As Displayed on Unit
Main Software Version	3.0	3.0
GPS Software Version	3.0	3.0

Table 1

Navigation Data Base

The GNS430W unit database cards listed in the following table (or later FAA approved versions for this installation) must be installed.

IFR enroute and terminal navigation is prohibited unless the pilot verifies
he currency of the database or verifies each selected waypoint for accuracy
by reference to current approved data.

REPORT: VB-1611 9-208 • Page 4 of 12 ISSUED: JULY 12, 1995 REVISED: JULY 29, 2010

SECTION 2 - LIMITATIONS (continued)

Navigation Data Base (continued)

- GPS instrument approaches using the GNS430W are prohibited, unless the GNS430W's approach data is verified by the pilot or crew to be current. Instrument approaches must be accomplished in accordance with an approved instrument approach procedure that is loaded from the GNS430W's database.
- Installations with dual 430W units will only crossfill between those units when they contain the same database cycle. Updating of each database must be accomplished on the ground prior to flight.

Approv	Approved Navigation Database Cards		
Part Number	Description		
010-10546-00	Data Card, WAAS, IFR, World Wide		
010-10546-01	Data Card, WAAS, IFR, Americas		
010-10546-02	Data Card, WAAS, IFR, International		

Table 2

TCTION 2 - LIMITATIONS (continued)

Terrain Data Base

The GNS430W supports Terrain and requires a Terrain database card to be installed in order for the feature to operate. The table below lists compatible database cards for the GNS430W. Each of the database cards contains the following data:

- The Terrain Database has an area of coverage from North 75° Latitude to South 60° Latitude in all longitudes.
- The Airport Terrain Database has an area of coverage that includes the United States, Canada, Mexico, Latin America, and South America.
- The Obstacle Database has an area of coverage that includes the United States, and is updated as frequently as every 56 days.

NOTE

The area of coverage may be modified as additional terrain data sources become available.

Approved Terrain Database Cards		
Part Number	Description	
010-10201-20	Data Card, TAWS / Terrain, 128ME	
010-10201-21	Data Card, TAWS / Terrain, 256ME	
	Table 3	

Navigation

No navigation is authorized north of 89° (degrees) north latitude or south of 89° (degrees) south latitude.

SECTION 2 - LIMITATIONS (continued)

Approaches

- During GPS approaches, the pilot must verify the GNS430W unit is operating in the approach mode. (LNAV, LNAV+V, L/VNAV, or LPV.)
- When conducting approaches referenced to true North, the heading selection on the AUX pages must be adjusted to TRUE.
- Accomplishment of an ILS, LOC, LOC-BC, LDA, SDF, MLS, VOR approach, or any other type of approach not approved for GPS overlay, is not authorized with GPS navigation guidance.
- Use of the GNS430W VOR/LOC/GS receiver to fly approaches not approved for GPS requires VOR/LOC/GS navigation data to be present on the external indicator (i.e. proper CDI source selection).

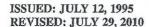
Terrain Display

Terrain refers to the display of terrain information. Pilots are NOT authorized to deviate from their current ATC clearance to comply with terrain/obstacle alerts. Terrain unit alerts are advisory only and are not equivalent to warnings provided by a Terrain Awareness and Warning System (TAWS). Navigation must not be predicated upon the use of the terrain display.

The terrain display is intended to serve as a situational awareness tool only. By itself, it may not provide either the accuracy or the fidelity on which to base decisions and plan maneuvers to avoid terrain or obstacles.

VNAV

VNAV information may be utilized for advisory information only. Use of VNAV information for instrument Approach Procedures does not guarantee Step-Down Fix altitude protection, or arrival at minimums in a normal position to land.



ECTION 3 - EMERGENCY PROCEDURES

Emergency Procedures

No change.

Abnormal Procedures

- If the Garmin GNS430W GPS navigation information is not available, or is invalid, utilize other remaining operational navigation equipment installed in the airplane as appropriate. If the 430W loses GPS position and reverts to Dead Reckoning mode (indicated by the annunciation of "DR" in the lower left of the display), the moving map will continue to be displayed. Aircraft position will be based upon the last valid GPS position and estimated by Dead Reckoning methods. Changes in airspeed or winds aloft can affect the estimated position substantially. Dead Reckoning is only available in Enroute mode; Terminal and Approach modes do not support DR.
- · If a "Loss of Integrity" (INTEG) message is displayed during:
 - Enroute/Terminal: continue to navigate using GPS equipment and periodically cross-check the GPS guidance to other approved means of navigation.
 - GPS Approach: GPS approaches are not authorized under INTEG -Execute missed approach or revert to alternate navigation.
- During a GPS LPV precision approach or GPS LNAV/VNAV approach, the 430W will downgrade the approach if the Horizontal or Vertical alarm limits are exceeded. This will cause the vertical guidance to flag as unavailable. The procedure may be continued using the LNAV only minimums.
- During any GPS approach in which precision and non-precision alarm limits are exceeded, the 430W will flag the lateral guidance and generate a system message "ABORT APPROACH loss of navigation".
 Immediately upon acknowledging the message the unit will revert to Terminal alarm limits. If the position integrity is within these limits, lateral guidance will be restored and the GPS may be used to execute the missed approach, otherwise alternate means of navigation should be utilized.

In an in-flight emergency, depressing and holding the Comm transfer button for 2 seconds will select the emergency frequency of 121.500 Mhz into the "Active" frequency window.

REPORT: VB-1611 9-212 • Page 8 of 12 ISSUED: JULY 12, 1995 REVISED: JULY 29, 2010

SECTION 4 - NORMAL PROCEDURES

Refer to the 400W Series unit Pilot's Guide defined in Section 2 - Limitations of this supplement for normal operating procedures. This includes all GPS operations, VHF COM and NAV, and Multi-Function Display (optional) information.

Although intuitive and user friendly, the GNS430W requires a reasonable degree of familiarity to prevent operations without becoming too engrossed at the expense of basic instrument flying in IMC and basic see-and-avoid in VMC. Pilot workload will be higher for pilots with limited familiarity in using the unit in an IFR environment, particularly without the autopilot engaged. Garmin provides excellent training tools with the Pilot's Guide and PC based simulator. Pilots should take full advantage of these training tools to enhance system familiarization. Use of an autopilot is strongly encouraged when using the GNS430W in IMC conditions.

Approaches with Vertical Guidance

The GNS430W supports three types of GPS approaches with vertical guidance: LPV approaches, LNAV/VNAV (annunciated as L/VNAV) approaches, and LNAV approaches with advisory vertical guidance (annunciated as LNAV+V). For LNAV approaches with advisory vertical guidance, the GNS430W will annunciate LNAV+V indicating vertical guidance is available. LNAV minimums will be controlling in this case.

NOTE

If flying an LPV or LNAV/VNAV approach, be prepared to fly the LNAV only approach prior to reaching the final approach fix (FAF). If the GPS integrity is not within vertical approach limits, the system will flag the vertical guidance. This may be annunciated by a downgrade to LNAV message.

For additional information on approaches with vertical guidance, refer to the 400W Series unit Pilot's Guide.

ISSUED: JULY 12, 1995 REVISED: JULY 29, 2010 REPORT: VB-1611 Page 9 of 12 • 9-213

CTION 4 - NORMAL PROCEDURES (continued)

Autopilot Operation

The Garmin GNS430W may be coupled to the STEC 55X Autopilot when operating as prescribed in the LIMITATIONS section of this supplement. For lateral guidance, the STEC 55X Autopilot may utilize GPSS or GPS Roll Steering in lieu of the analog deviation information. For autopilot operational instructions, refer to the FAA approved Flight Manual or Flight Manual Supplement for the autopilot.

Coupling the Autopilot during Approaches

The Garmin GNS430W supports analog and digital (GPSS) control interfaces to the STEC 55X Autopilot. The STEC 55X may use digital GPS roll steering commands (GPSS) during GPS enroute, terminal, and LNAV approach operations only. When switching between GPS and VLOC, the pilot should be aware that the autopilot will need to be re-engaged in GPSS or NAV/APR, depending on the CDI nav source last selected or the type of roach desired.

Autopilot coupling to GPS vertical guidance requires that the autopilot be engaged in an analog APR mode identical to coupling to an ILS. To capture the vertical guidance, the pilot may engage the autopilot in APR mode at any time when the GPS Glide Slope (VDI) becomes valid (displayed without a FLAG).

Should a missed approach be required per the published missed approach procedure, the autopilot must be engaged in GPSS mode for proper guidance.

CAUTION

Do not operate the autopilot in the approach (APR) mode when conducting the published missed approach procedure.

SECTION 4 - NORMAL PROCEDURES (continued)

WFDE Prediction Program

The Garmin WAAS Fault Detection and Exclusion (WFDE) Prediction Program is required for Remote/Oceanic operations.

The Prediction Program should be used in conjunction with the Garmin 400W/500W Simulator. After entering the intended route of flight in the Simulator flight plan, the pilot selects the FDE Prediction Program under the Options menu of the Simulator program.

For detailed information, refer to the WFDE Prediction Program instructions (190-00643-01). The availability of FDE is only required for Oceanic or Remote operations.

SECTION 5 - PERFORMANCE

No change.

SECTION 6 - WEIGHT AND BALANCE

No change.

SECTION 7 - DESCRIPTION AND OPERATION

See Garmin 400W Series unit Pilot's Guide for a complete description of the GNS430W unit.

ISSUED: JULY 12, 1995 REVISED: JULY 29, 2010 REPORT: VB-1611 Page 11 of 12 • 9-215 THIS PAGE INTENTIONALLY LEFT BLANK

REPORT: VB-1611 9-216 • Page 12 of 12 ISSUED: JULY 12, 1995 REVISED: JULY 29, 2010

TABLE OF CONTENTS SECTION 10 OPERATING TIPS

Paragraph No.		Page No.	
10.1	General	10-1	
10.3	Operating Tips	10-1	

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SECTION 10

OPERATING TIPS

10.1 GENERAL

This section provides operating tips of particular value in the operation of Archer III.

10.3 OPERATING TIPS

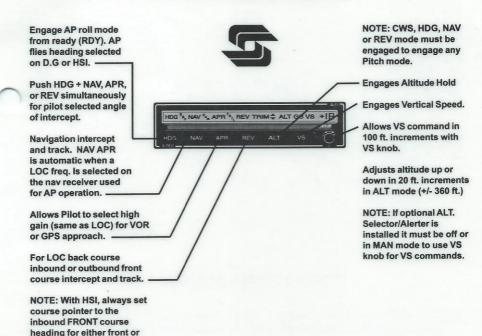
- (a) Learn to trim for takeoff so that only a very light back pressure on the control wheel is required to lift the airplane off the ground.
- (b) The best speed for takeoff is about 57 KIAS under normal conditions. Trying to pull the airplane off the ground at too low an air-speed decreases the controllability of the airplane in the event of engine failure.
- (c) Flaps may be lowered at airspeeds up to 102 KIAS. To reduce flap operating loads, it is desirable to have the airplane at a slower speed before extending the flaps. The flap step will not support weight if the flaps are in any extended position. The flaps must be placed in the "UP" position before they will lock and support weight on the step.
- (d) Before attempting to reset any circuit breaker, allow a two to five minute cooling off period.
- (e) Before starting the engine, check that all radio switches, light switches and the pitot heat switch are in the off position so as not to create an overloaded condition when the starter is engaged.
- (f) Anti-collision lights should not be operating when flying through cloud, fog or haze, since reflected light can produce spacial disorientation. Strobe lights should not be used in close proximity to the ground such as during taxiing, takeoff or landing.

ISSUED: JULY 12, 1995

REPORT: VB-1611

- (g) The rudder pedals are suspended from a torque tube which extends across the fuselage. The pilot should become familiar with the proper positioning of his feet on the rudder pedals so as to avoid interference with the torque tube when moving the rudder pedals or operating the toe brakes.
- (h) In an effort to avoid accidents, pilots should obtain and study the safety related information made available in FAA publications such as regulations, advisory circulars, Aviation News, AIM and safety aids.
- (i) Prolonged slips or skids which result in excess of 2000 ft. of altitude loss, or other radical or extreme maneuvers which could cause uncovering of the fuel outlet must be avoided as fuel flow interruption may occur when tank being used is not full.
- (i) Hand starting of the engine is not recommended, however, should hand starting of the engine be required, only experienced personnel should attempt this procedure. The magneto selector should be placed to "LEFT" during the starting procedure to reduce the probability of "kick back." Place the ignition switch to "BOTH" position after the engine has started.

SYSTEM 55 QUICK REFERENCE



ADDITIONAL FEATURES/ANNUNCIATIONS

RDY Indicates system has passed self test and is ready to engage.

CWS Remote switch activation. From RDY mode or Autopilot modes, engages Autopilot (Roll and Pitch axis) synchronized with existing roll and pitch

attitude WHEN RELEASED.

back course approach.

FAIL Indicates a) System did not pass self test on initial power-up.

 NAV Warning Flag – VOR/LOC or GPS with Autopilot NAV mode engaged. NAV will flash.

GS Warning Flag with Autopilot GS mode engaged.
 GS will flash

TRIM Indicates Trim in motion OR trim required if Auto trim is off or inoperative.

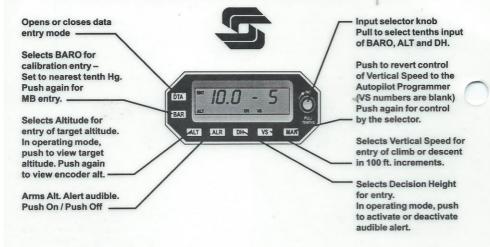
Pressing NAV mode a second time when in NAV APR mode to disable GS coupling. GS will flash (no fail indication). Press again to restore.

To capture GS from above: a) Press ALT again IF already in ALT Mode.

b) If in VS mode, Press ALT then ALT again.

NOTE: To capture from above, GS must be valid (no flag) and localizer course deviation must be 50% or less.

ALTITUDE SELECTOR/ALERTER QUICK REFERENCE



POINTS TO REMEMBER

- Set Barometric calibration, Altitude and / or Vertical Speed following initial power up self-test. System will be in data entry mode following self test.
- Push "DTA" to enter or change any data EXCEPT vertical speed –"VS".
 Once entered, push "DTA" to close the entry mode or the unit can not communicate your input / settings to the autopilot.
- When "ENT" is displayed, the function flashing is the one selected for change or input. Once set, push "DTA" to close the data entry mode.
- To activate Pre-Selected ALTITUDE and VERTICAL SPEED, push BOTH the ALT and VS function buttons ON THE AUTOPILOT Programmer AT THE SAME TIME. This will be confirmed by both ALT and VS modes being annunciated on the AUTOPILOT PROGRAMMER.
- If "VS", +/- and a number are not displayed, "MAN" mode has been selected and Vertical Speed commands must be input from the AUTOPILOT programmer. A target Altitude can still be pre-selected and the Autopilot "VS and "ALT" function buttons pushed at the same time to activate.
- For COMPLETE details of operation and additional features and functions, refer to the Pilot's Operating Handbook for this product.
- If you are unsure of correct operation, it is always best to turn off the Altitude Selector / Alerter and revert to normal Autopilot operation.



Révision: 2

Du: 03/06/2008

AFMS n° AFM-37-2007-000

Page 1 sur 7

MALONNIER LPS

Supplément au manuel de vol pour l'installation d'un système malonnier de type LPS sur l'avion Piper PA-28 en conformité avec la modification n°FA 37/2007

Les informations remplacent ou complètent celles du manuel de vol approuvé par l'AESA, tel que défini ci-après.

Il est recommandé aux utilisateurs de se reporter systématiquement au supplément afin de vérifier la présence éventuelle de mise à jour ainsi que le marquage des indications applicables à l'utilisation de l'aéronef.

Ce manuel inclut les informations que les conditions de certification exigent de fournir au pilote. Ceci ne constitue pas une autorisation opérationnelle.

N° et date d'approbation AESA

EASA .A.S .03031



Révision:

Du:

03/06/2008

AFMS n° AFM-37-2007-000

Page 2 sur 7

Page de révision

Révision n°:0

Date: 25/10/2007

PAGES A PAGES A DÉTRUIRE INSÉRER		DESCRIPTION DE LA RÉVISION		

Sommaire

SECTION 1 -	GENERALITES	3
SECTION 2 -	LIMITATIONS	3
SECTION 3 -	PROCEDURES D'URGENCE	3
SECTION 4 -	PROCEDURES NORMALES	4
SECTION 5 -	PERFORMANCES	6
SECTION 6 -	MASSE ET CENTRAGE	6
SECTION 7 -	DESCRIPTION	7



Révision: 2

Du: 03/06/2008

AFMS n° AFM-37-2007-000

Page 3 sur 7

Section 1 - Généralités

Ce supplément est applicable au Piper PA-28. L'installation suivante et les critères opérationnels doivent être observés quand l'avion est équipé de la commande manuelle de direction et de frein «LPS».

Section 2 - Limitations

INSTALLATION

L'installation ou le démontage de la partie fixe de cette commande ne peut être effectué que par un mécanicien habilité à l'entretien des avions.

L'installation ou le démontage du bras de commande démontable peut être effectué par un pilote convenablement formé et autorisé.

Quand la poignée n'est pas en place, une protection doit être insérée dans l'extrémité de la partie fixe de la commande à main pour se protéger de tous contacts anormaux.

ATTENTION ! L'utilisation de cette commande exige une formation au sol et en vol

<u>ATTENTION</u>! La partie démontable de la commande doit être enlevée pour tous vols sans pilote handicapé des membres inférieurs.

LIMITATIONS OPERATIONNELLES

Les jambes du pilote handicapé des membres inférieurs doivent être positionnées afin d'éviter la possibilité d'interférence avec les systèmes de commandes de vol de l'avion. Il s'agit de garantir les points suivants :

A/ pleins débattements du volant (les genoux doivent être suffisamment bas),

B/ le genou droit doit rester à gauche du plan vertical sur lequel se déplace la commande manuelle de dérive,

C/ pas de blocage des pédales de palonnier avec les pieds.

Pour satisfaire à ces conditions, sont adéquates :

- une position du siège réglé plutôt en arrière,
- ainsi qu'une sangle à scratch rapprochant les jambes au niveau des genoux.

<u>ATTENTION</u>! L'amortisseur de shimmy de roue avant doit être entièrement opérationnel.

Lorsqu'il y a du shimmy sur la roue avant le bras de commande peut blesser le pilote ou le passager du siège avant.

Section 3 - Procédures d'urgence

Pendant le roulage, si les vibrations se font sentir, réduire immédiatement la vitesse.

FRANCE AVIATION

SUPPLÉMENT AU MANUEL DE VOL

Révision: 2

Du: 03/06/2008

AFMS n° AFM-37-2007-000

Page 4 sur 7

Section 4 - Procédures normales

PREVOL

En sus de la procédure standard du manuel de vol, s'assurer de la bonne configuration des commandes manuelles additionnelles.

DEMARRAGE

Avant de commencer, le frein à main doit être mis solidement. Une attention particulière doit être faite pour garder les yeux à l'extérieur de l'avion afin de s'assurer de l'immobilité de l'avion.

ROULAGE AU SOL

Le roulage au sol s'effectue de la manière suivante :

- la main gauche reste en permanence sur la commande déportée de frein,
- un affichage de 1200 tours/min (+ ou 100 trs/min : lors de la mise en mouvement de l'avion, et en fonction des pentes et revêtement des taxiways) est effectué puis la droite agit sur la commande manuelle de dérive pour assurer le contrôle directionnel.
- l'action sur le frein (avec la main gauche) détermine la vitesse de roulage. Le frein à main doit être appliqué à basses vitesses. Pendant ce temps le volant peut être retenu avec un coude, mais aucune main ne le retient réellement.

Le rayon de braquage est légèrement plus grand dû au manque de freinage différentiel.

Au sol et en vol, se rappeler que :

La commande actionnée VERS LE HAUT la direction va vers la GAUCHE

La commande actionnée VERS LE BAS la direction va vers a DROITE

Apporter une attention particulière à ceci, jusqu'à ce que les mouvements devienment automatiques.

POINT FIXE

Une attention supplémentaire est nécessaire pour avoir le frein à main serré pour que l'avion reste stationnaire tandis que la mise en puissance est effectuée jusqu'au niveau exigé.

Il est encore essentiel de faire un effort pour garder les yeux à l'extérieur pour s'assurer que l'avion n'avance pas.

Il est nécessaire de vérifier la friction de la manette des gaz afin qu'elle ne permette aucune variation de position notamment pendant la mise en puissance et la montée initiale.

FRANCE AVIATION

SUPPLÉMENT AU MANUEL DE VOL

Révision: 2

Du: 03/06/2008

AFMS n° AFM-37-2007-000

Page 5 sur 7

DECOLLAGE

A/ Pendant la phase de mise en puissance, l'avion est maintenu aligné avec la main droite sur la commande manuelle de dérive, alors que la commande de puissance est ajustée par la main gauche.

B/ Quand la pleine puissance est appliquée, la main gauche est alors déplacée vers le volant de commande de vol. Des changements de pression très doux sur la commande manuelle sont suffisants pour maintenir l'avion aligné.

C/ Après la rotation, la main droite peut passer de la commande manuelle de dérive vers la commande des gaz pour maintenir la puissance désirée. Un ajustement du lacet peut être effectuer au moyen du réglage de trim de direction.

Décollage court

A/ Une attention supplémentaire est exigée pour que le frein à main gauche soit maintenu pendant la mise en puissance.

B/ Après avoir affiché la pleine puissance, la main droite se déplace de la commande de gaz vers la commande manuelle de dérive en vue du contrôle de trajectoire de l'avion sur la piste.

C/ Enfin la main gauche libère le frein à main gauche, puis est immédiatement transfétée du frein au volant de commande de vol.

D/ Les procédures normales de décollage court sont suivies.

Décollage par vents de travers

Pour un décollage par vent de travers, l'aileron peut être maintenu dans le vent avec le coude au-dessus ou au-dessous du volant de commande de vol jusqu'à ce que la pleine puissance soit appliquée et que la main gauche retourne au volant de commande de vol afin que les procédures normales soient suivies.

ATTERRISSAGE

Normal

A/ L'approche est faite avec la main droite positionnée sur la commande de puissance jusqu'au début de l'arrondi.

B/ Afin d'alléger la charge de travail dans l'hypothèse d'une remise de gaz ou d'un toucherdécoller, deux actions sont à effectuer au passage des 300 pieds sol :

- la commande de réchauffe carburateur est actionnée avec la main droite de la position ON (en haut) vers le OFF (bas),
- le trim de direction est ajusté, à partir de sa position neutre, de deux rotations d'un quart de tour dans le sens horaire.

C/ A l'arrondi, la main droite actionne la manette des gaz sur plein réduit puis vient se positionner sur la commande manuelle de dérive pour la gestion de la trajectoire.

D/ Une fois l'avion au sol, la main droite reste en place sur la commande manuelle de dérive et la main gauche se déplace du volant vers le levier de frein déporté (à gauche du volant) jusqu'à très faible vitesse. La procédure « ROULAGE AU SOL » est ensuite appliquée.



Révision: 2

Du: 03/06/2008

AFMS n° AFM-37-2007-000

Page 6 sur 7

Toucher Décoller

A/B/ et C/: idem « Atterrissage Normal »

D/ Pendant la phase de roulage, l'avion est contrôlé avec la main droite sur la commande manuelle de dérive tandis que la main gauche vient se positionner du volant vers la commande de puissance pour afficher plein régime et ensuite revenir se placer de nouveau sur le volant de commande de vol.

E/ Après la rotation, la main droite peut passer de la commande manuelle de dérive vers la commande des gaz pour maintenir la puissance désirée.

Atterrissage par vent de travers

Technique de coordination identique à celle décrite pour « l'Atterrissage Normale ». Notamment le point C/: à l'arrondi, juste après avoir positionné la commande de puissance sur plein réduit avec la main droite, la correction de dérive et remise dans l'axe s'effectue à l'aide de cette même main droite alors transférée sur la commande manuelle de dérive.

Atterrissage court

Pas de consigne particulière liée au système additionnel « LPS » autre que celles qui sont rapportées dans le paragraphe « Atterrissage Normal »

Section 5 - Performances

La commande manuelle de direction n'a aucune influence sur les performances de l'appareil.

Section 6 - Masse et centrage

Partie fixe de la poignée de commande	= 1.3 Kg	à	1230 mm
Partie démontable de la poignée de commande faisant partie de l'équipement du pilote	= 1.0 Kg		
Total des masses posées	$= 2.3 \mathrm{Kg}$		



Révision:

Du: 03/06/2008

AFMS n° AFM-37-2007-000

Page 7 sur 7

Section 7 -Description

La commande manuelle de direction est constituée de deux parties : la partie du bas, est fixée mécaniquement sur le palonnier droit de la place gauche, cette partie demeurant fixe.

La partie du haut démontable, qui lorsque est installée s'emboîte dans la partie du bas et est maintenue par deux goupilles à bille.

La commande manuelle de frein située à gauche du pilote est reliée directement à la commande de frein de parc d'origine

Ces deux commandes permettent au pilote installé en place gauche de manœuvrer la gouverne de direction de la main droite et d'actionner les freins de la main gauche. Ce système de commande utilisé permet, par un jeu de bras de levier, de diminuer les efforts à la commande manuelle par rapport à la commande aux palonniers.

La commande moteur se situe d'origine dans la partie centrale, proches de la commande manuelle de direction.

EMERGENCY PROCEDUERS CHECK LIST SE-ILV

ENGINE FIRE DURING START

STARTER **CRANK ENGINE** MIXTURE **IDLE CUT OFF** THROTTLE OPEN **ELECTRIC FUEL PUMP** OFF **FUEL SELECTOR**

ENGINGE POWER LOSS DURING TAKEOFF

FUEL SELECTOR

OFF

SWITCH TO TANK-FULL **ELECTRIC FUEL PUMP** CHECK ON MIXTURE **CHECK RICH**

CARBURATOR HEAT ON

ENGINE POWER LOSS IN FLIGHT

AIRSPEED **MAINTAIN 76 KIAS FUEL SELECTOR** SWITCH TO FULL TANK **ELECTRIC FUEL PUMP** ON

MIXTURE RICH **CARBURATOR HEAT** ON

FIRE IN FLIGHT

SOURCE OF FIRE CHECK **ELECTRICAL FIRE (SMOKE IN CABIN) CHECK**

BATT.MASTER SWITCH OFF ALTR SWITCH OFF **VENTS OPEN**

LAND AS SOON AS POSSIBLE

ENGINE FIRE FUEL SELECTOR OFF

THROTTLE CLOSED MIXTURE **IDLE CUT OFF**

ELECTRIC FUEL PUMP OFF **HEATHER AND DEFROSTER** OFF

LAND AS SOON AS POSSIBLE